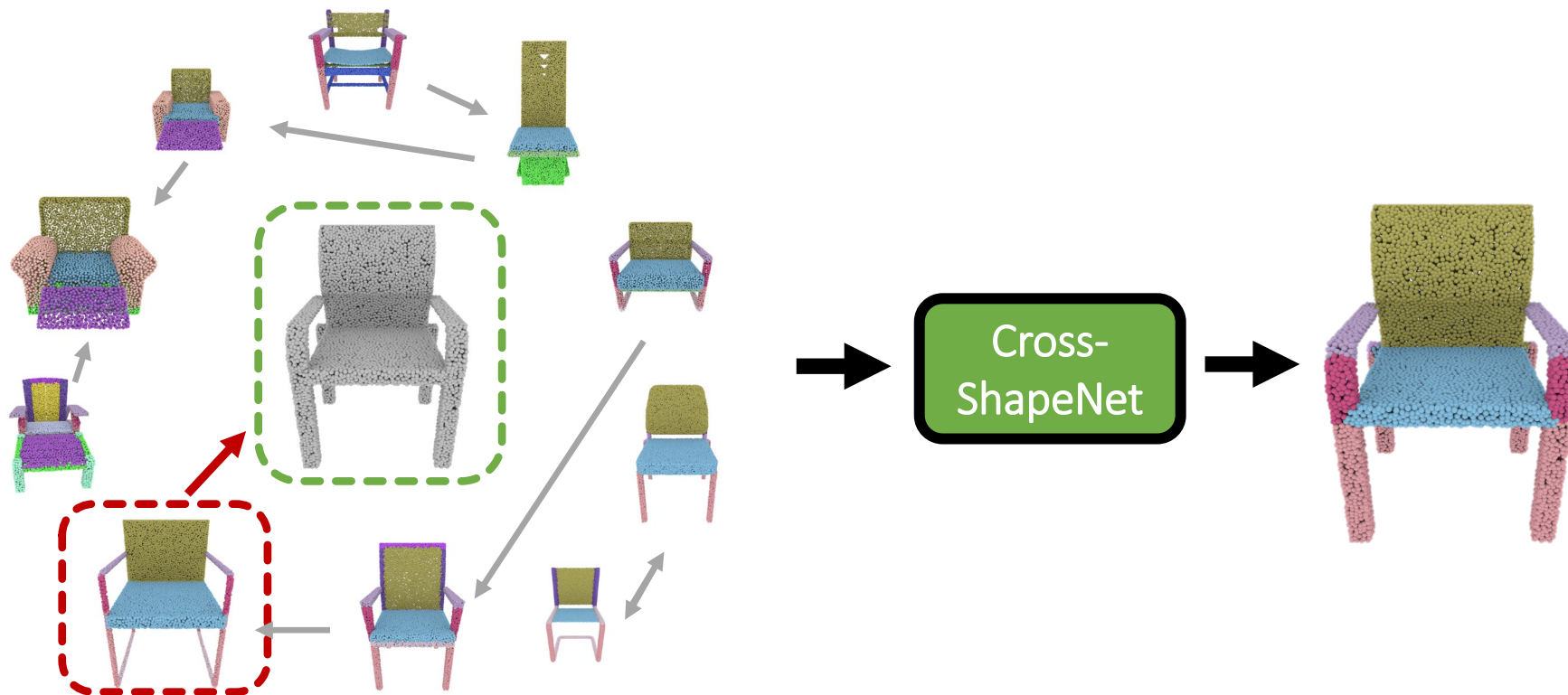


Cross-Shape Attention for Part Segmentation of 3D Point Clouds



Marios Loizou^{†1}

Melinos Averkiou¹

Siddhant Garg^{†2}

Evangelos Kalogerakis²

Dmitry Petrov^{†2}

¹University of Cyprus / CYENS CoE

²University of Massachusetts Amherst

Goal: learn more coordinated feature representations

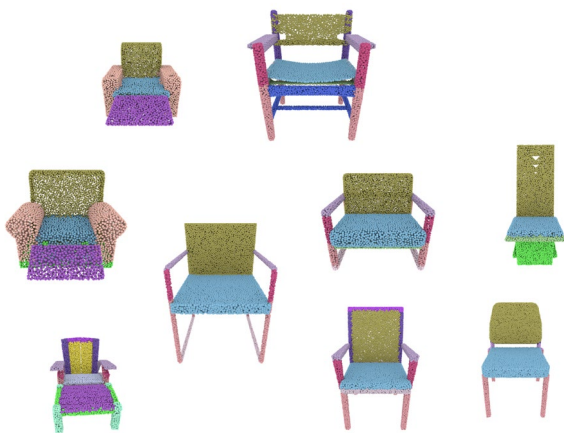


test shape

Goal: learn more coordinated feature representations

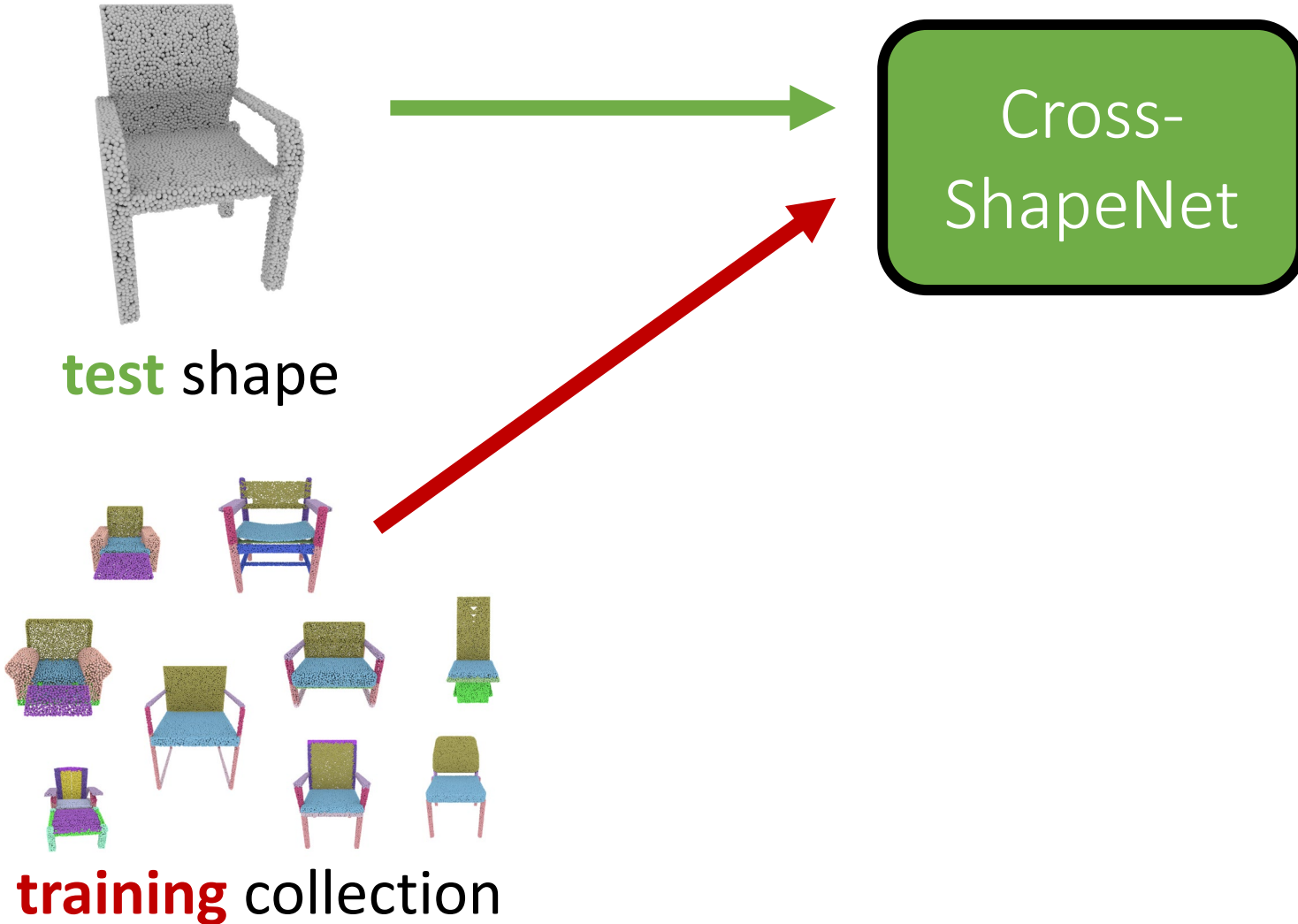


test shape

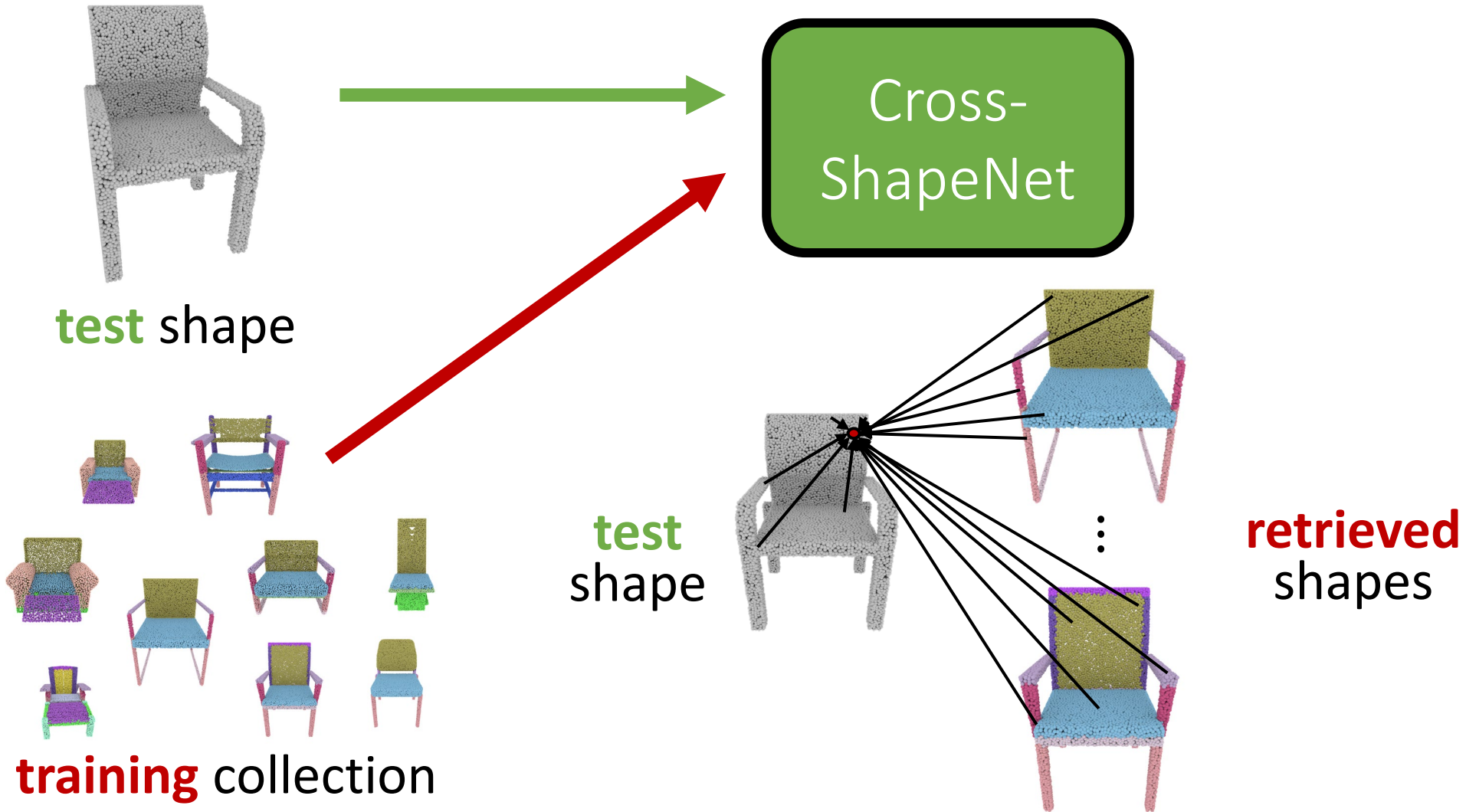


training collection

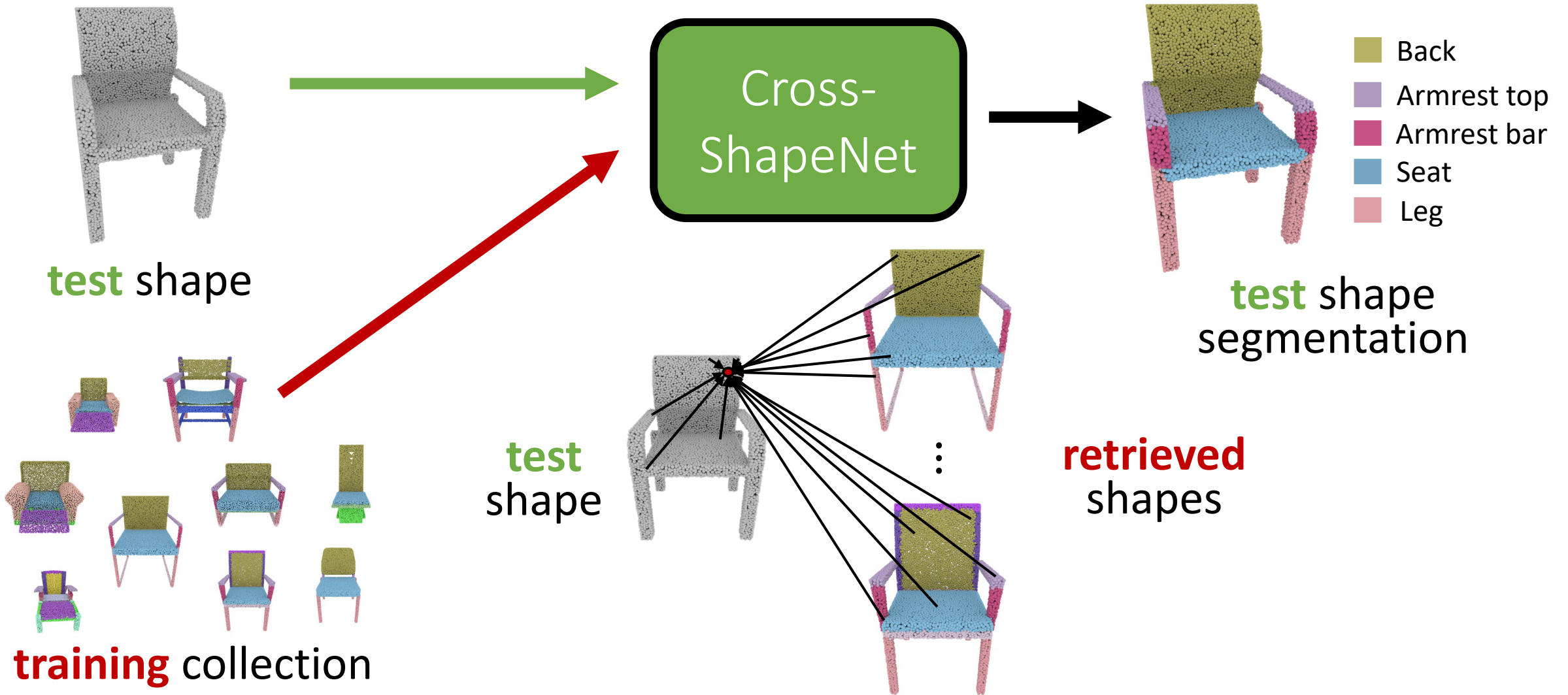
Goal: learn more coordinated feature representations



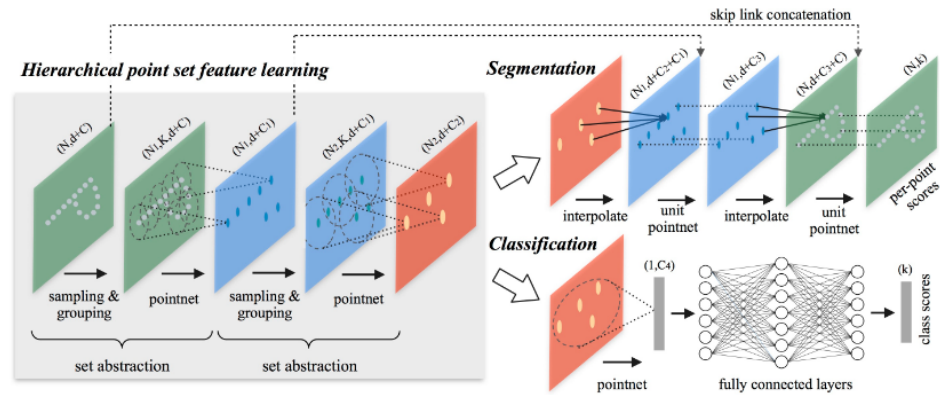
Goal: learn more coordinated feature representations



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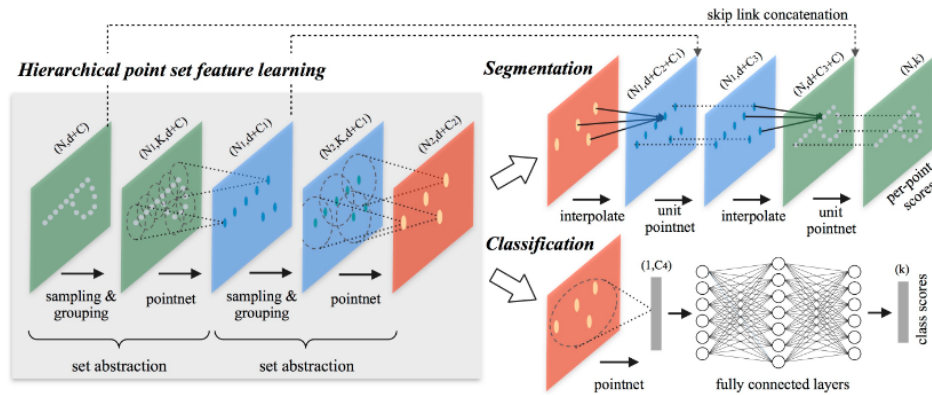


Prior work: Point-based networks

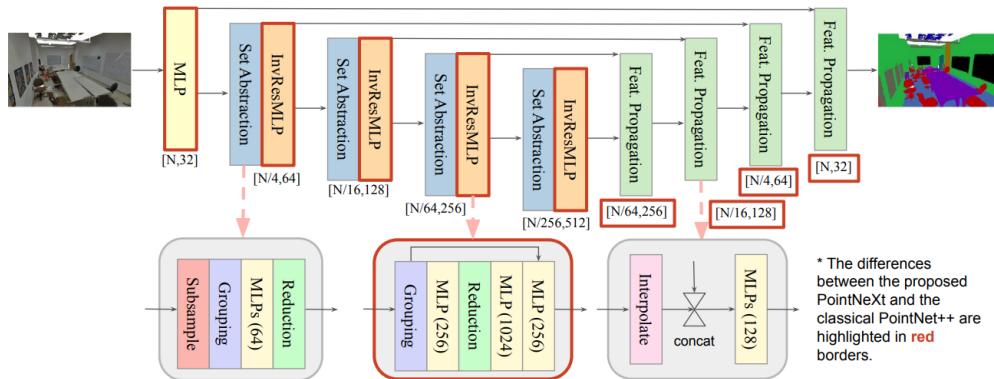


PointNet++ [Qi et al. 2017]

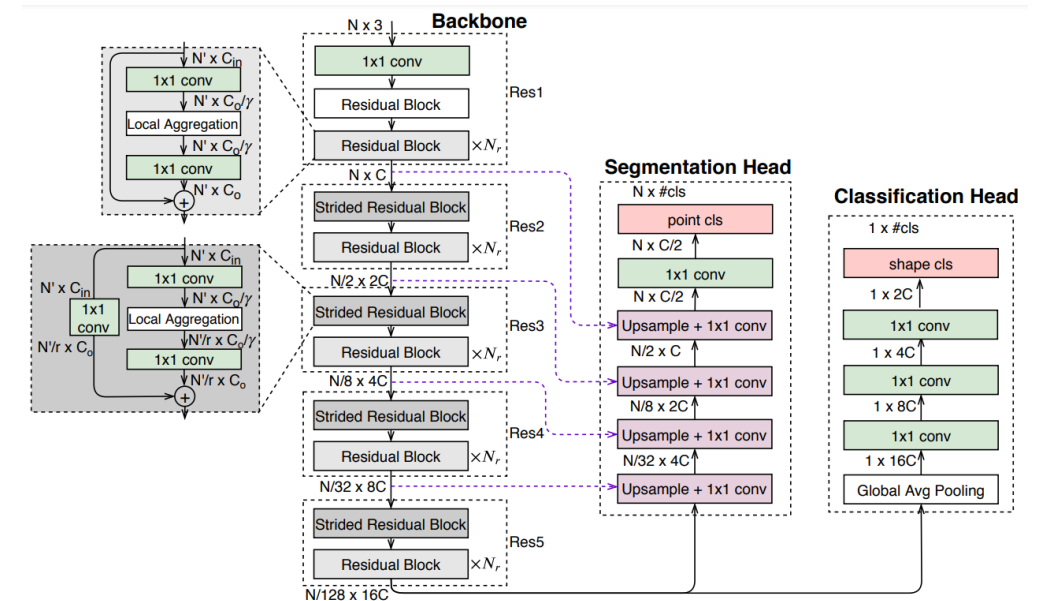
Prior work: Point-based networks



PointNet++ [Qi et al. 2017]

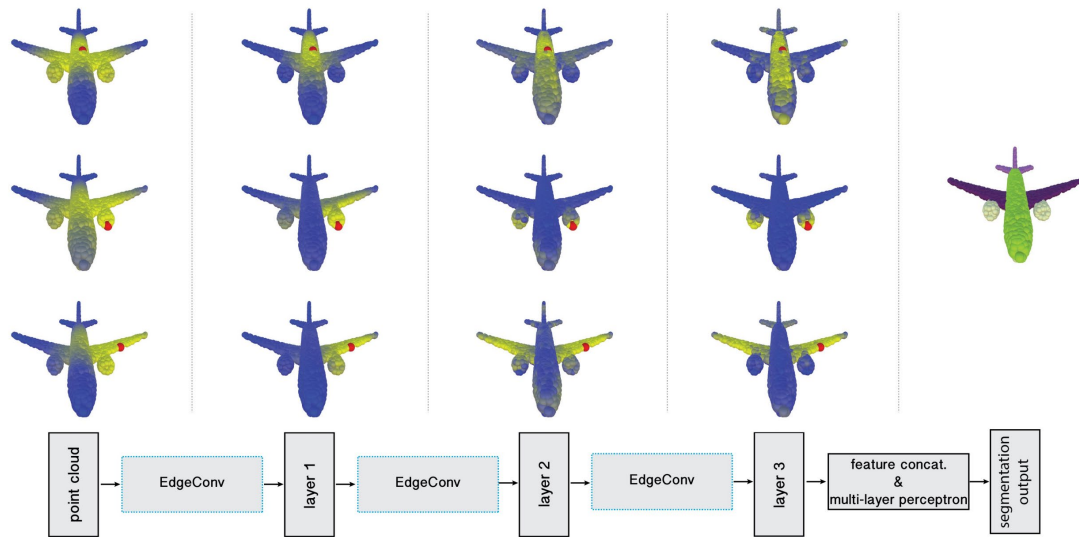


PointNeXt [Qian et al. 2022]

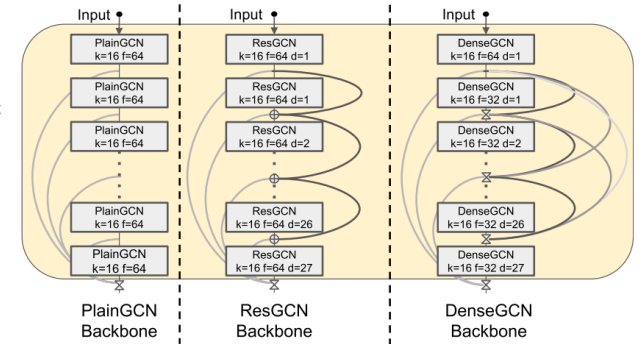
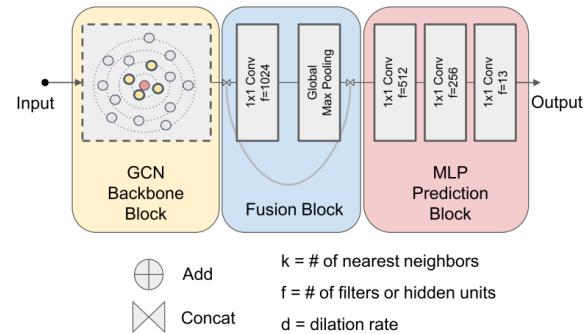


CloserLook3D [Liu et al. 2020]

Prior work: GCNs for non-Eucledian data

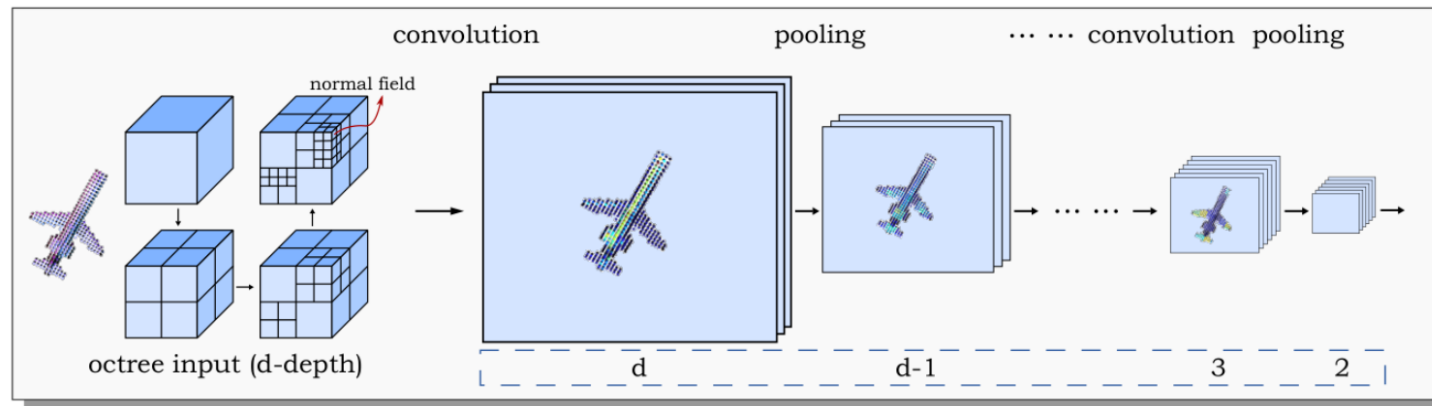


DGCNN [Wang et al. 2019]

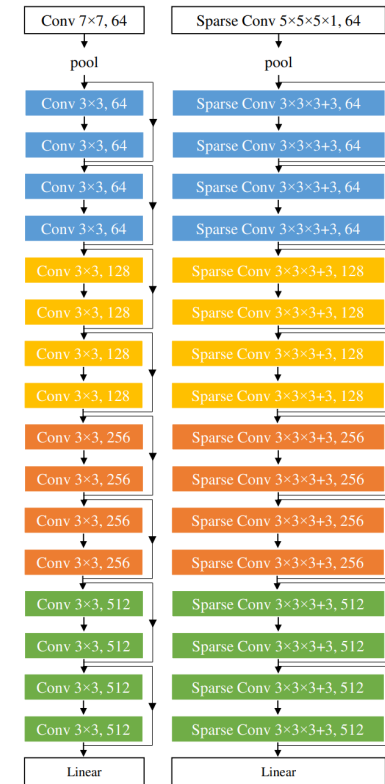


DeepGCNs [Li et al. 2023]

Prior work: Volumetric networks

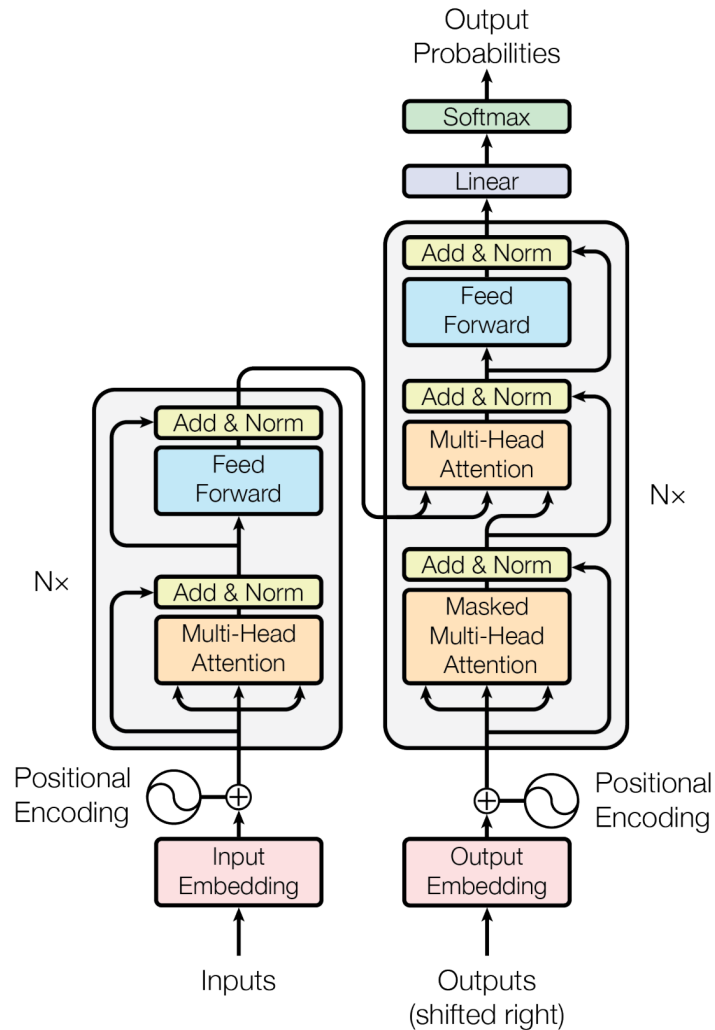


O-CNN [Wang et al. 2017]

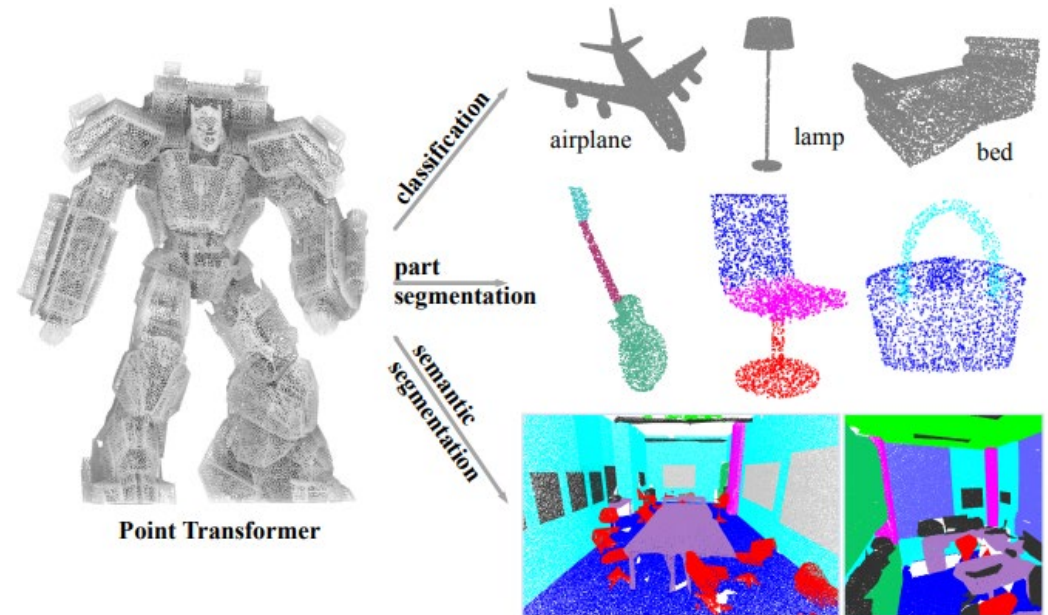


MinkowskiNet [Choy et al. 2019]

Prior work: Attention is All You Need



Transformer [Vaswani et al. 2017]



PointTransformer v1/v2 [Zhao et al. 2021, 2022]

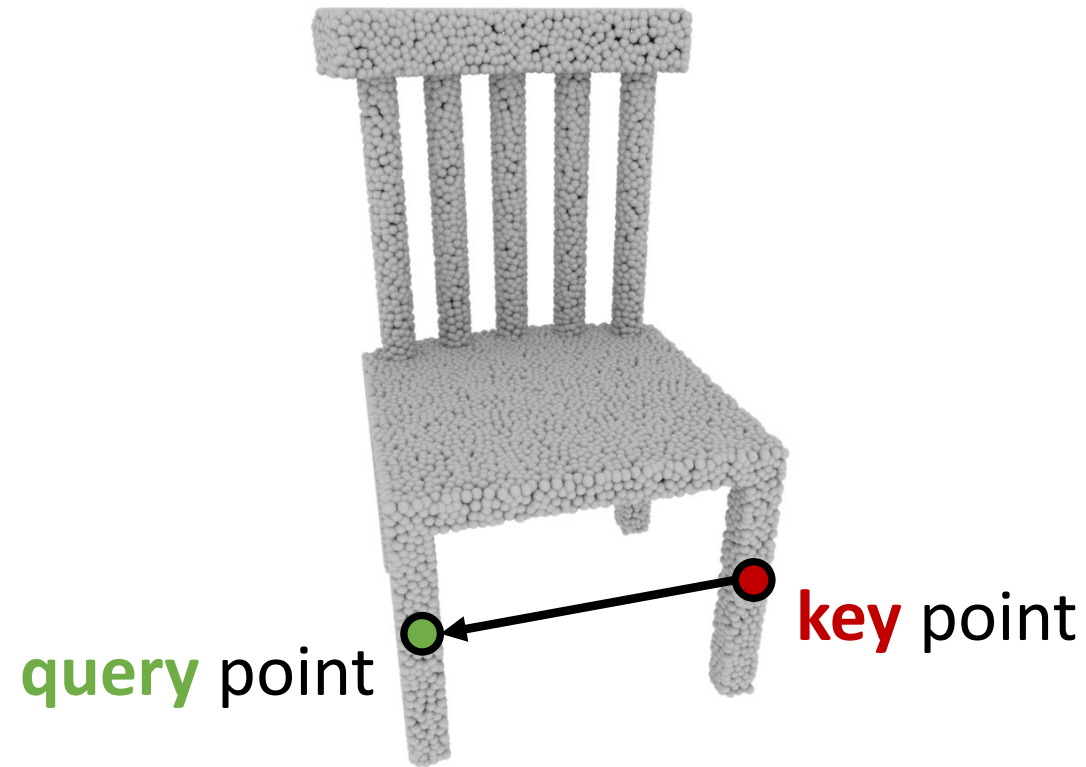
Why use **attention** for 3D representations?

Encode points such that their features capture **relations** wrt the rest of the shape



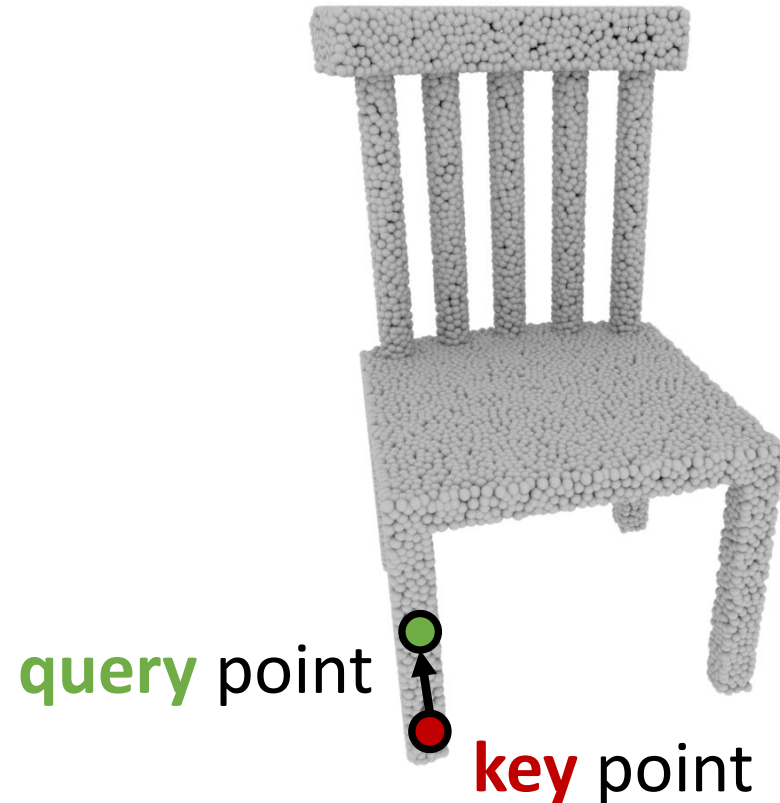
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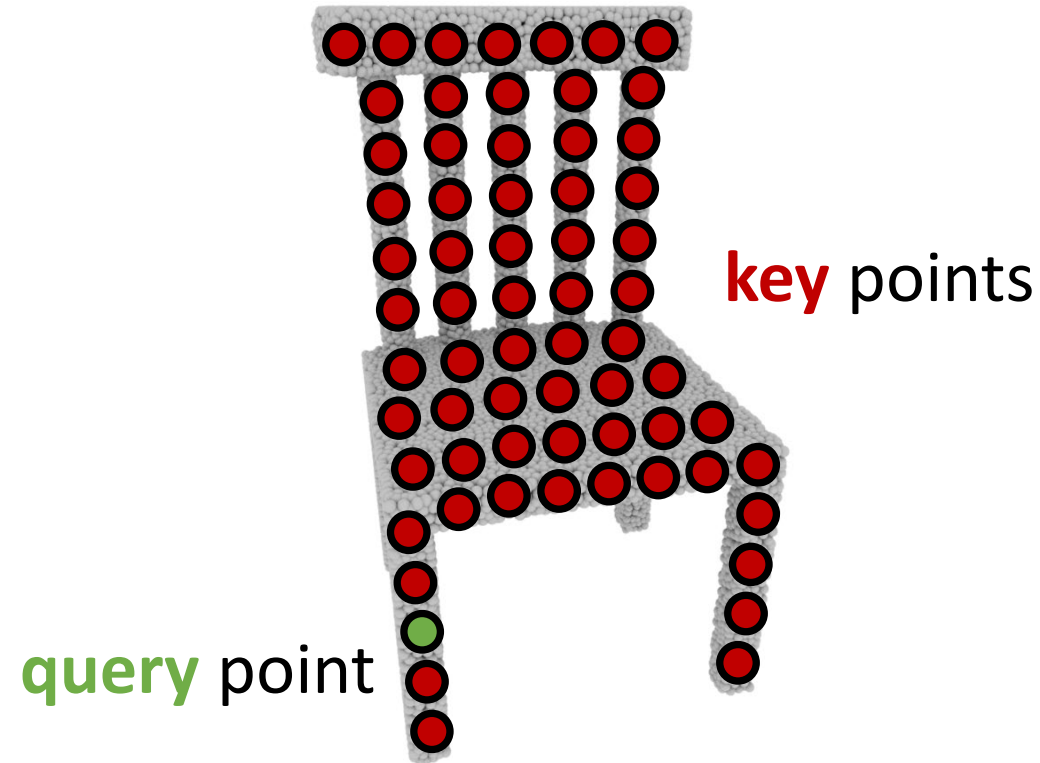
Why use **attention** for 3D representations?

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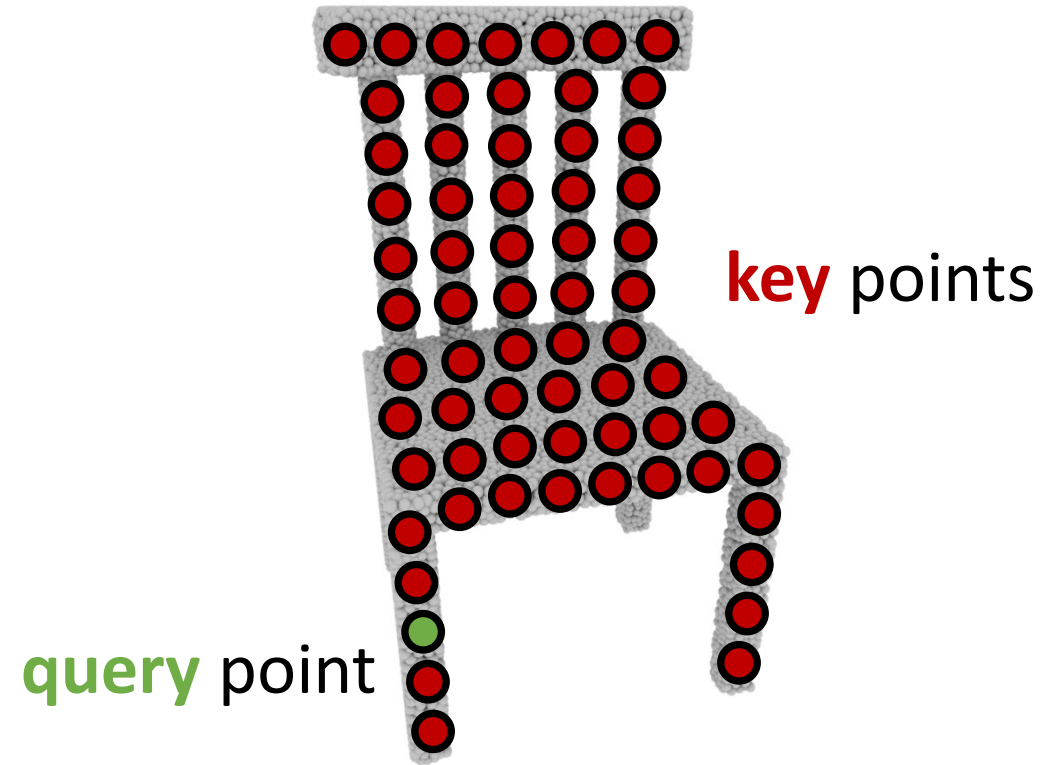
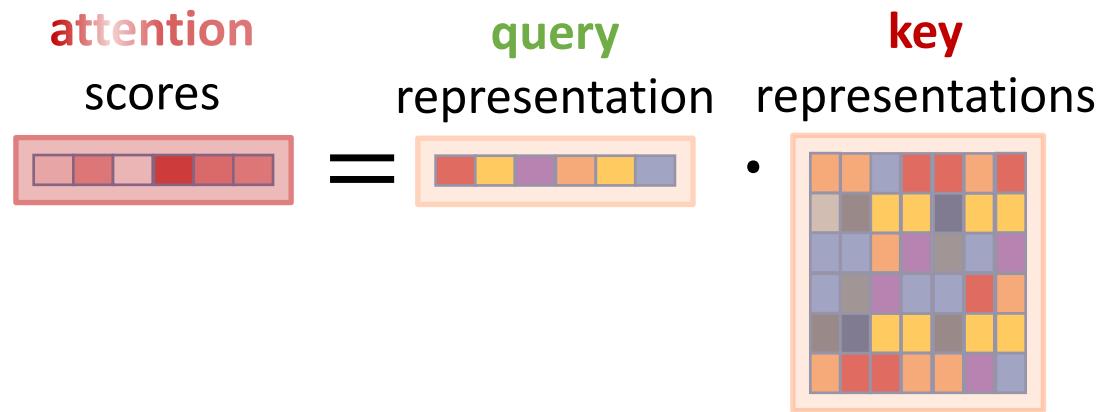
Why use **attention** for 3D representations?

Encode points such that their features capture **relations** wrt the rest of the shape

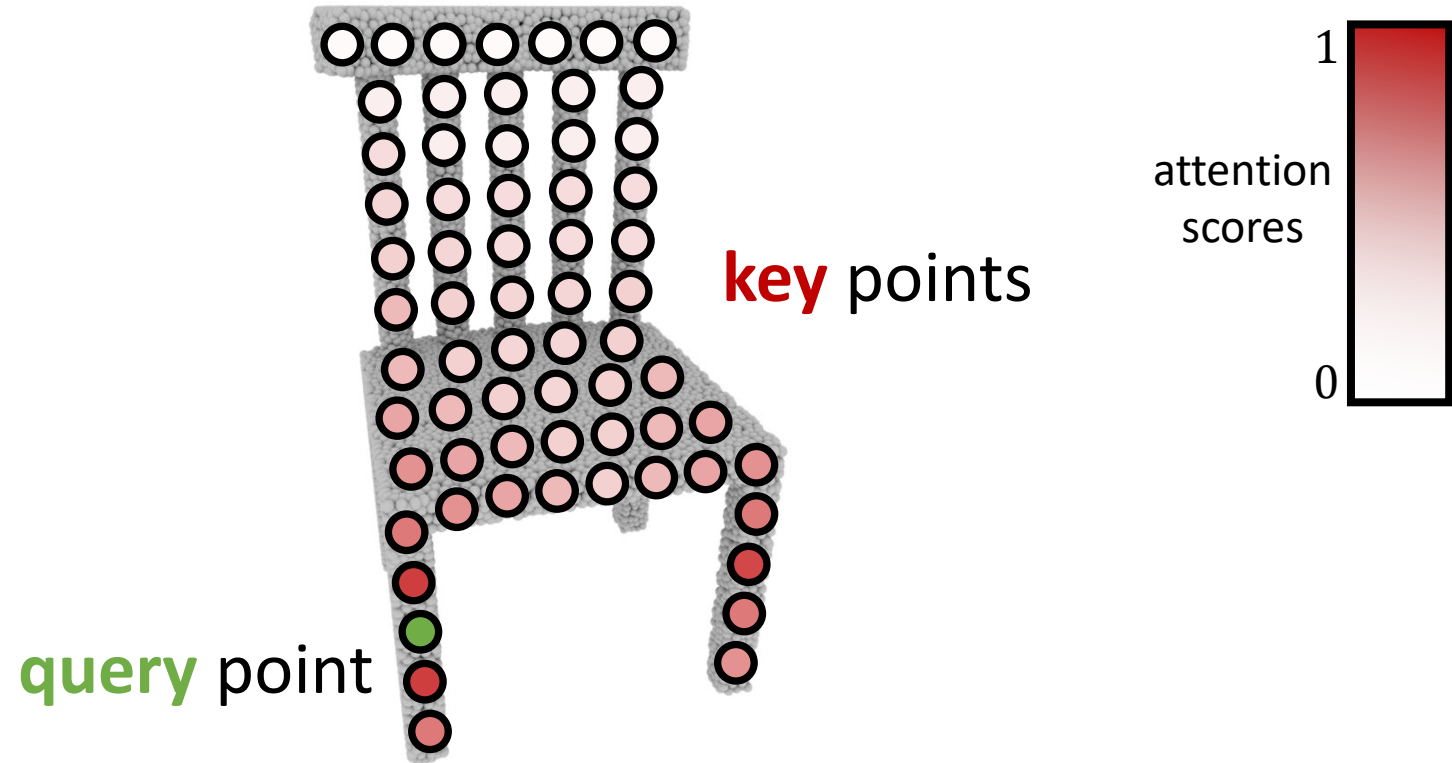


Why use **attention** for 3D representations?

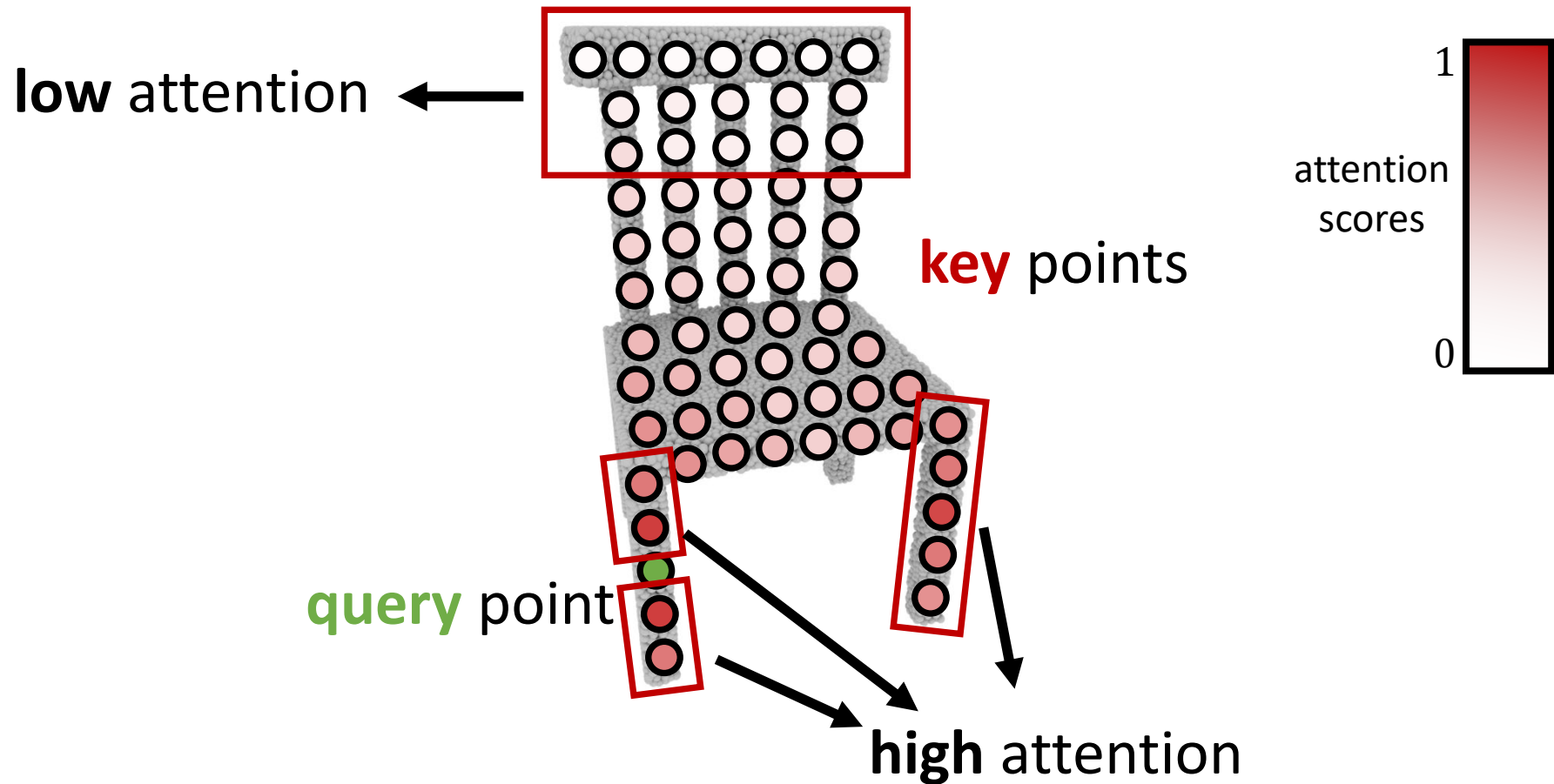
Encode points such that their features capture **relations** wrt the rest of the shape



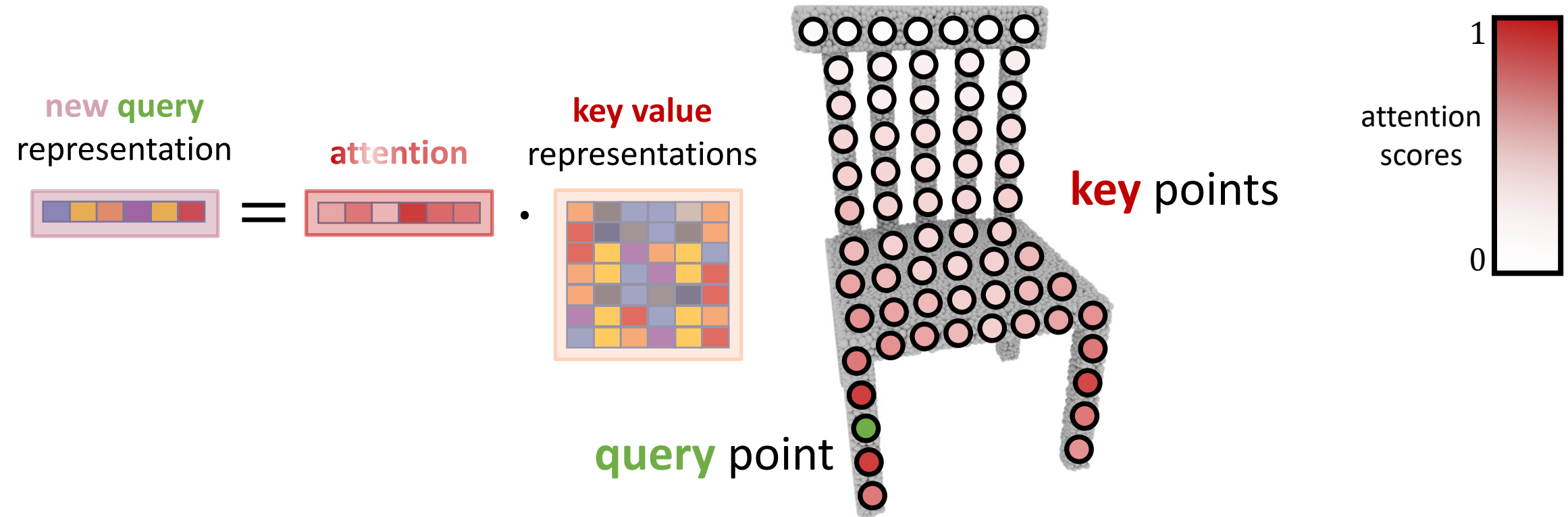
Why use **attention** for 3D representations?



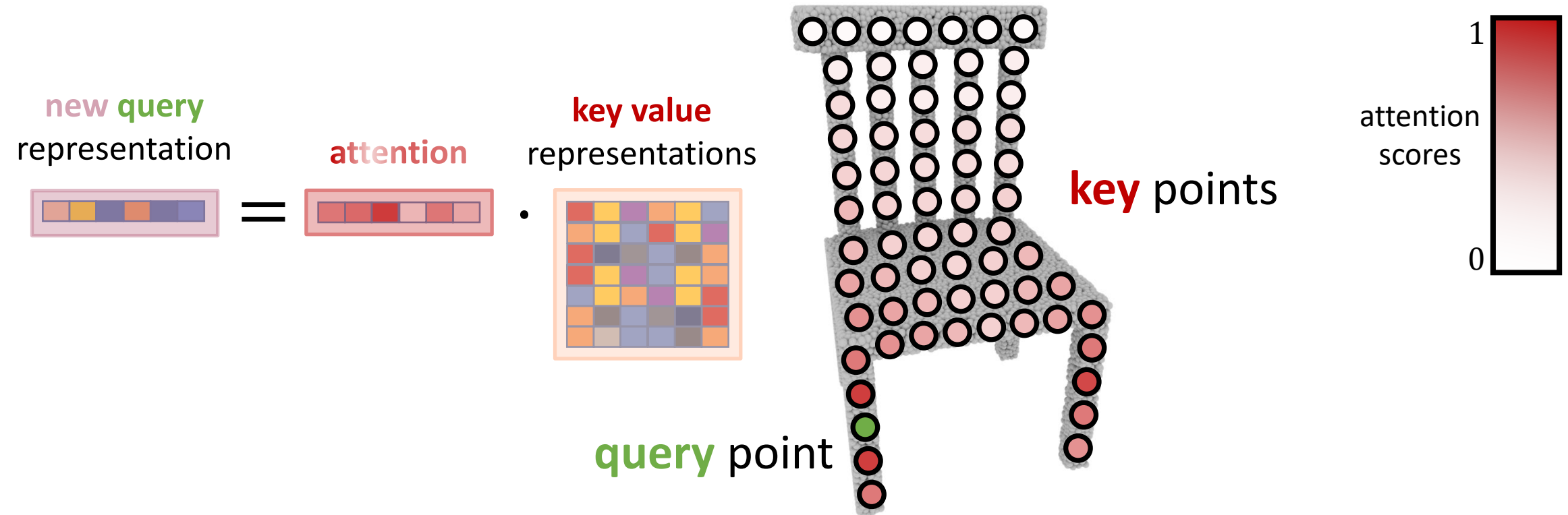
Why use **attention** for 3D representations?



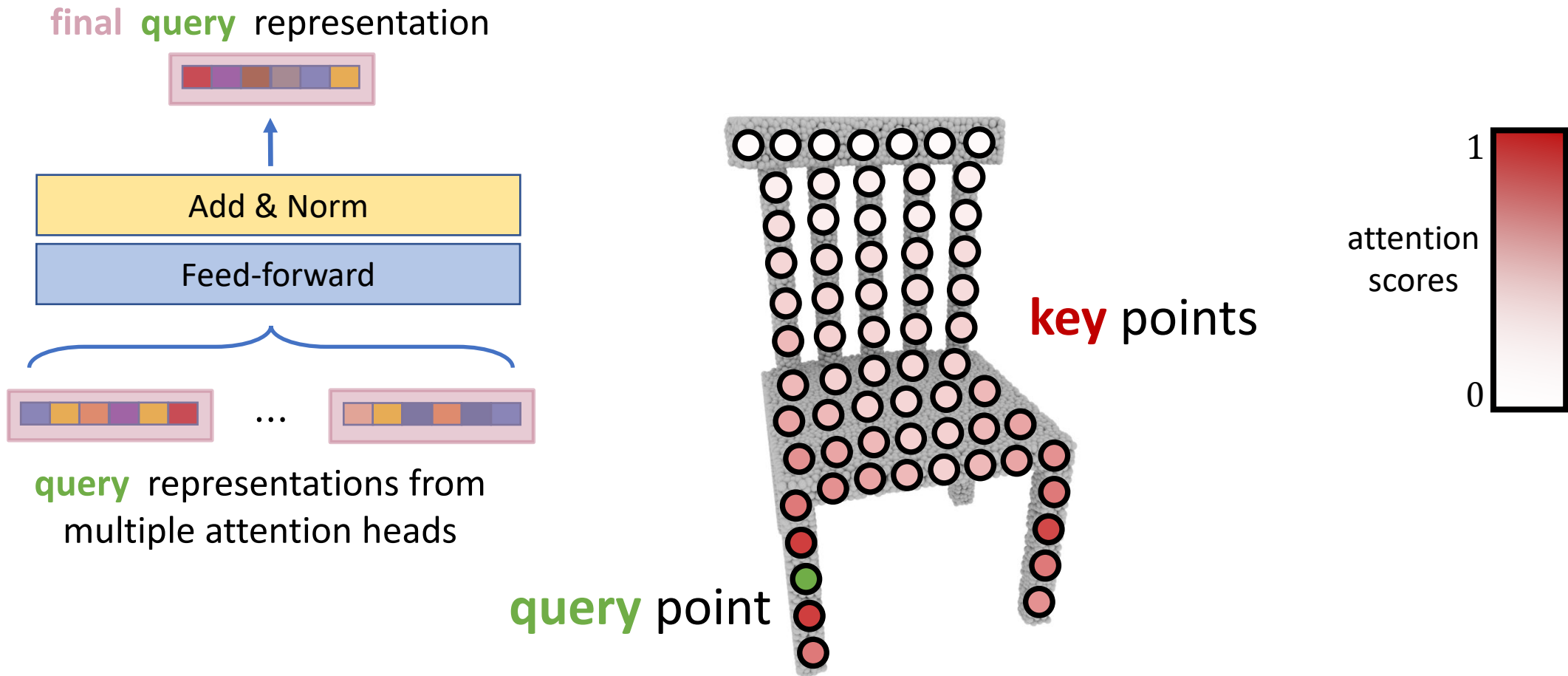
Why use **attention** for 3D representations?



Why use **attention** for 3D representations?



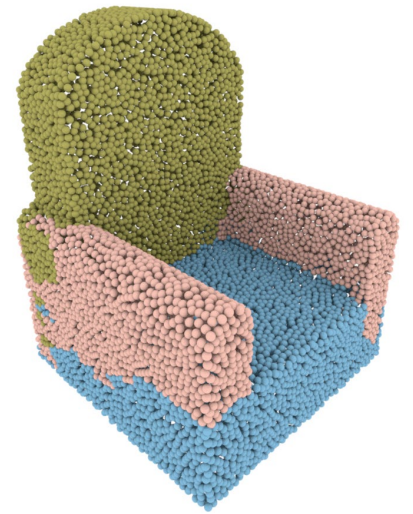
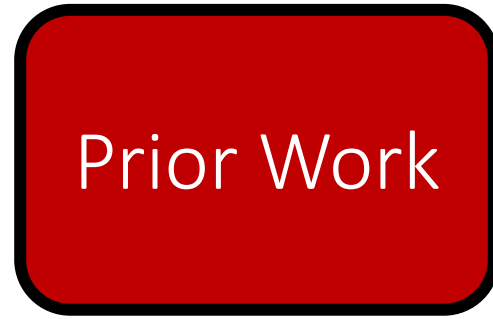
Why use **attention** for 3D representations?



Motivation: Long-range interactions **across** shapes



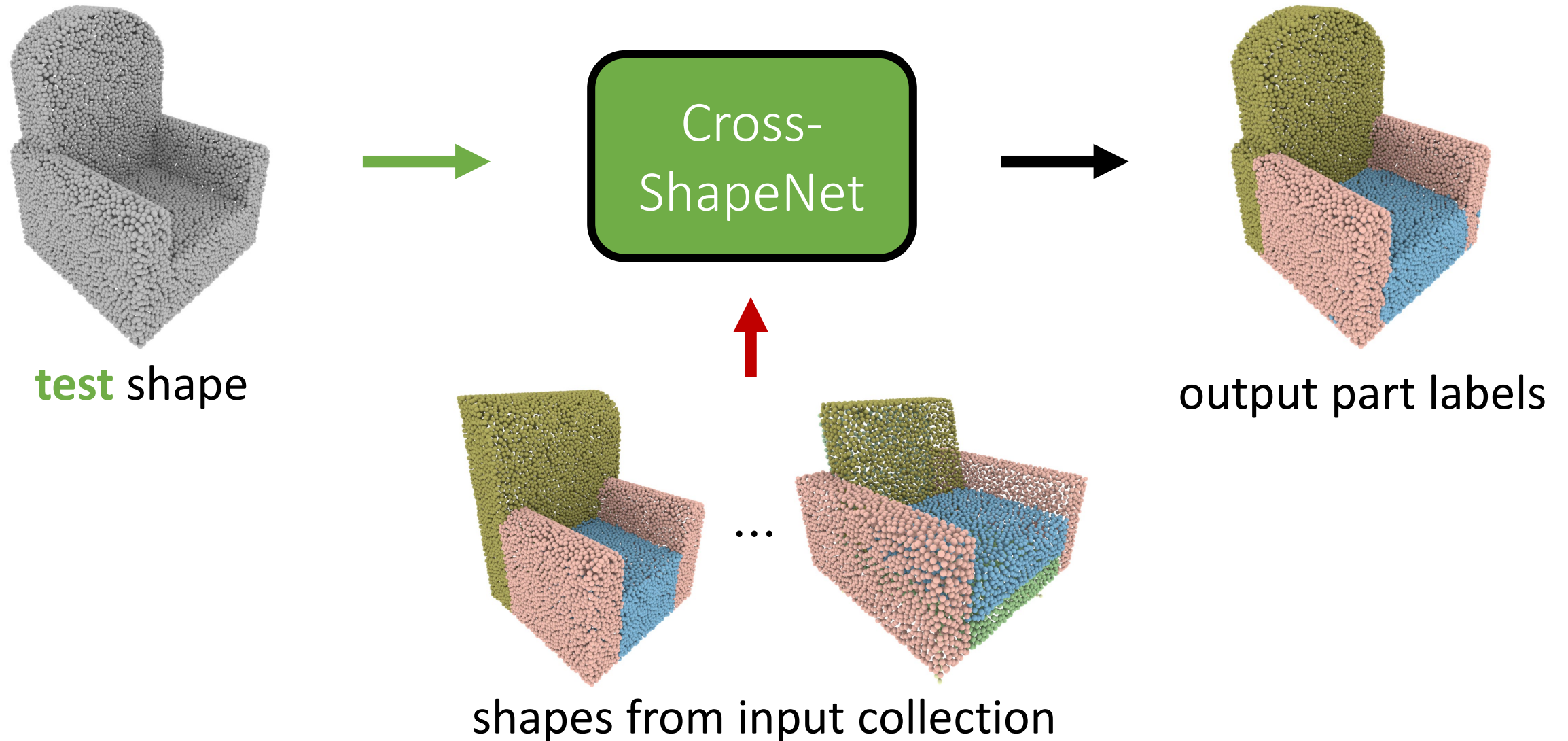
test shape



output part labels

No interactions across shapes

Motivation: Long-range interactions **across** shapes



Key challenge: Retrieve compatible shapes

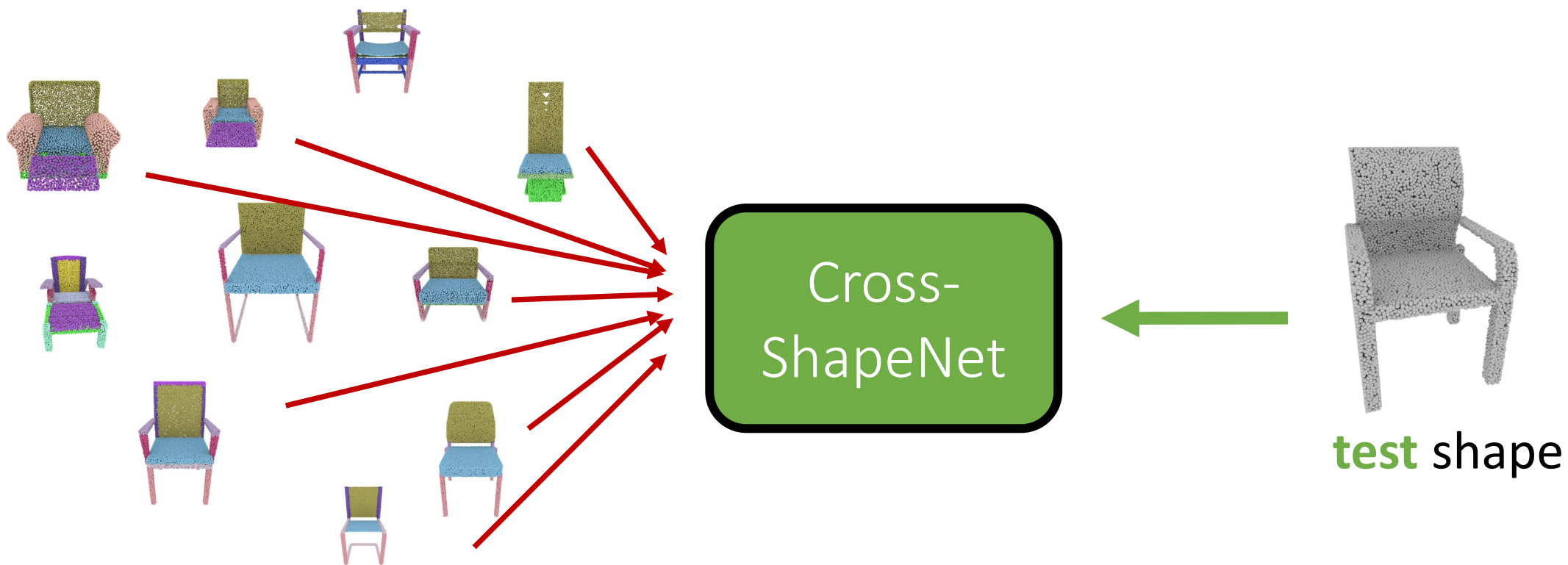


Shape Collection



test shape

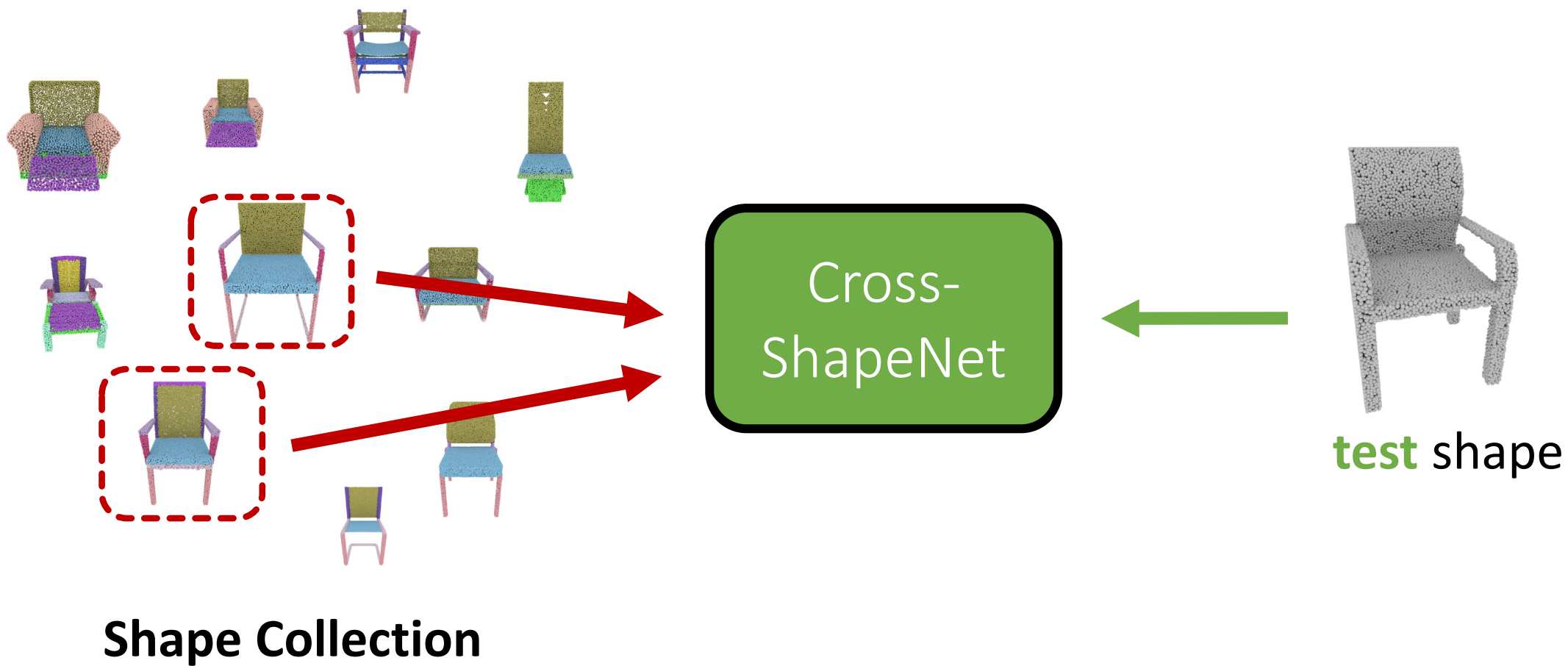
Key challenge: Retrieve compatible shapes



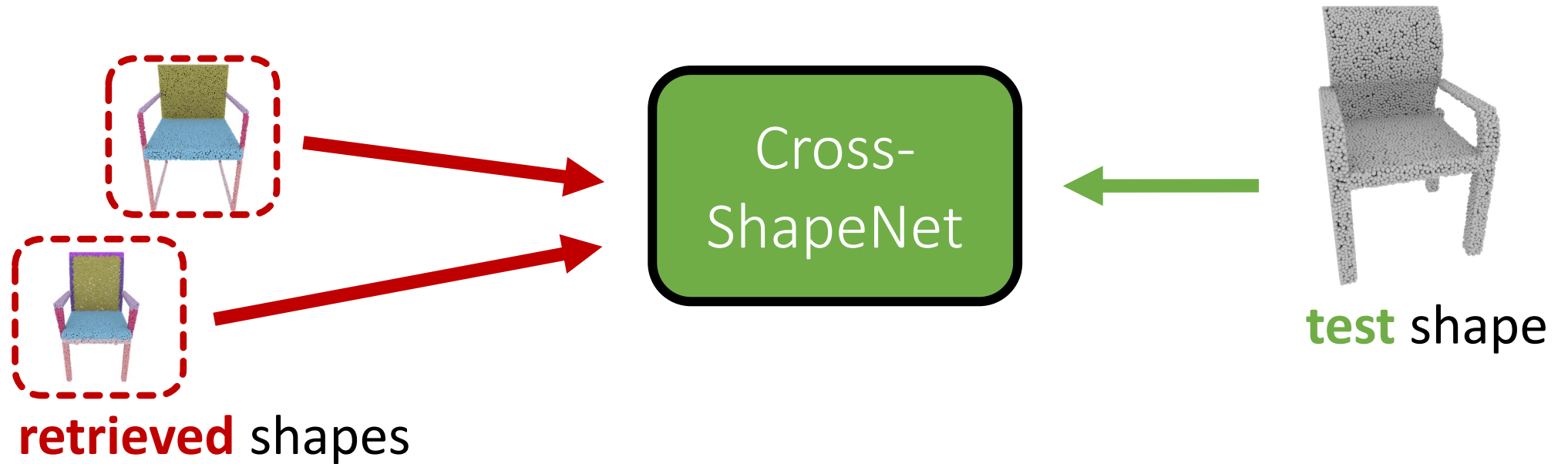
Shape Collection

test shape

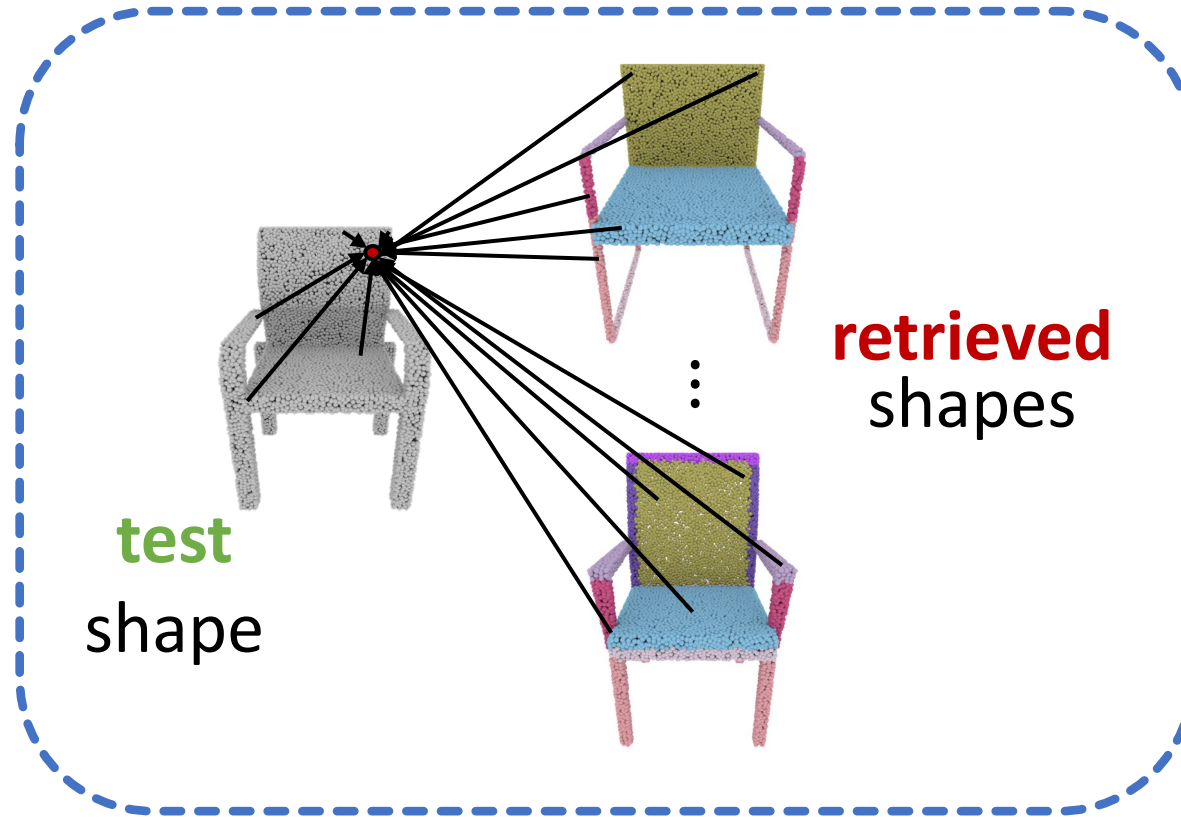
Key challenge: Retrieve compatible shapes



Key challenge: Combine multiple shapes

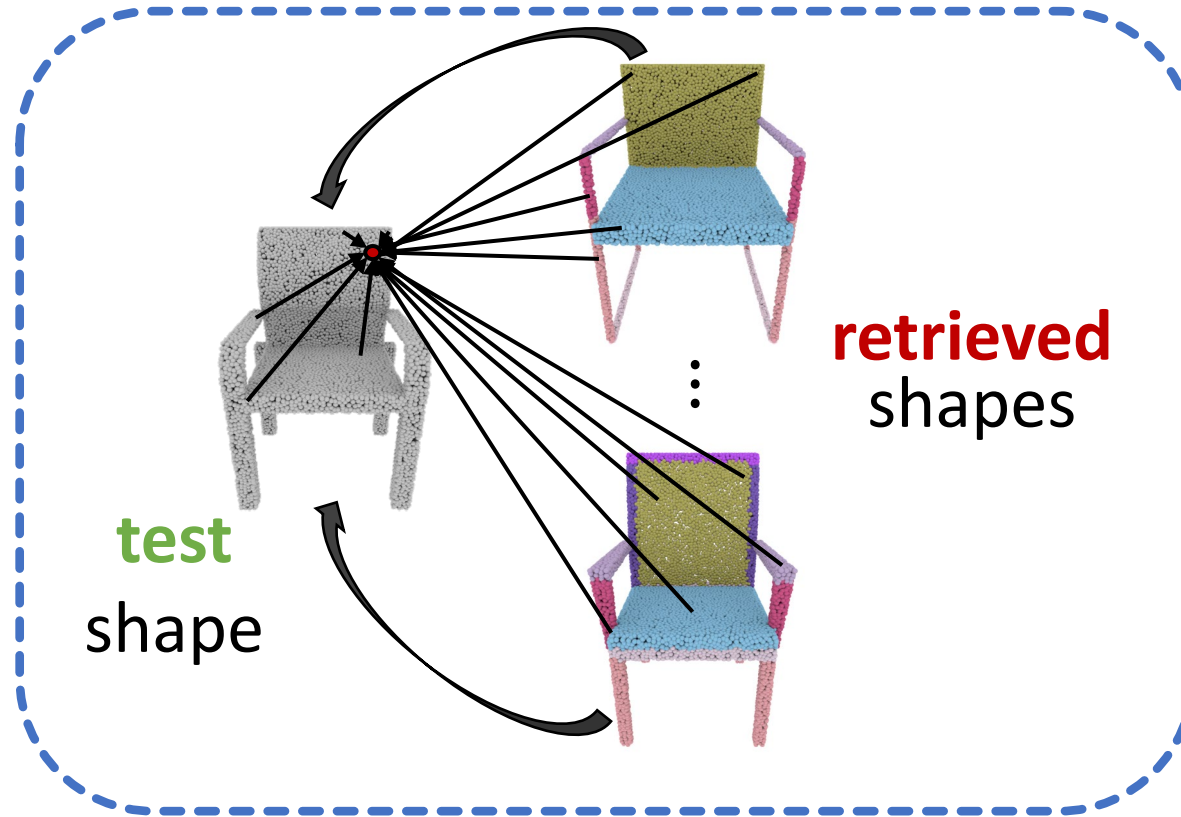


Key challenge: Combine multiple shapes



Cross-shape
attention

Key challenge: Combine multiple shapes

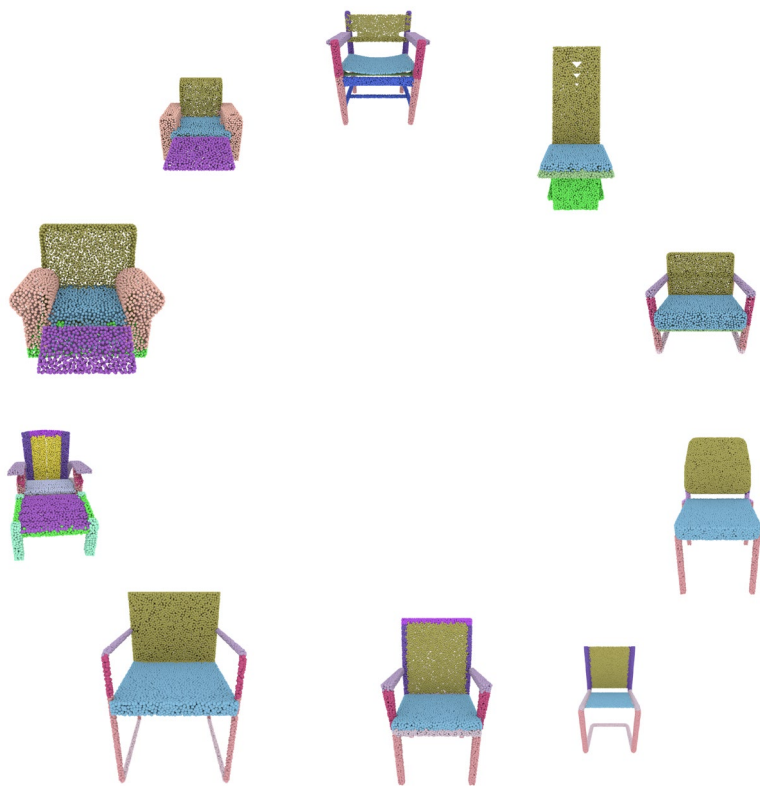


test
shape

retrieved
shapes

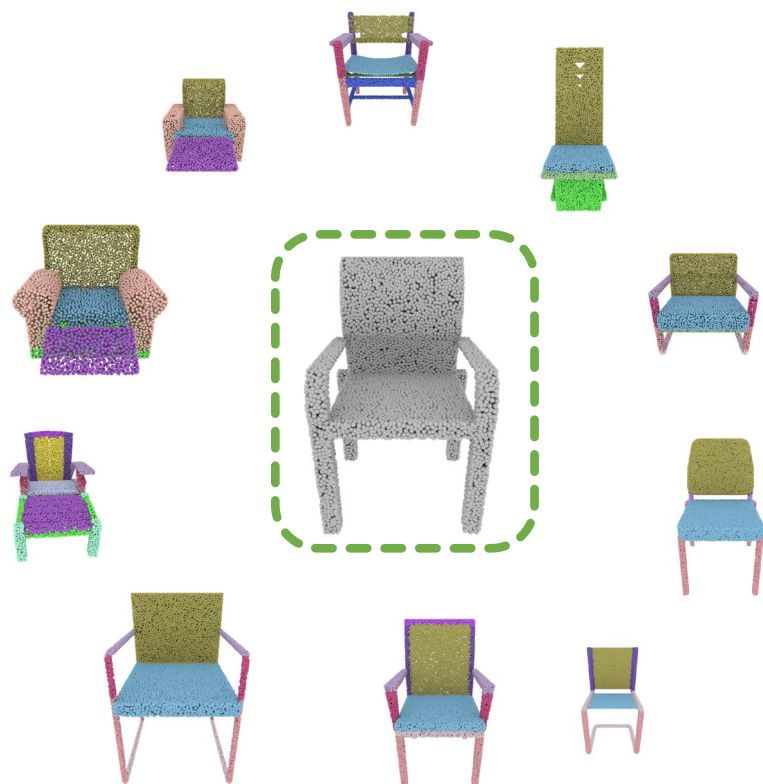
Cross-shape
attention

Pipeline



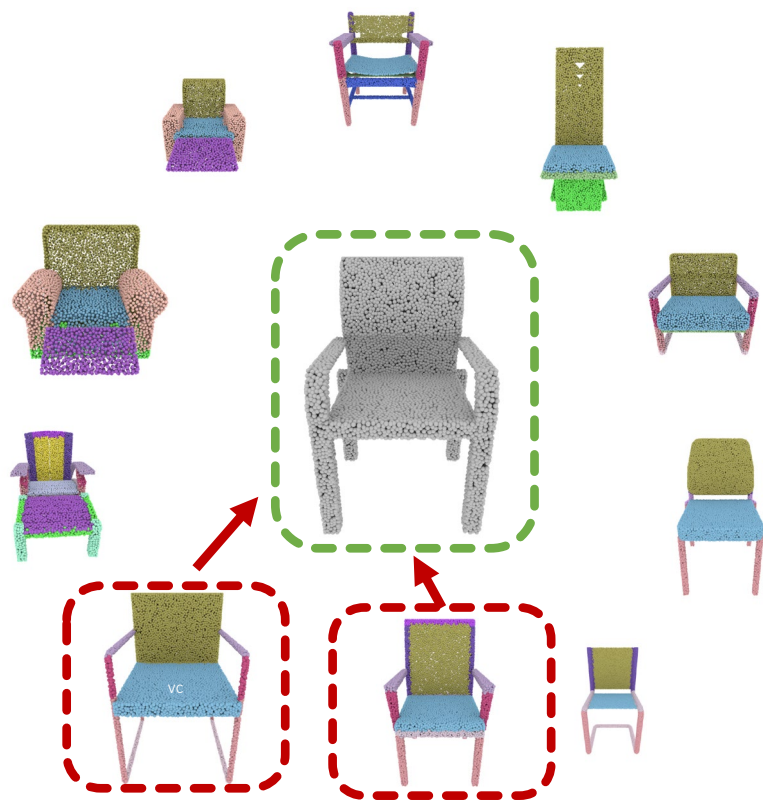
Shape Collection

Pipeline



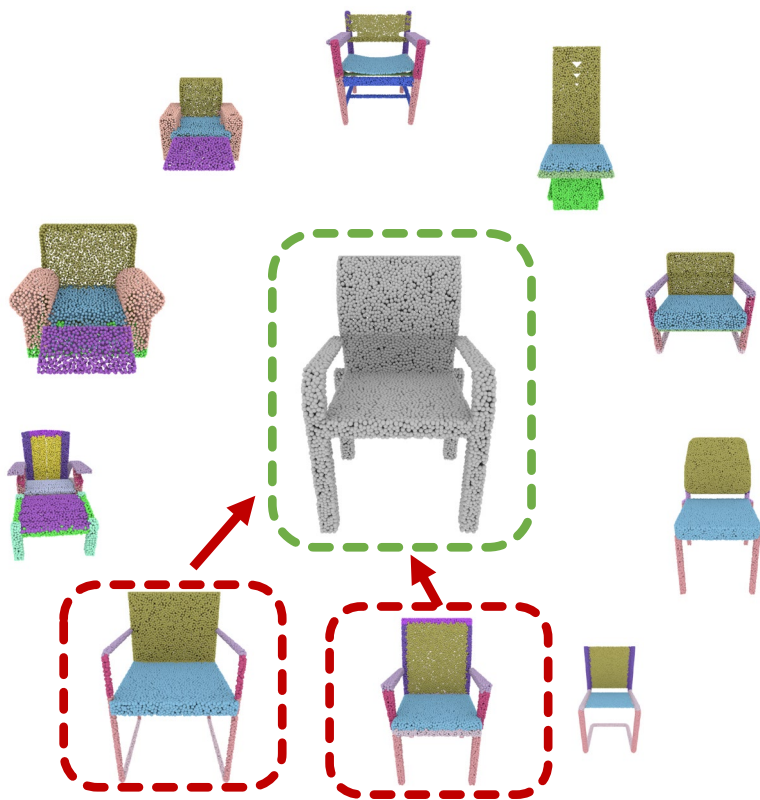
Shape Collection

Pipeline

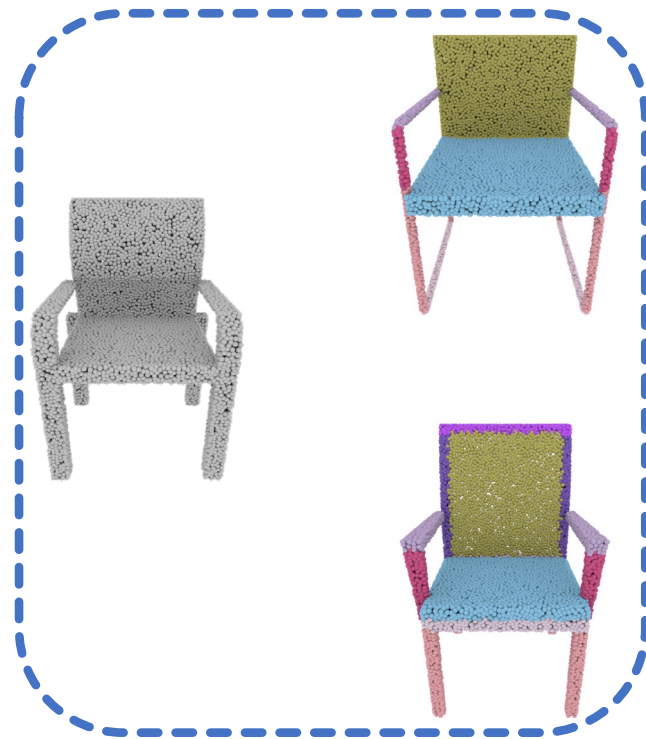


Shape Collection

Pipeline

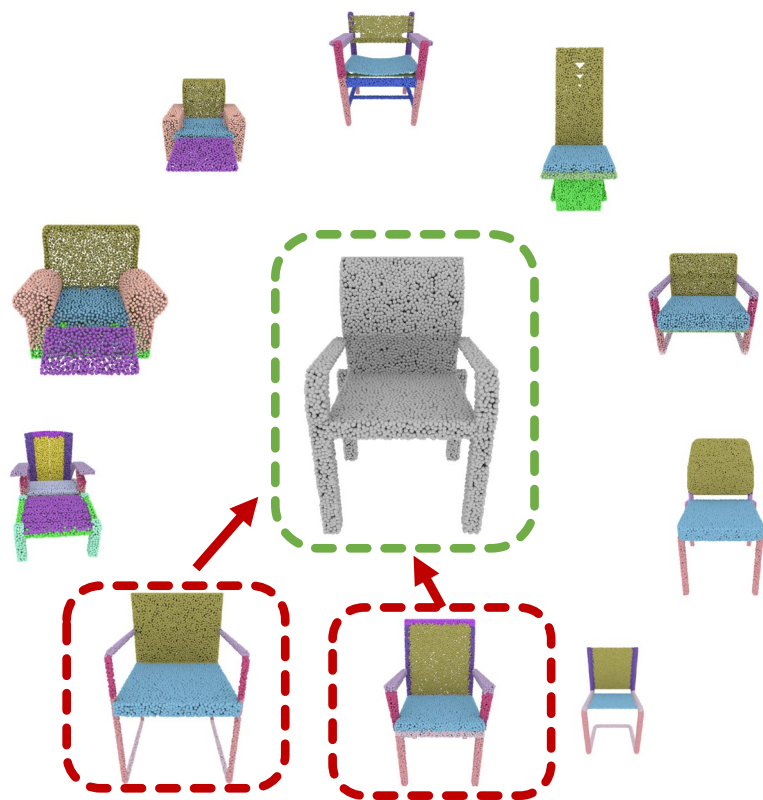


Shape Collection

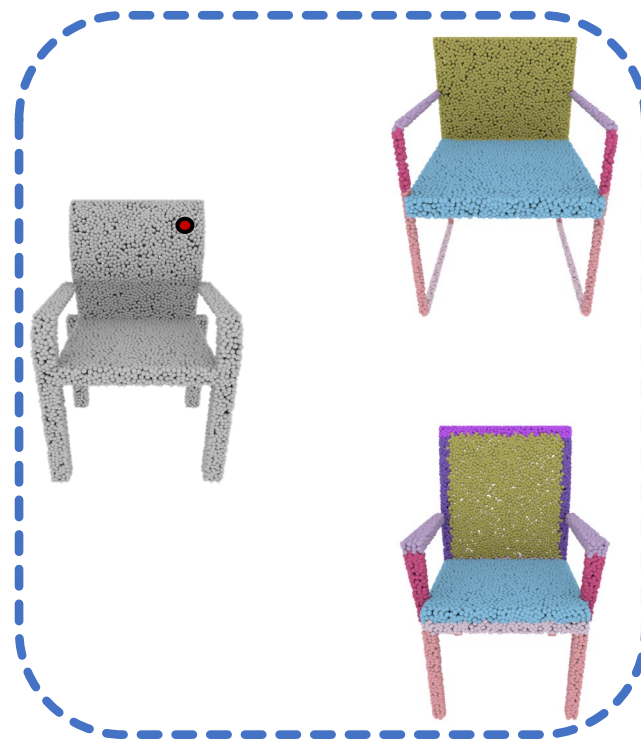


Cross-shape attention

Pipeline

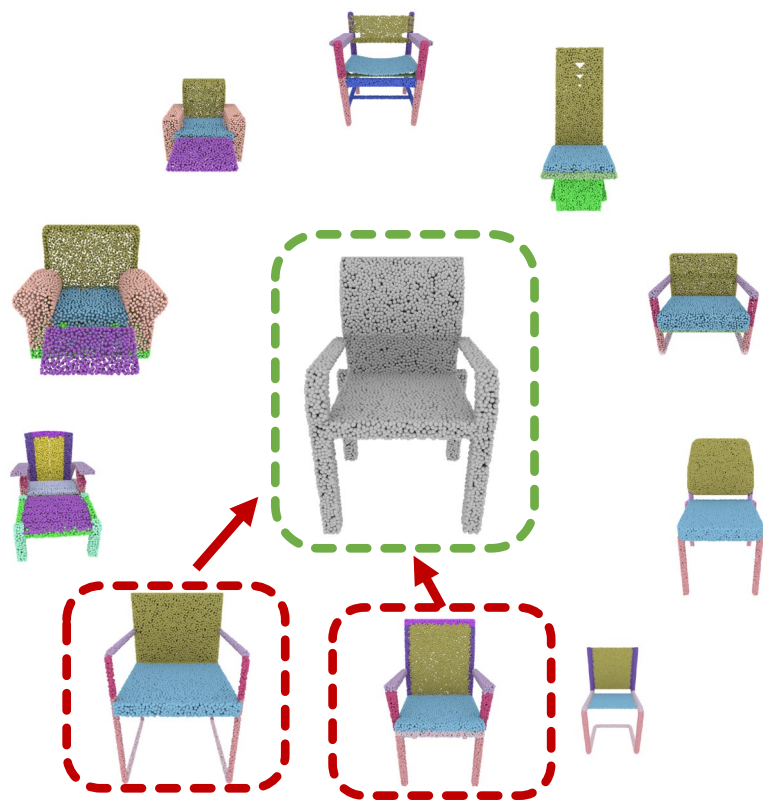


Shape Collection

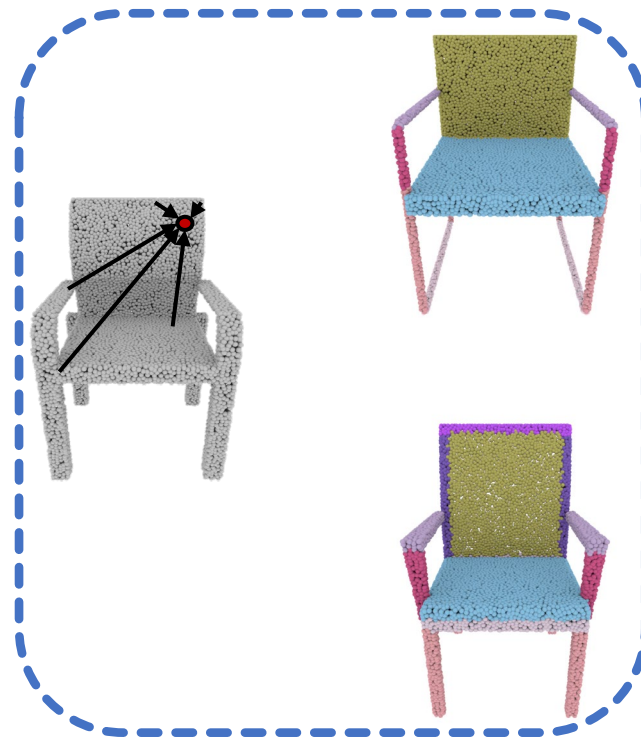


**Cross-shape
attention**

Pipeline

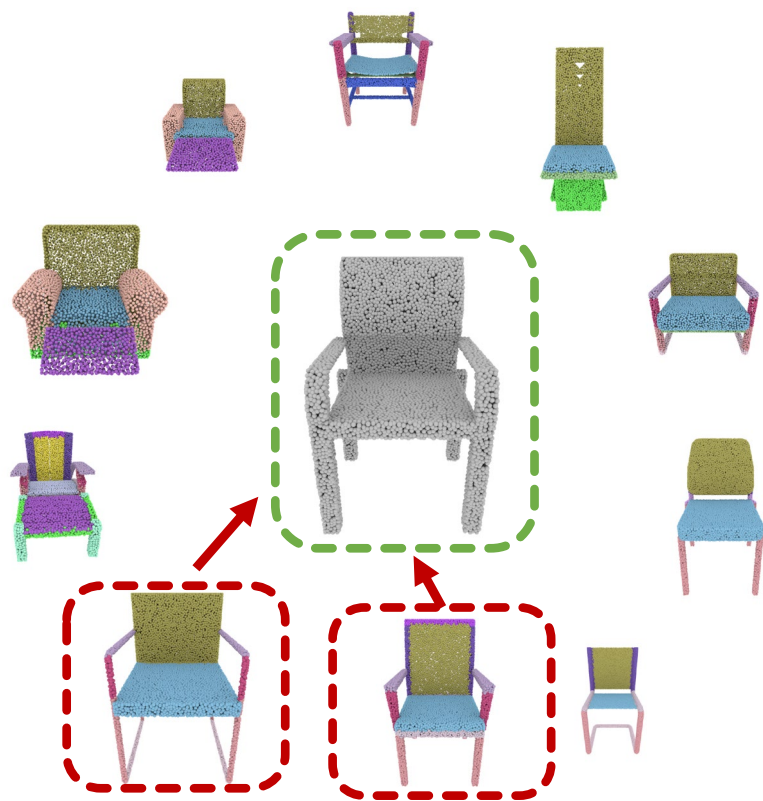


Shape Collection

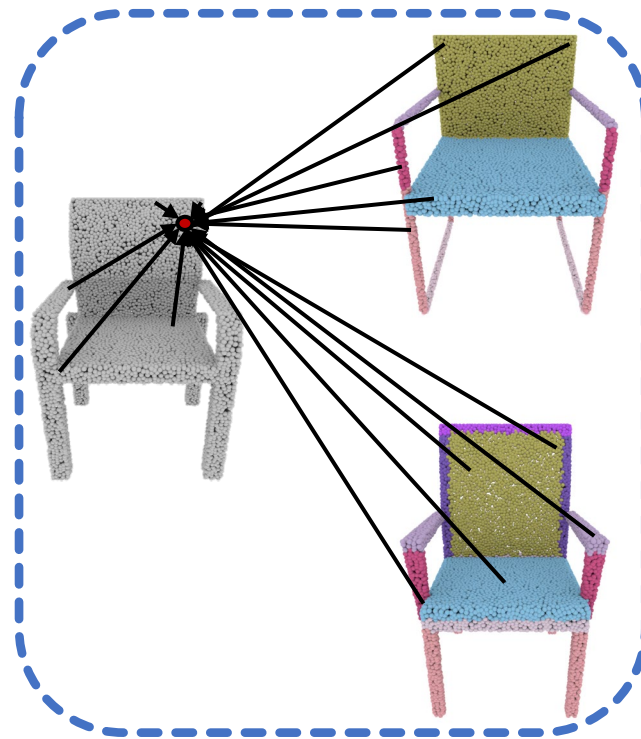


Cross-shape attention

Pipeline

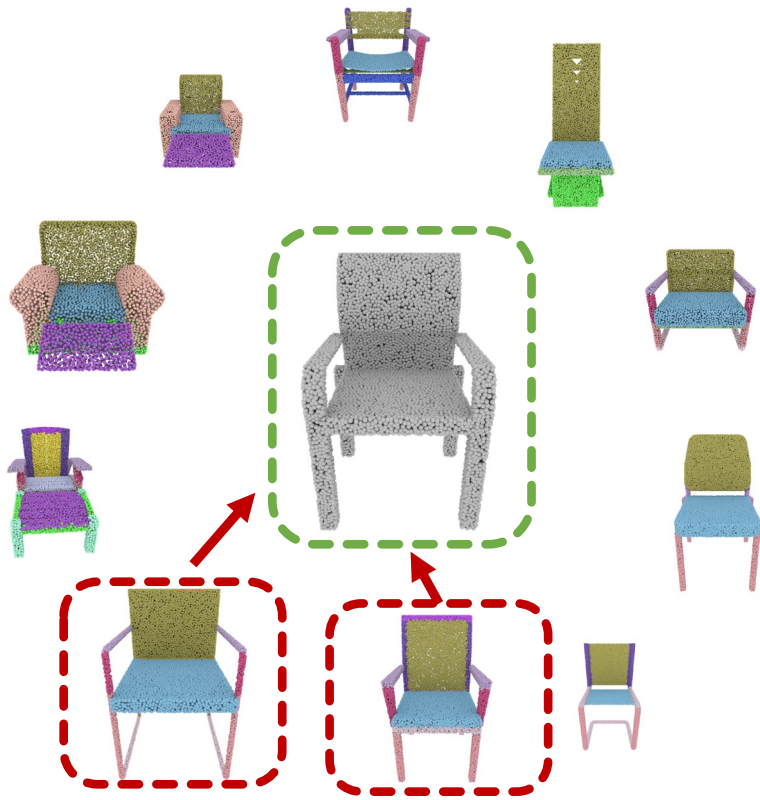


Shape Collection

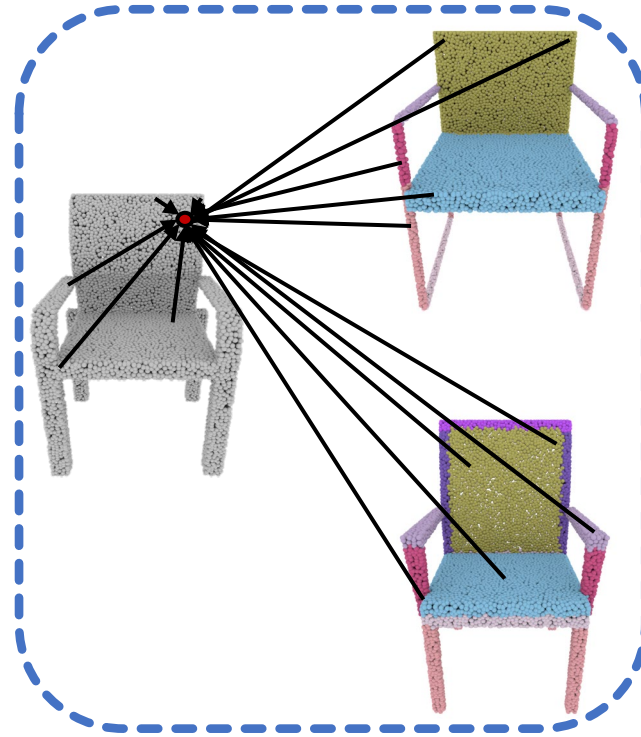


**Cross-shape
attention**

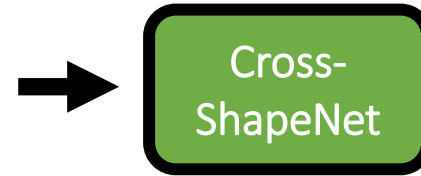
Pipeline



Shape Collection

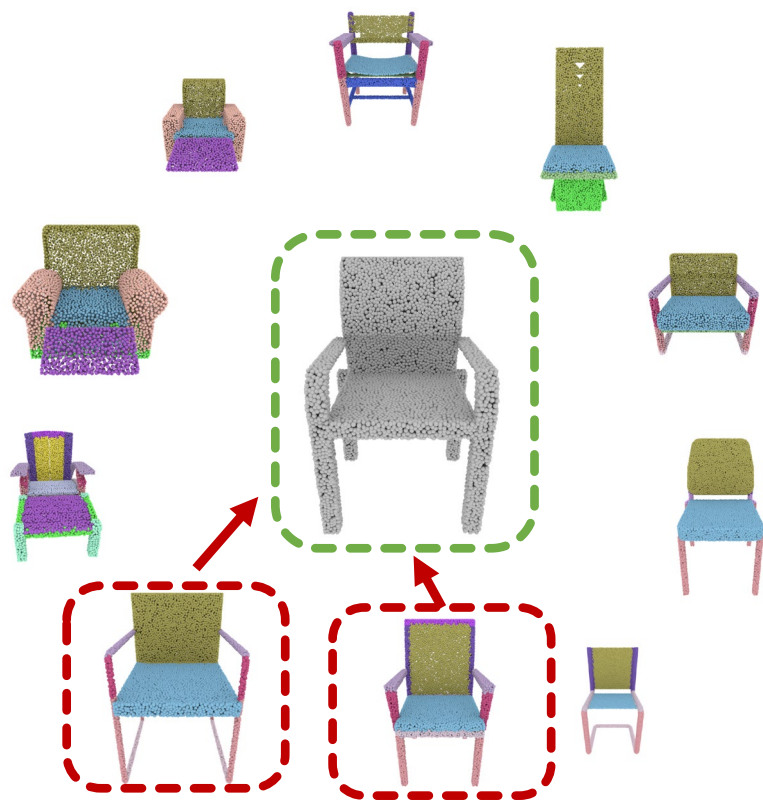


**Cross-shape
attention**

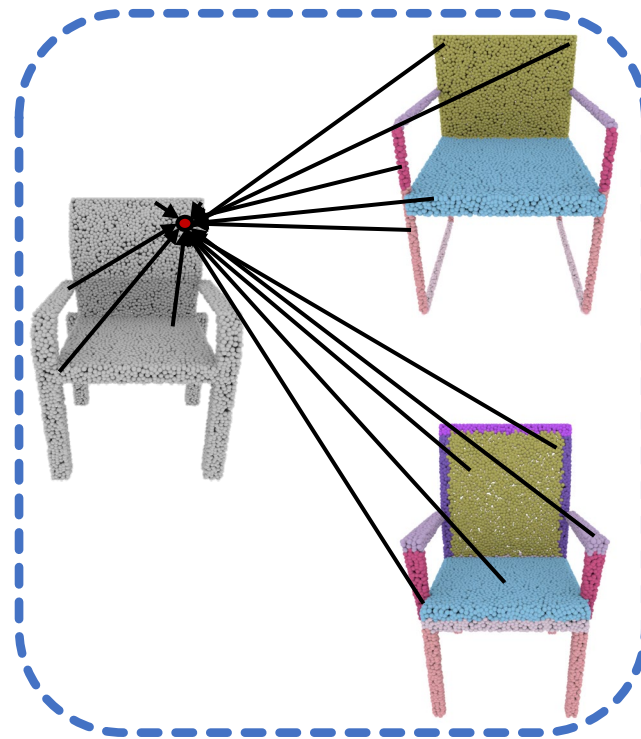


Cross-
ShapeNet

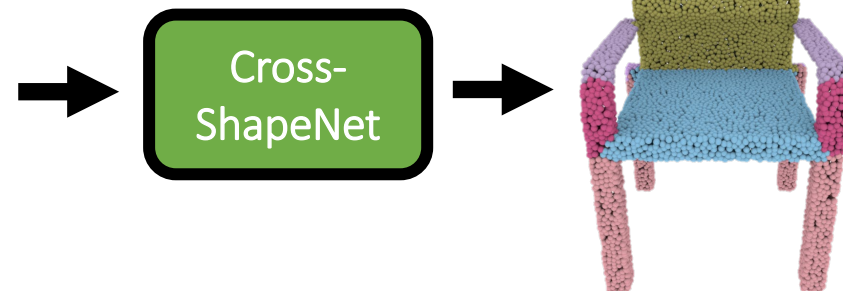
Pipeline



Shape Collection

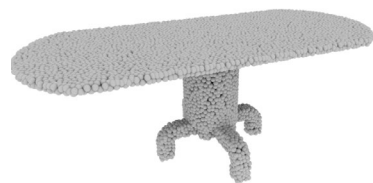


**Cross-shape
attention**



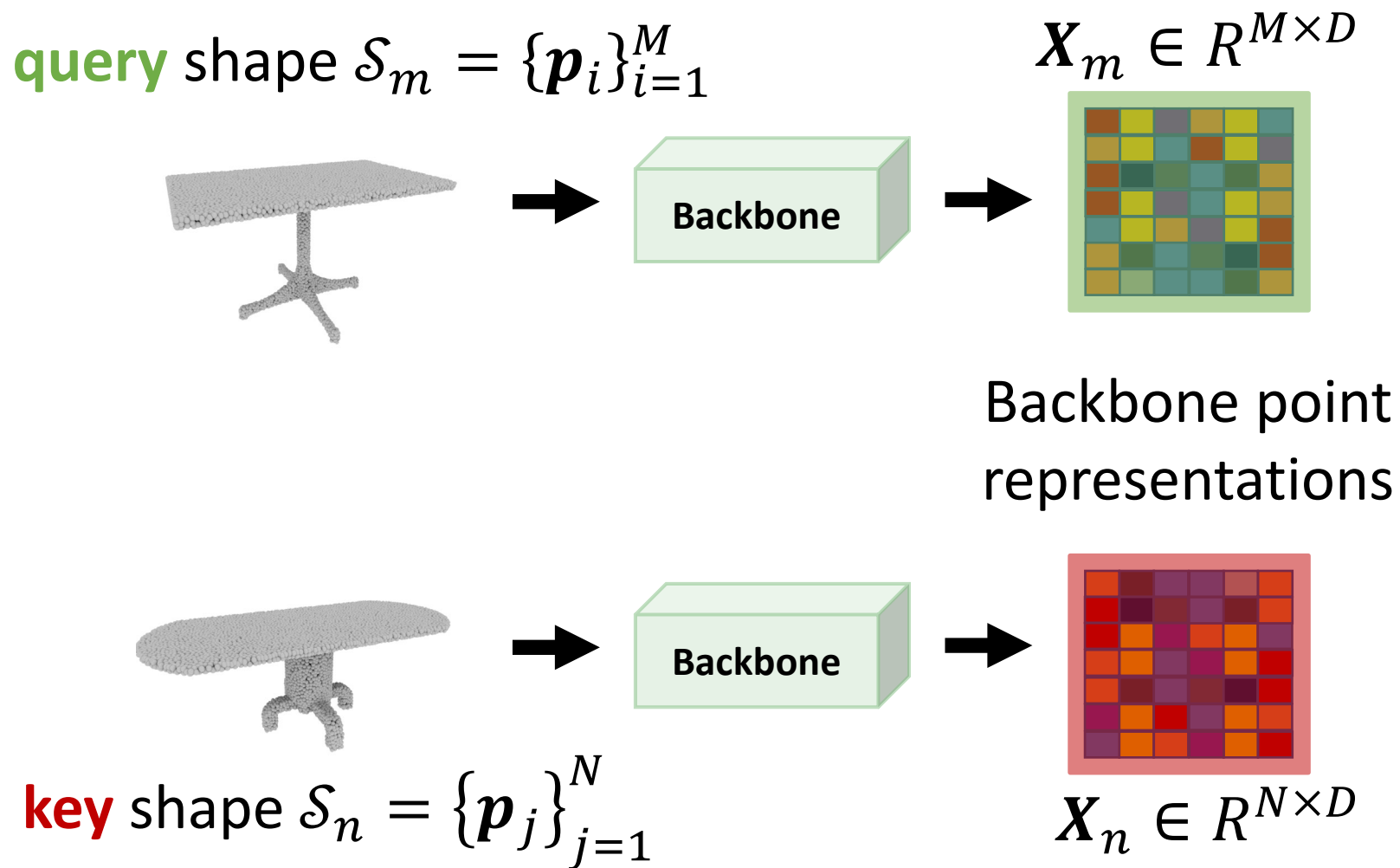
Cross-Shape Attention

query shape $\mathcal{S}_m = \{\mathbf{p}_i\}_{i=1}^M$



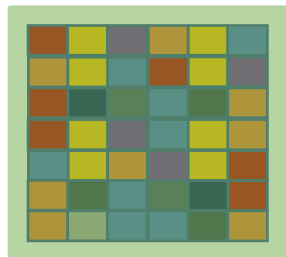
key shape $\mathcal{S}_n = \{\mathbf{p}_j\}_{j=1}^N$

Cross-Shape Attention

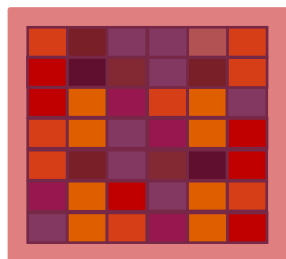


Cross-Shape Attention

$$\mathbf{X}_m \in \mathbb{R}^{M \times D}$$

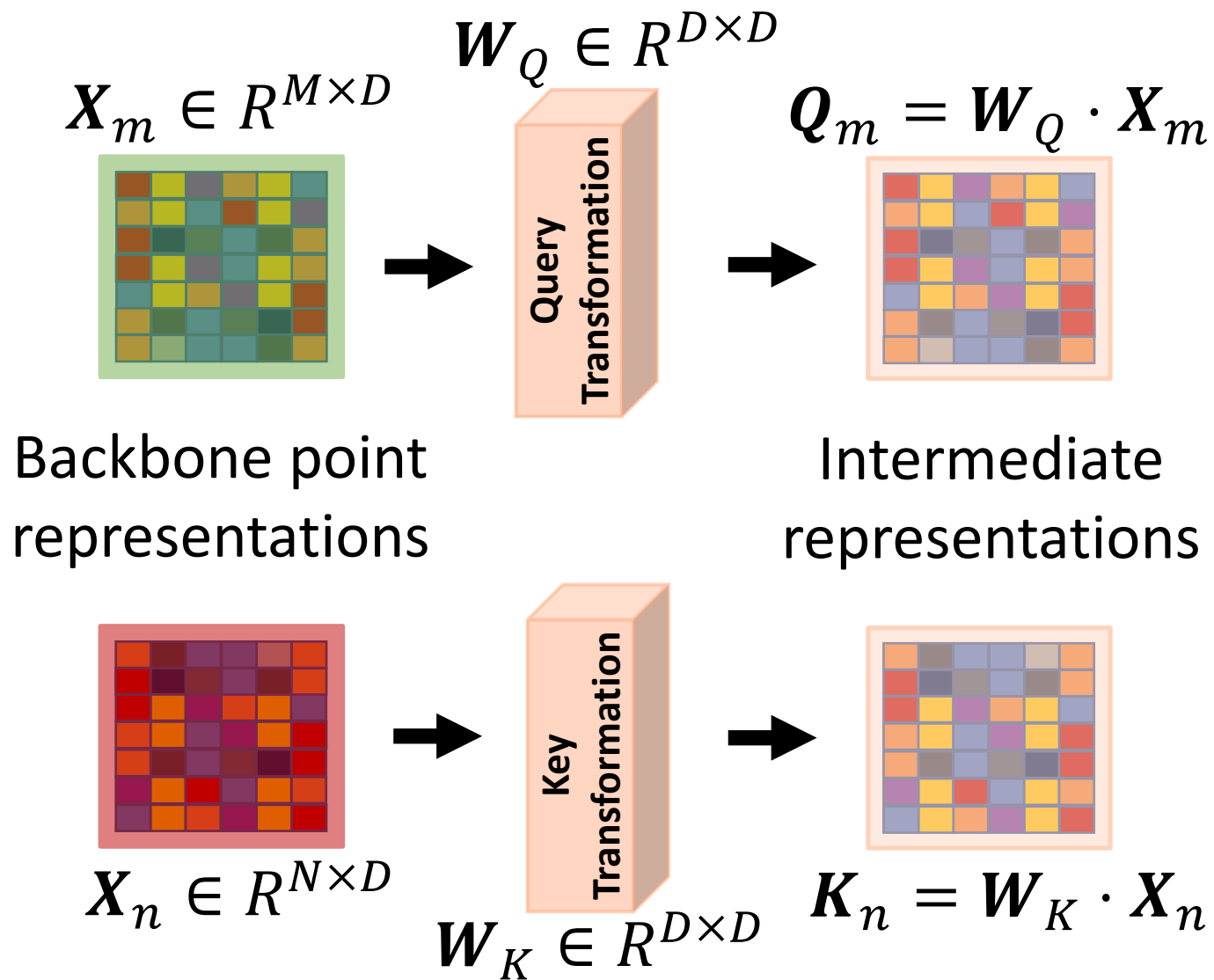


Backbone point
representations

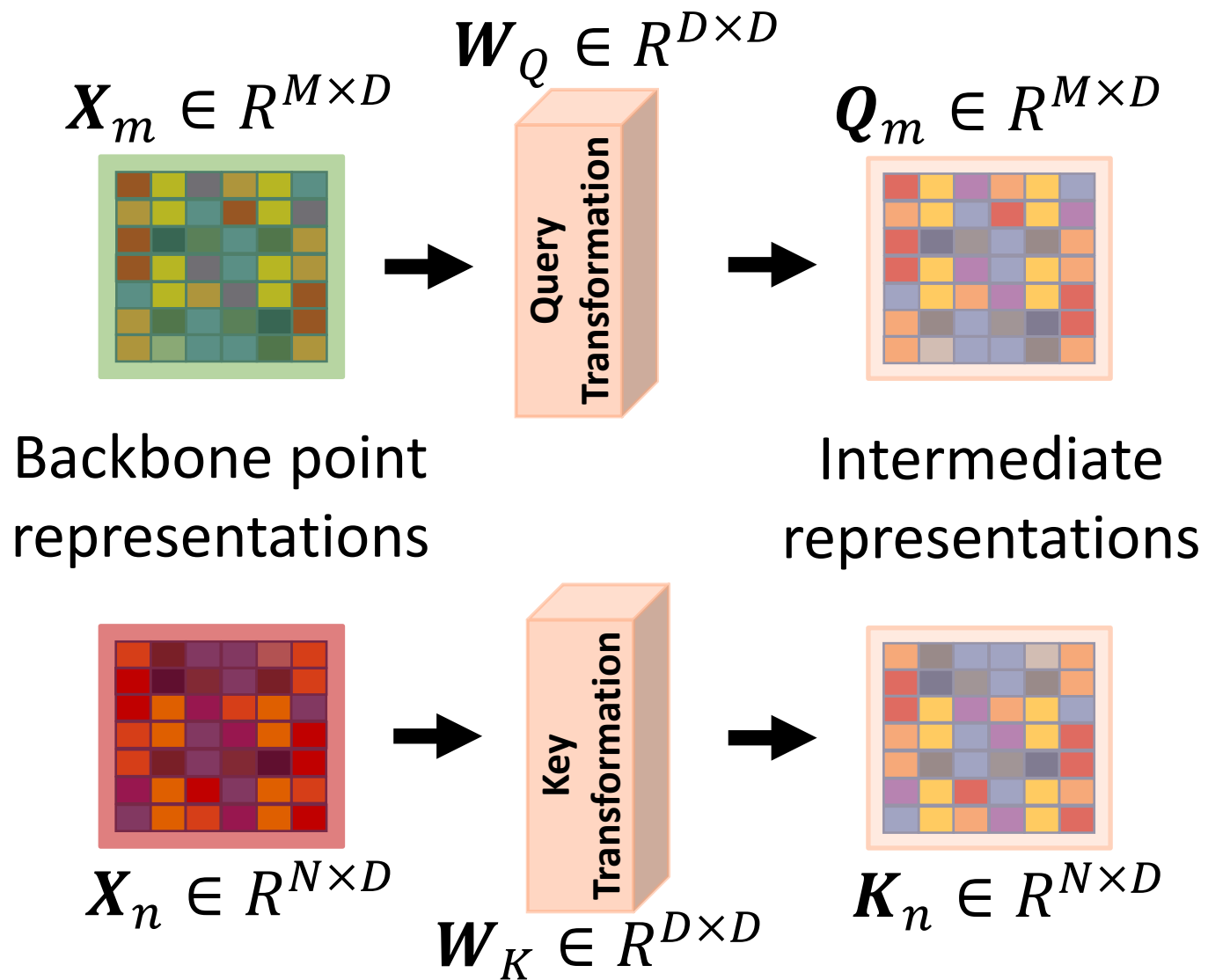


$$\mathbf{X}_n \in \mathbb{R}^{N \times D}$$

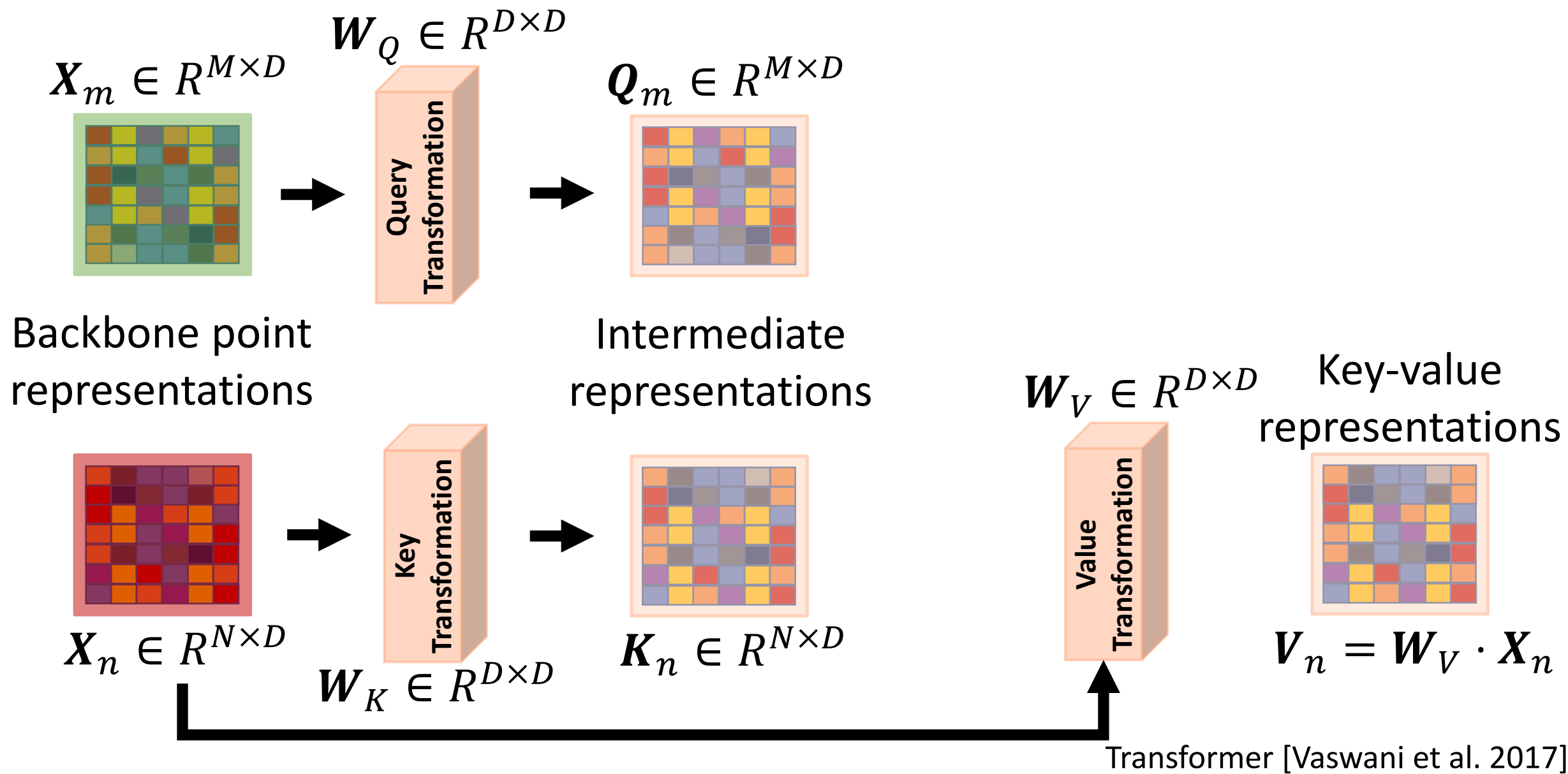
Cross-Shape Attention



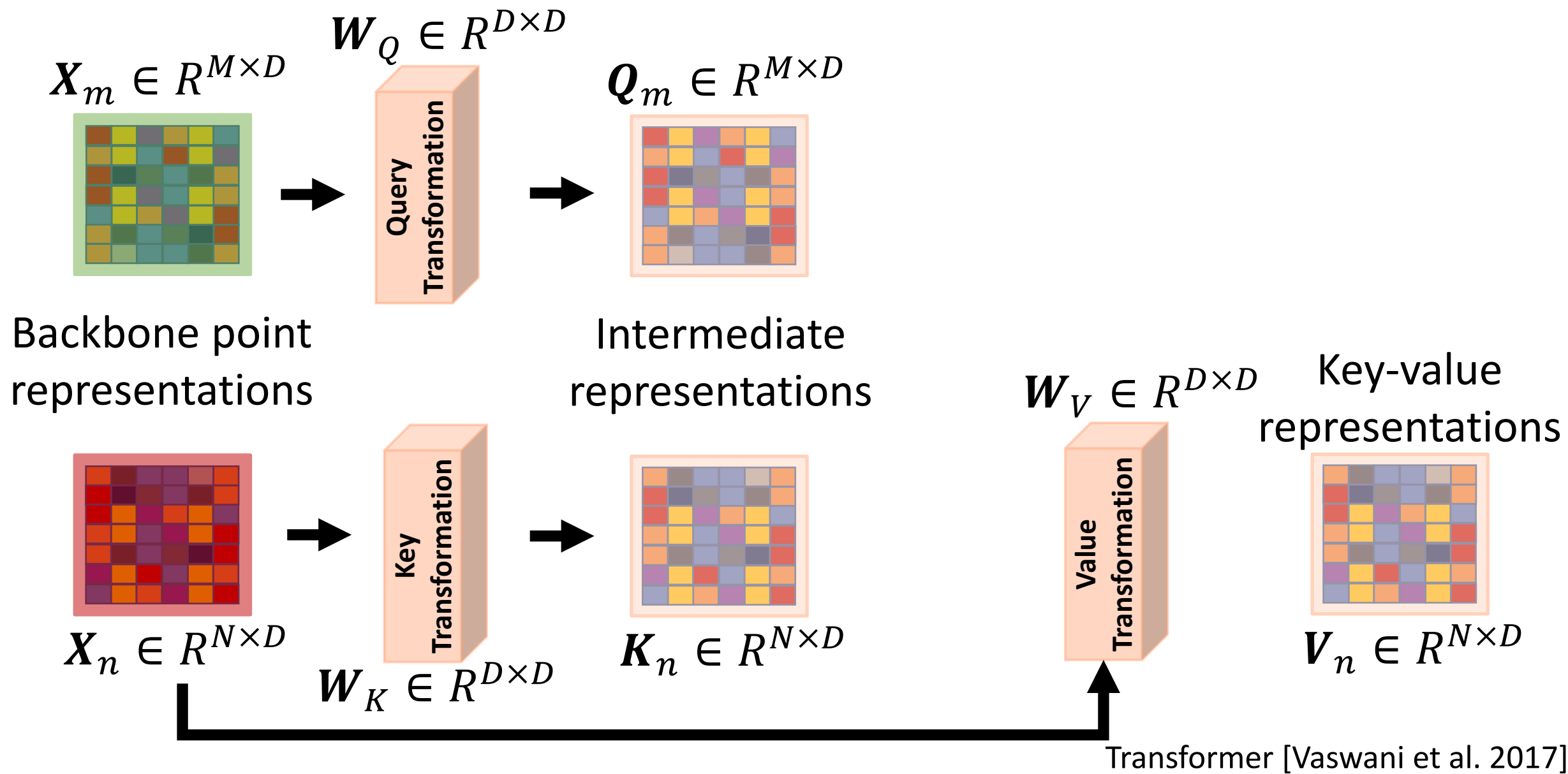
Cross-Shape Attention



Cross-Shape Attention



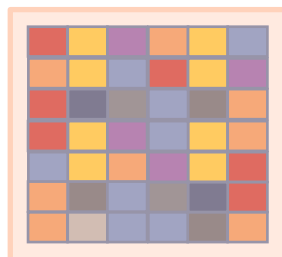
Cross-Shape Attention



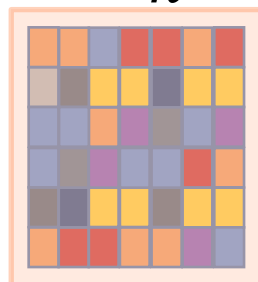
Cross-Shape Attention

Query representations Key representations

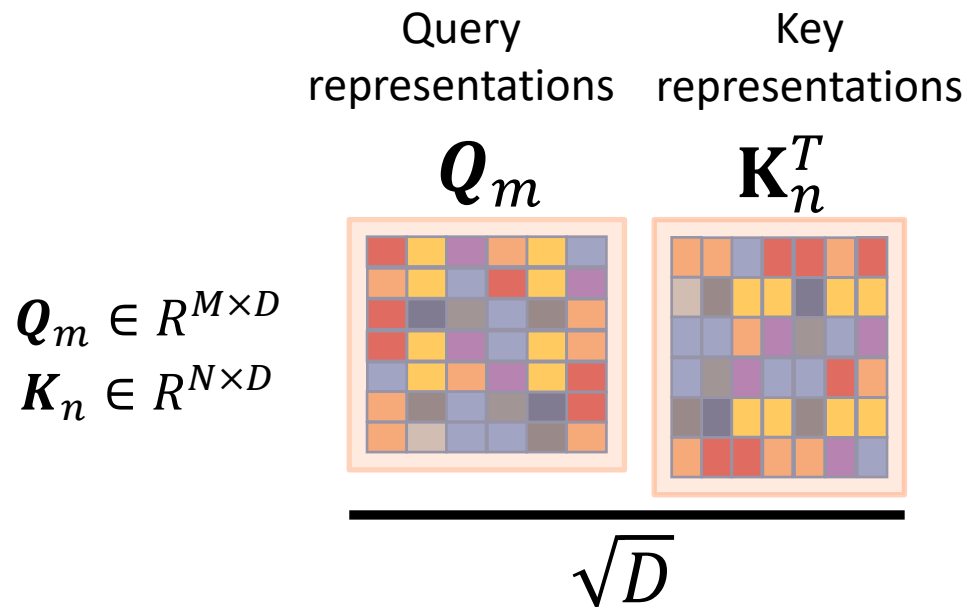
Q_m



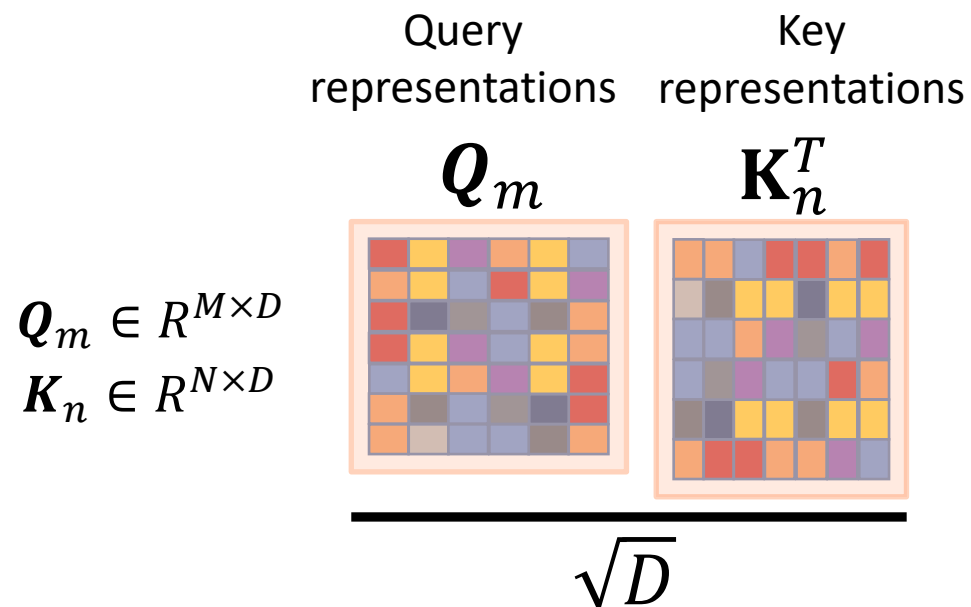
K_n^T



Cross-Shape Attention

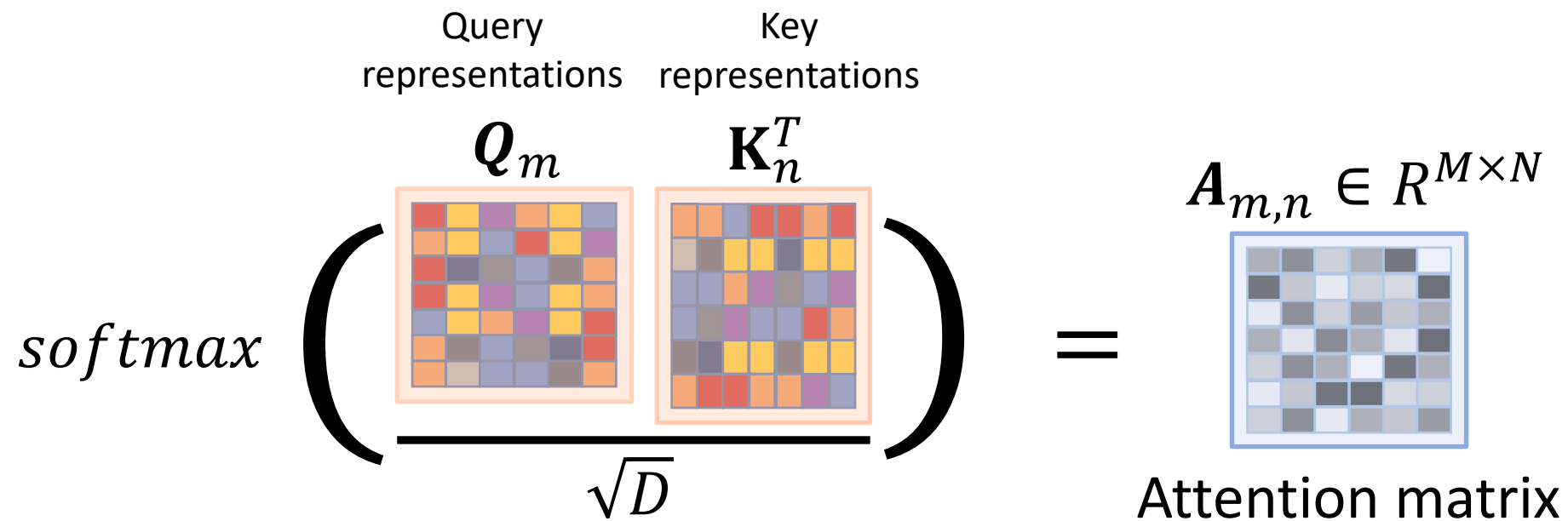


Cross-Shape Attention

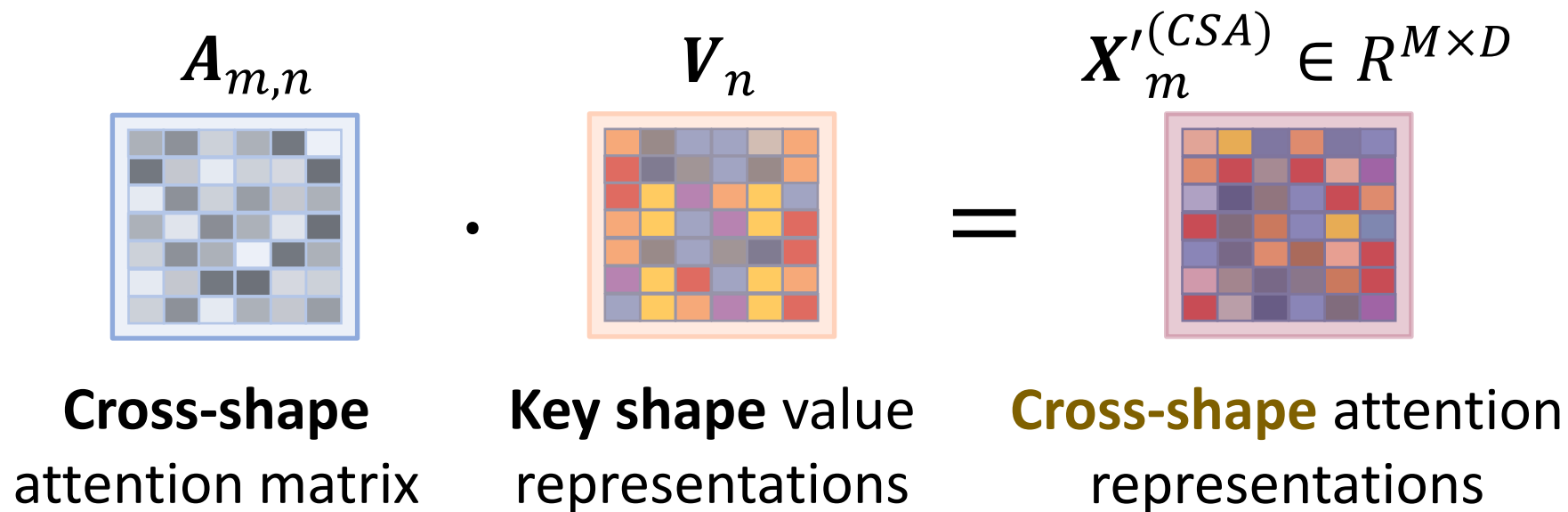


$$\text{Var} \left(\frac{\mathbf{Q}_{i,:} \mathbf{K}_{:,j}^T}{\sqrt{D}} \right) = 1,$$
$$\forall i = 1, \dots, M$$
$$\forall j = 1, \dots, N$$

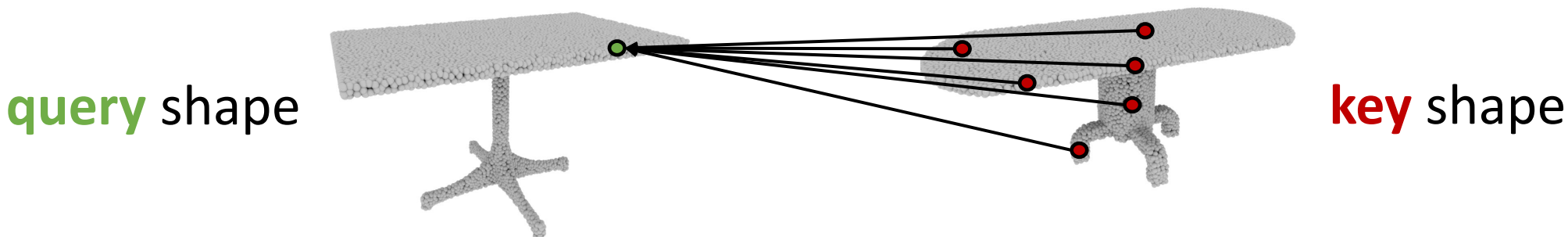
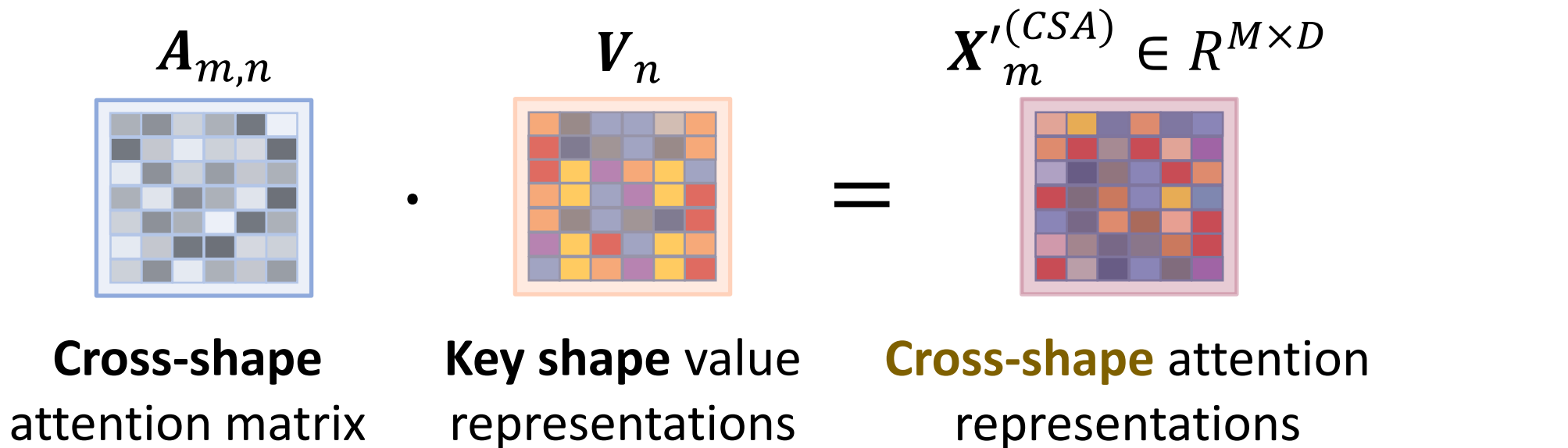
Cross-Shape Attention



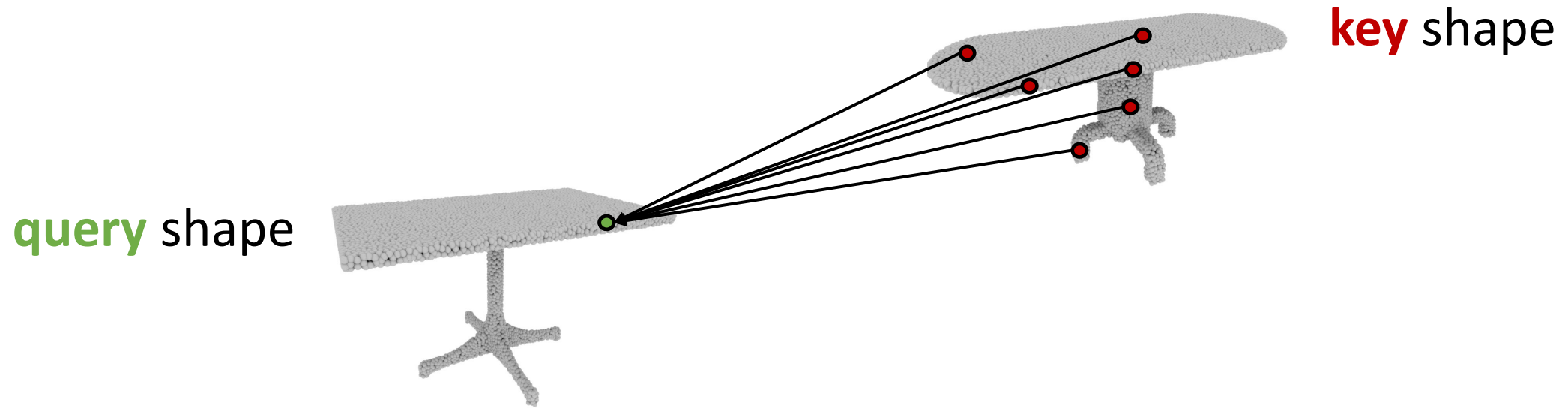
Cross-Shape Attention



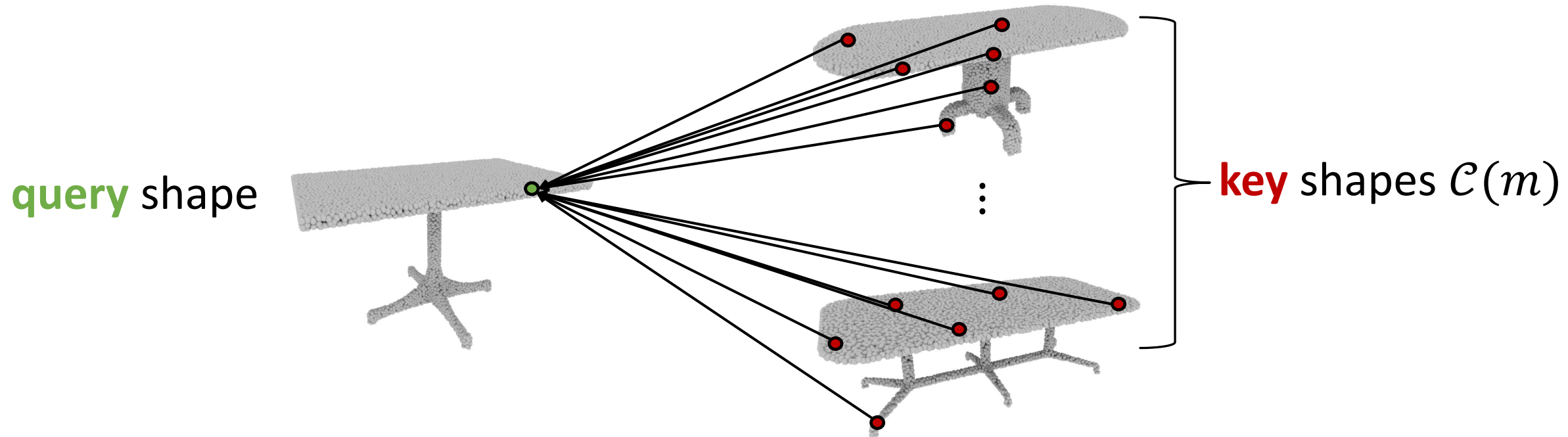
Cross-Shape Attention



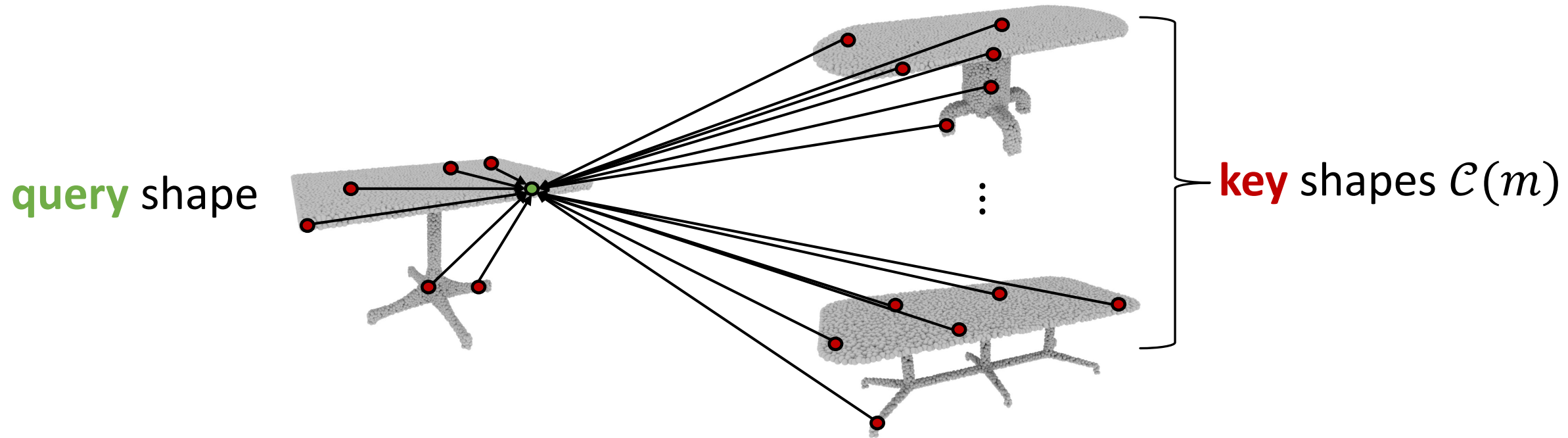
Cross-Shape Attention for multiple shapes



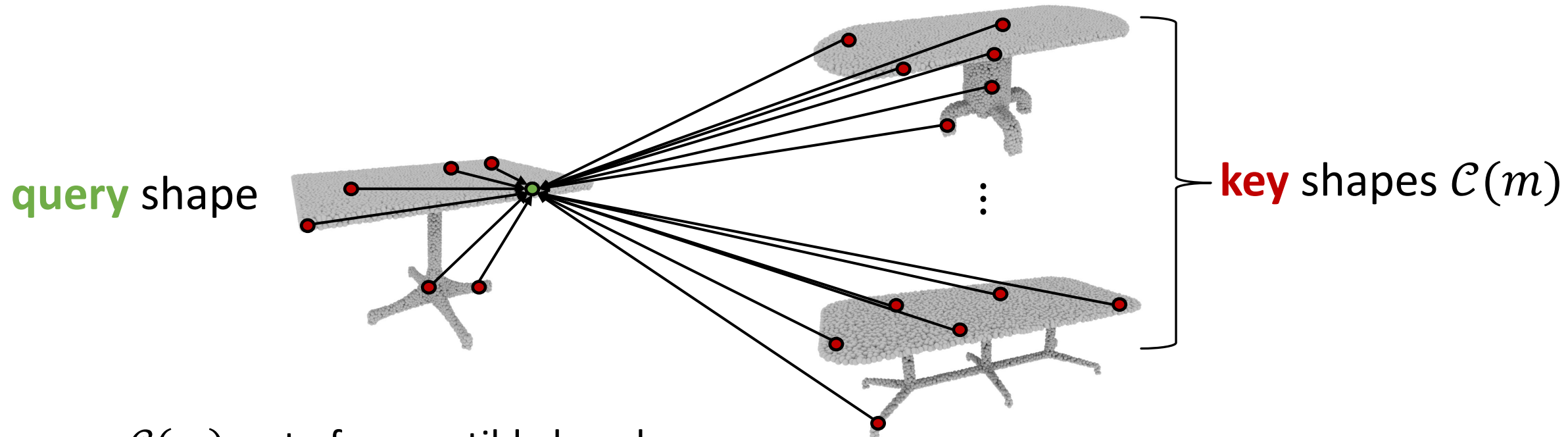
Cross-Shape Attention for multiple shapes



Cross-Shape Attention for multiple shapes



Cross-Shape Attention for multiple shapes



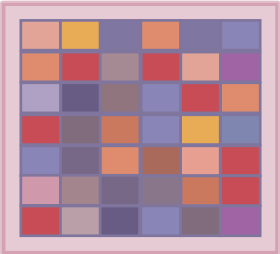
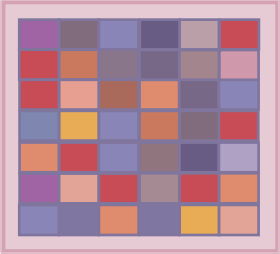
- $\mathcal{C}(m)$: set of compatible key shapes
- $c(m, n)$: compatibility function between query shape S_m and key shape S_n

**Cross-shape
attention output**

$$\mathbf{X}'_m = \sum_{n \in \{\mathcal{C}(m), m\}} c(m, n) \mathbf{A}_{m,n} \mathbf{V}_n$$

Compatibility function

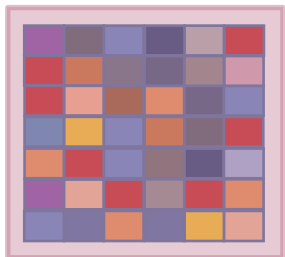
$$\mathbf{X}'_m^{(SSA)} \in \mathbb{R}^{M \times D}$$



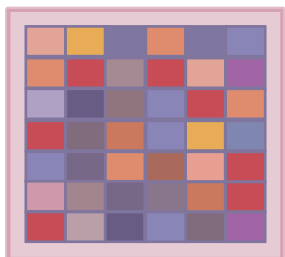
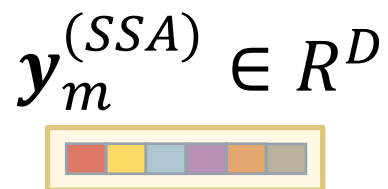
$$\mathbf{X}'_n^{(SSA)} \in \mathbb{R}^{N \times D}$$

Compatibility function

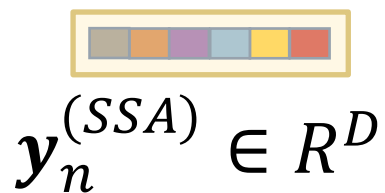
$$\mathbf{X}'_m^{(SSA)} \in R^{M \times D}$$



$$\xrightarrow{\text{avg}_i \mathbf{X}'_{m,i}^{(SSA)}} \mathbf{y}_m^{(SSA)} \in R^D$$

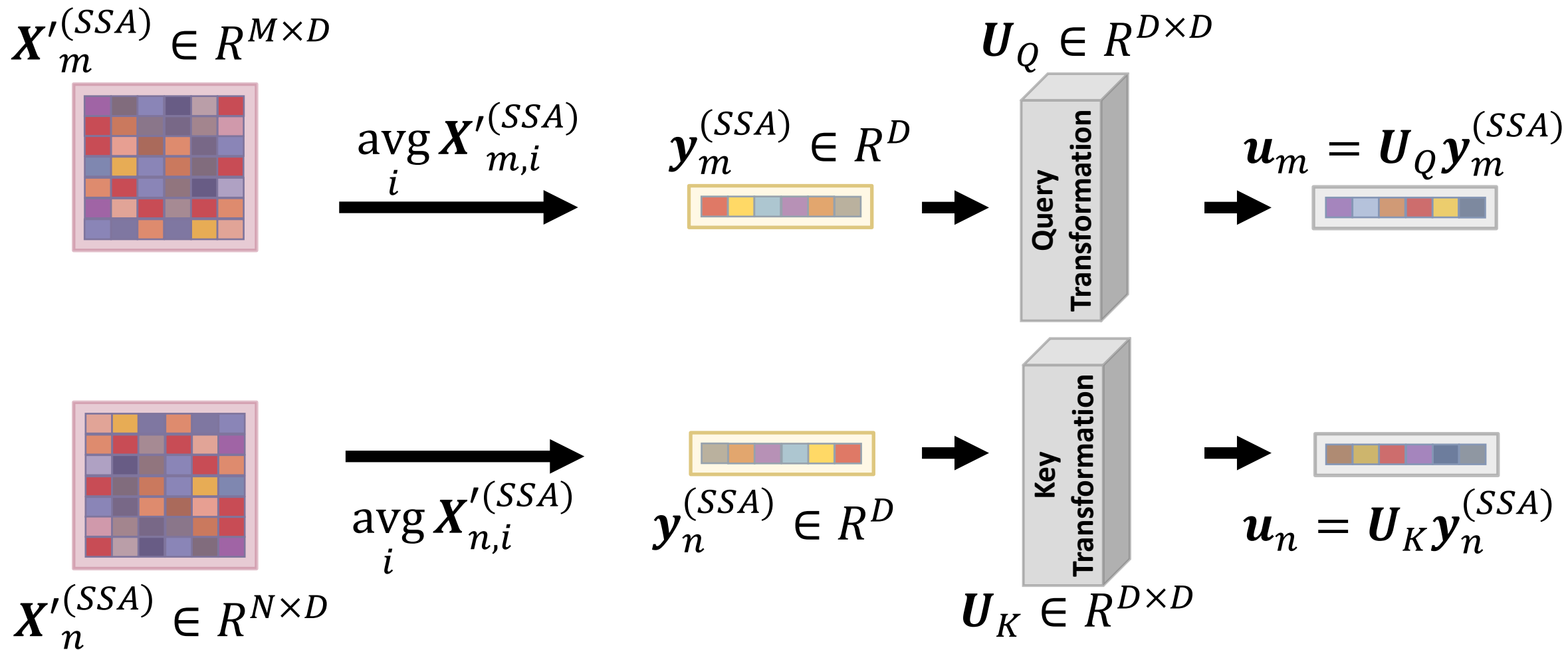


$$\xrightarrow{\text{avg}_i \mathbf{X}'_{n,i}^{(SSA)}} \mathbf{y}_n^{(SSA)} \in R^D$$



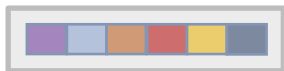
$$\mathbf{X}'_n^{(SSA)} \in R^{N \times D}$$

Compatibility function



Compatibility function

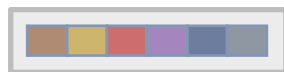
$$\mathbf{u}_m \in \mathbb{R}^D$$



$$\hat{\mathbf{u}}_m = \mathbf{u}_m / \|\mathbf{u}_m\|$$

Cosine similarity

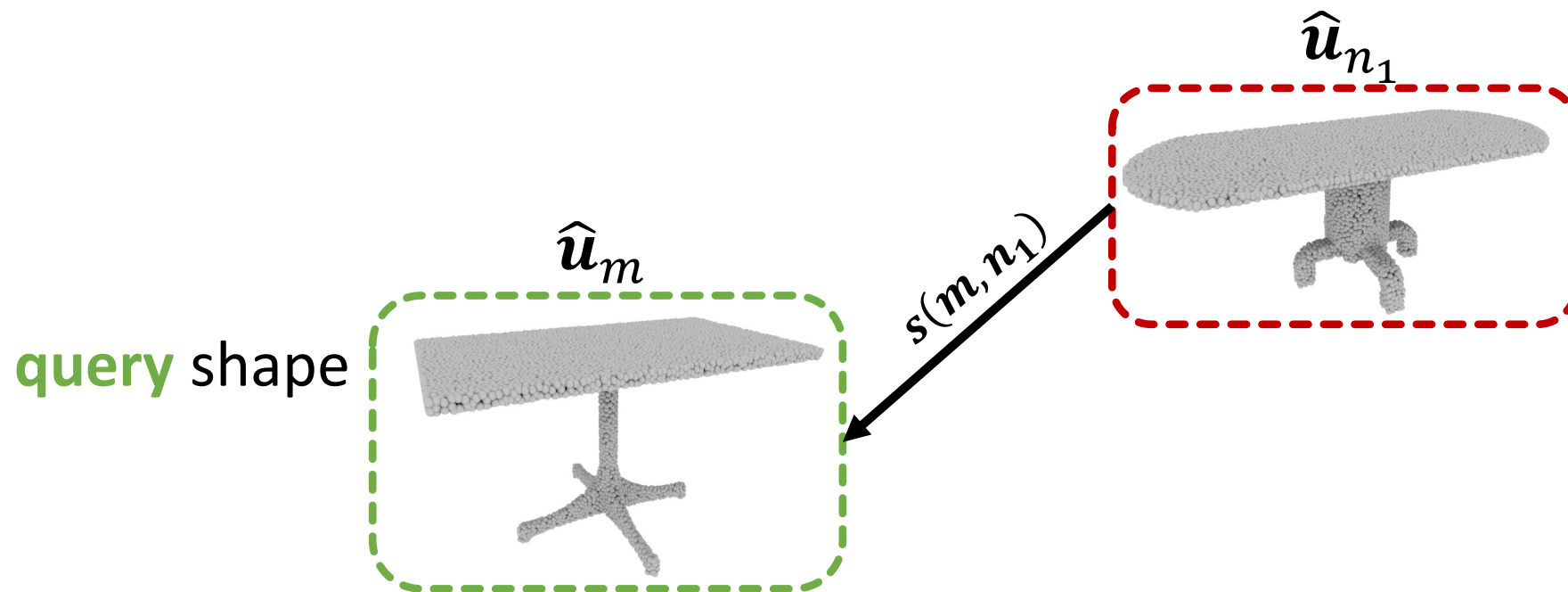
$$s(m, n) = \hat{\mathbf{u}}_m \cdot \hat{\mathbf{u}}_n$$



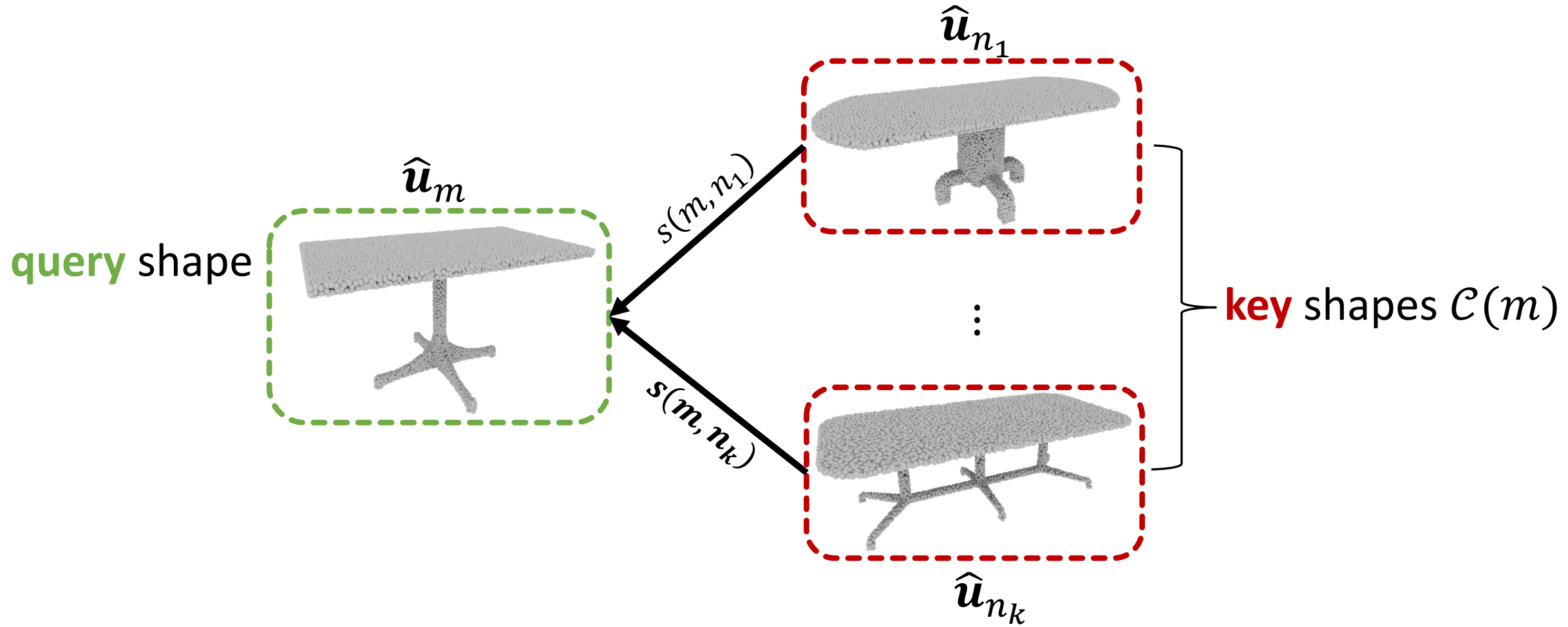
$$\mathbf{u}_n \in \mathbb{R}^D$$

$$\hat{\mathbf{u}}_n = \mathbf{u}_n / \|\mathbf{u}_n\|$$

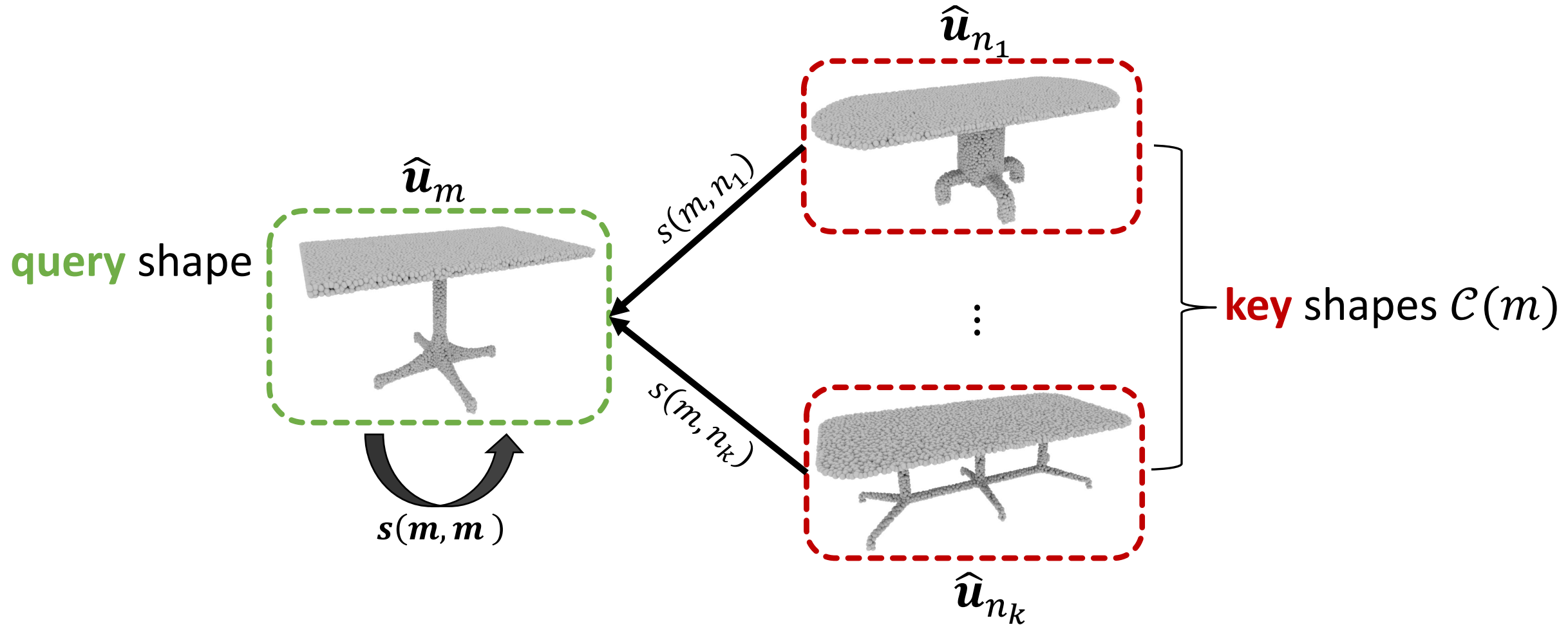
Compatibility function



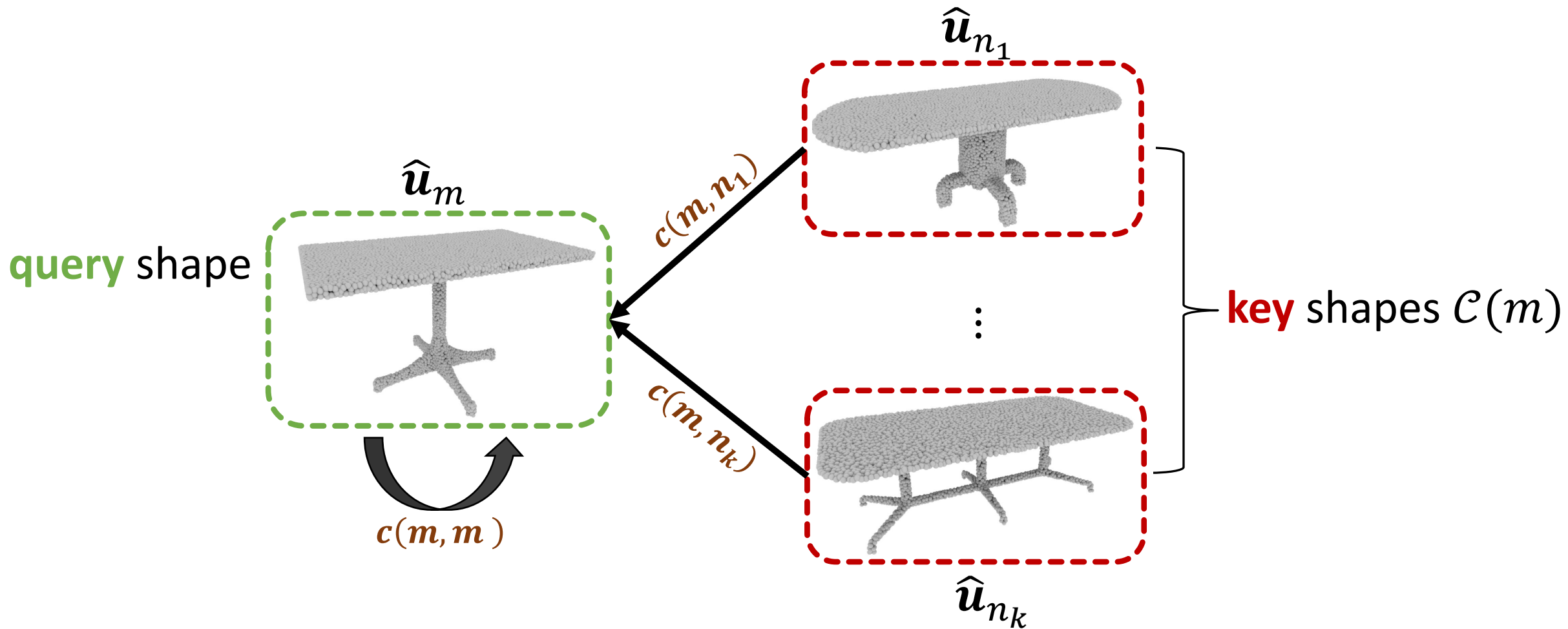
Compatibility function



Compatibility function

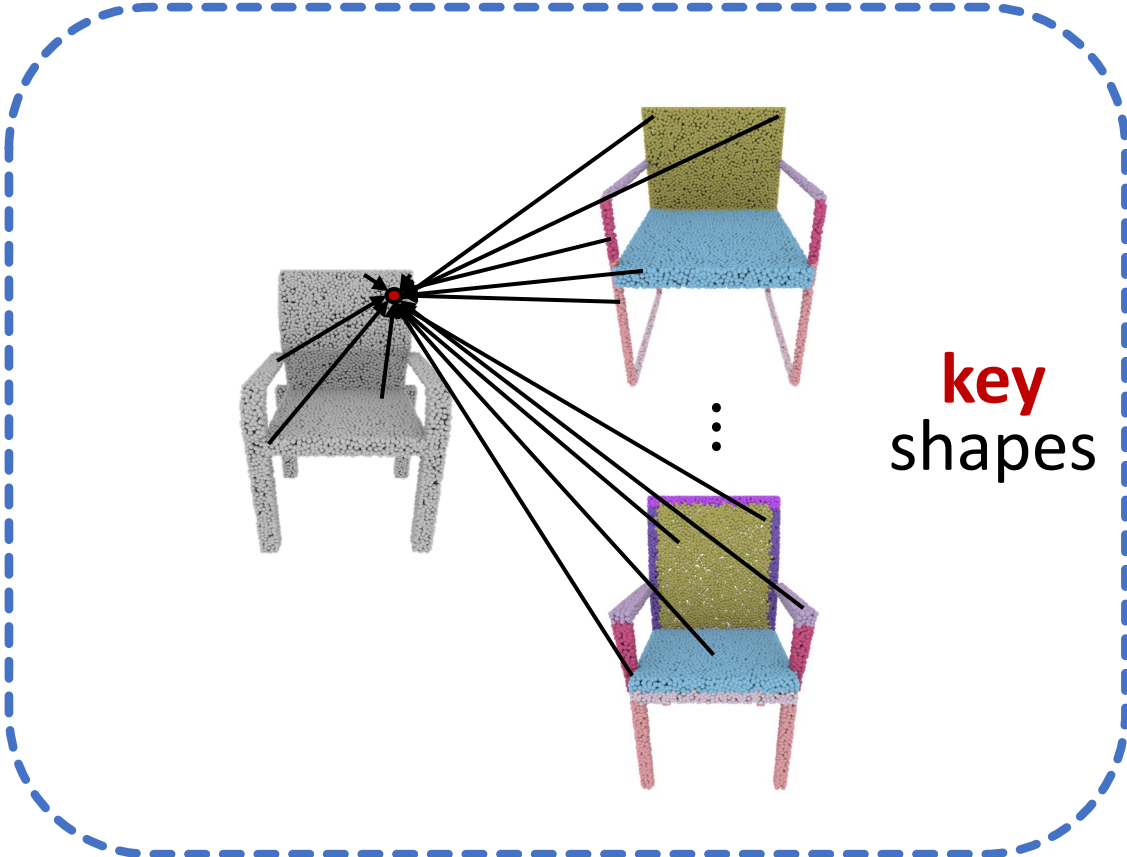


Compatibility function



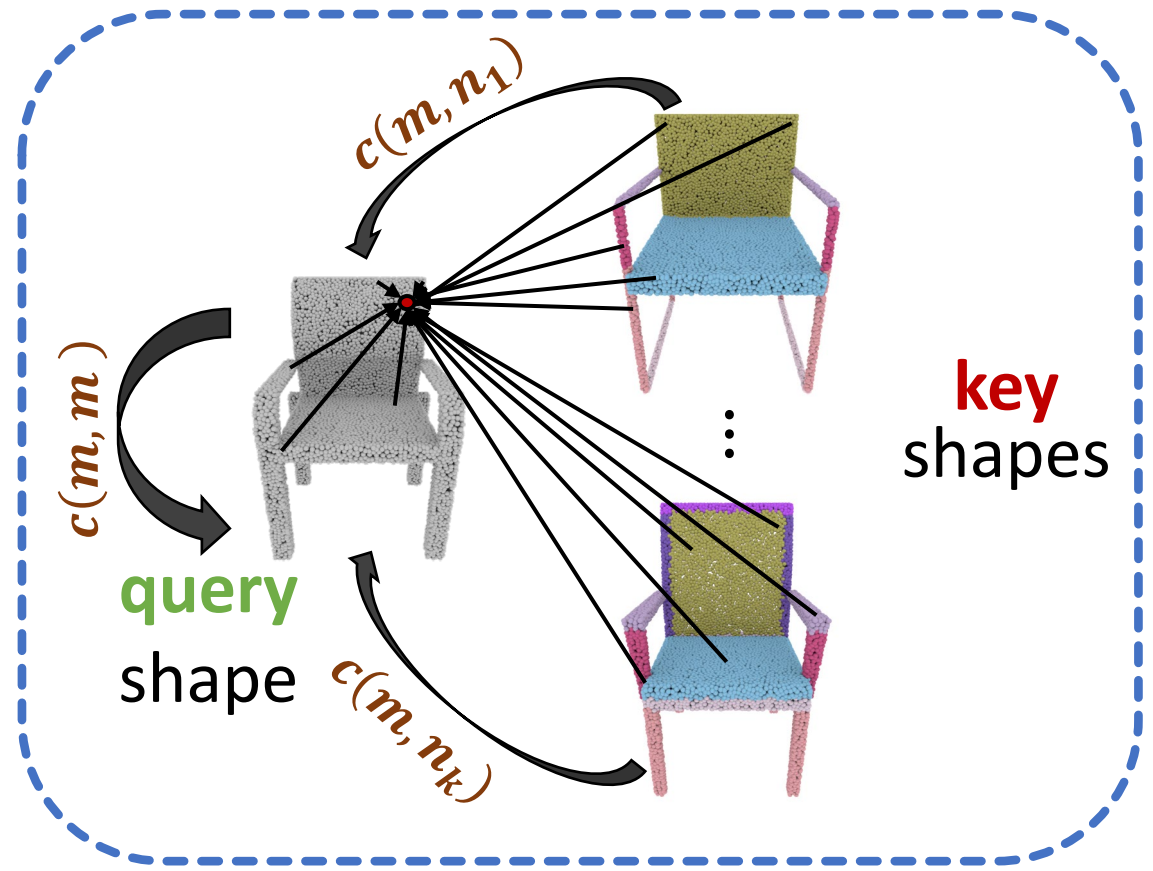
compatibility $c(m, n) = \frac{e^{s(m, n)}}{\sum_{n \in \{\mathcal{C}(m), m\}} e^{s(m, n)}}$

Cross-Shape Attention for multiple shapes



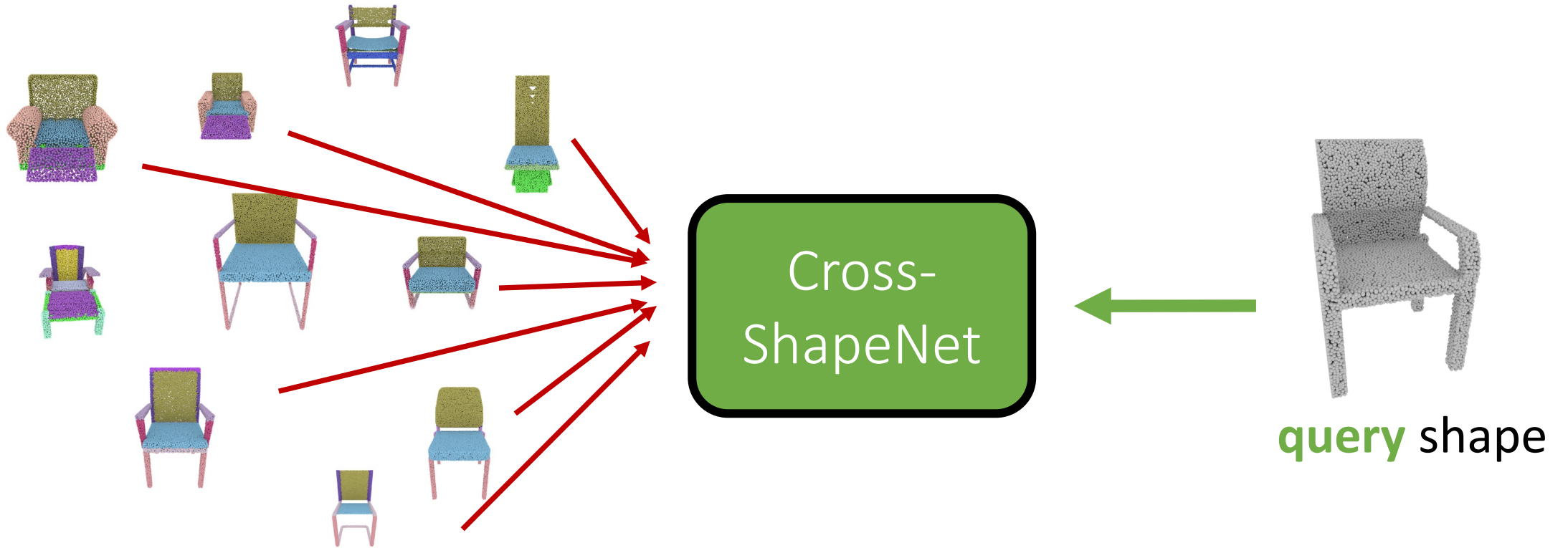
Cross-shape
attention

Cross-Shape Attention for multiple shapes



Cross-shape attention

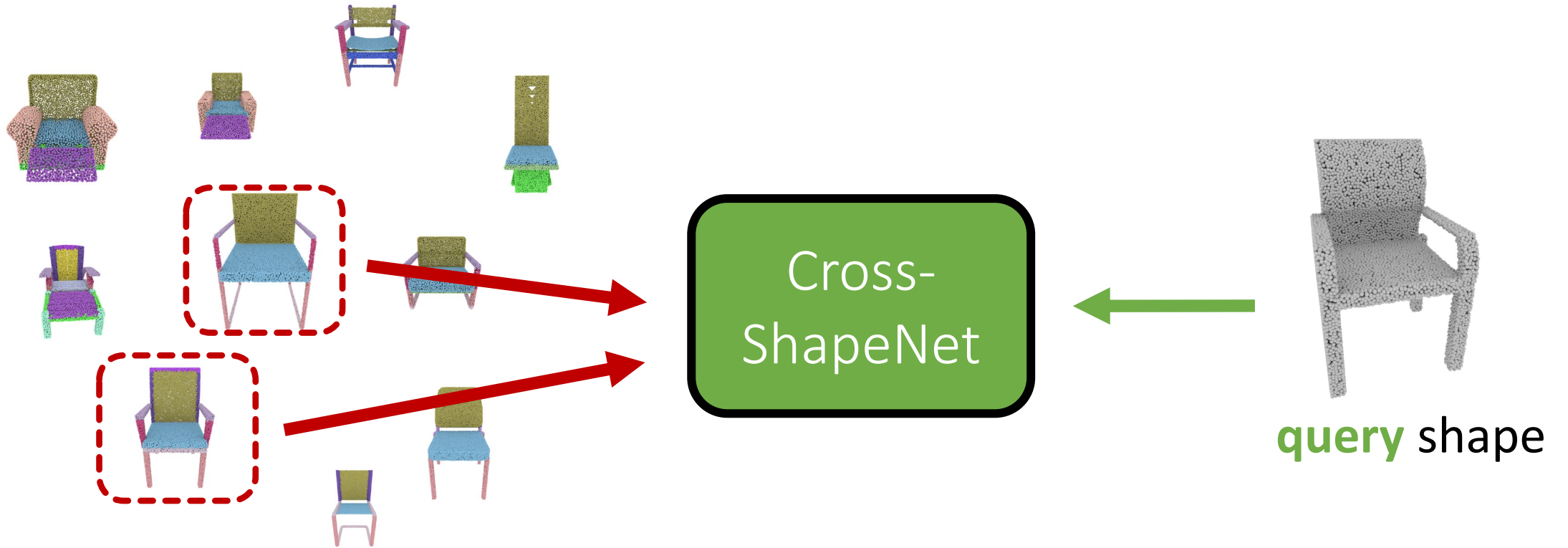
Retrieve compatible shapes



Shape Collection

query shape

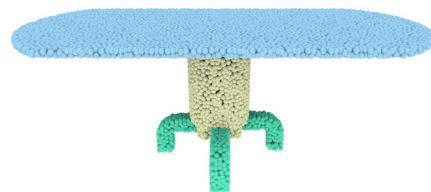
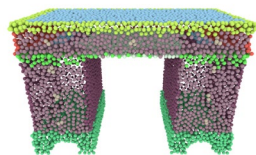
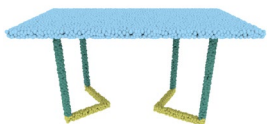
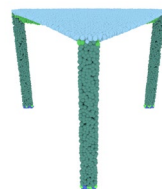
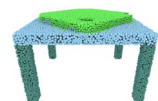
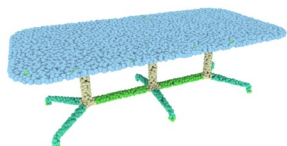
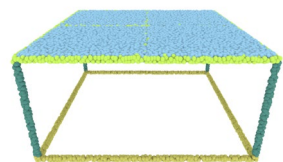
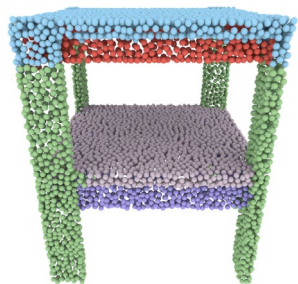
Retrieve compatible shapes



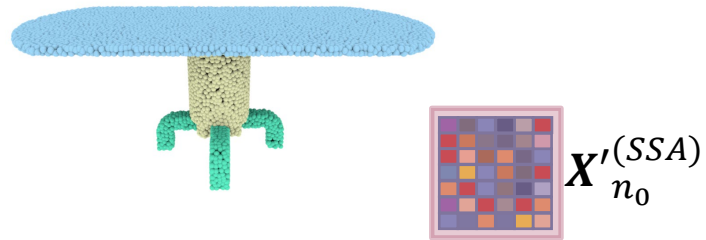
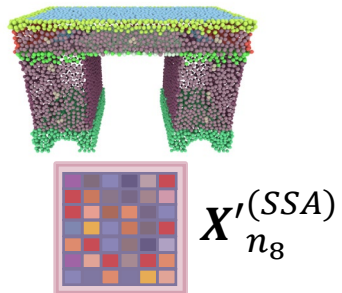
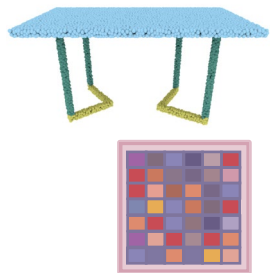
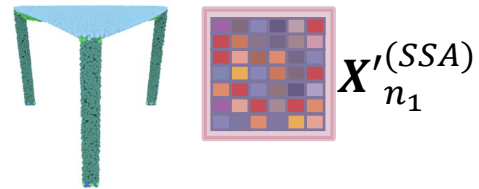
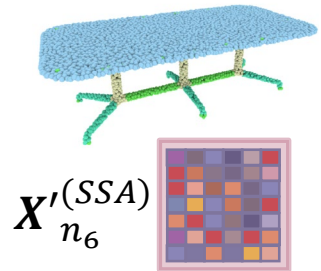
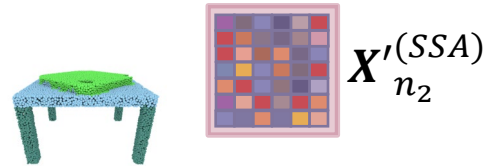
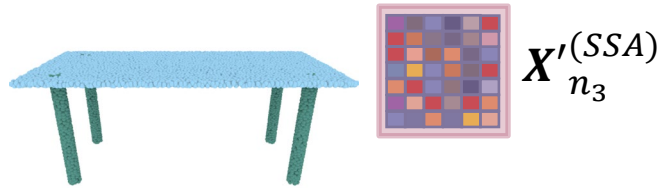
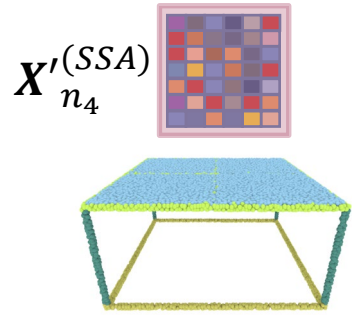
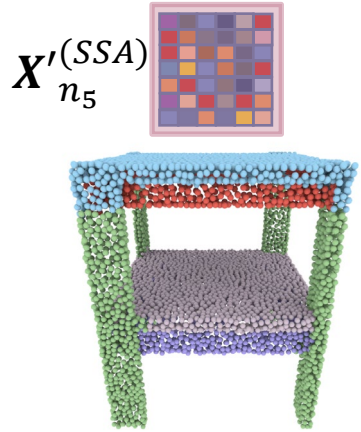
Shape Collection

query shape

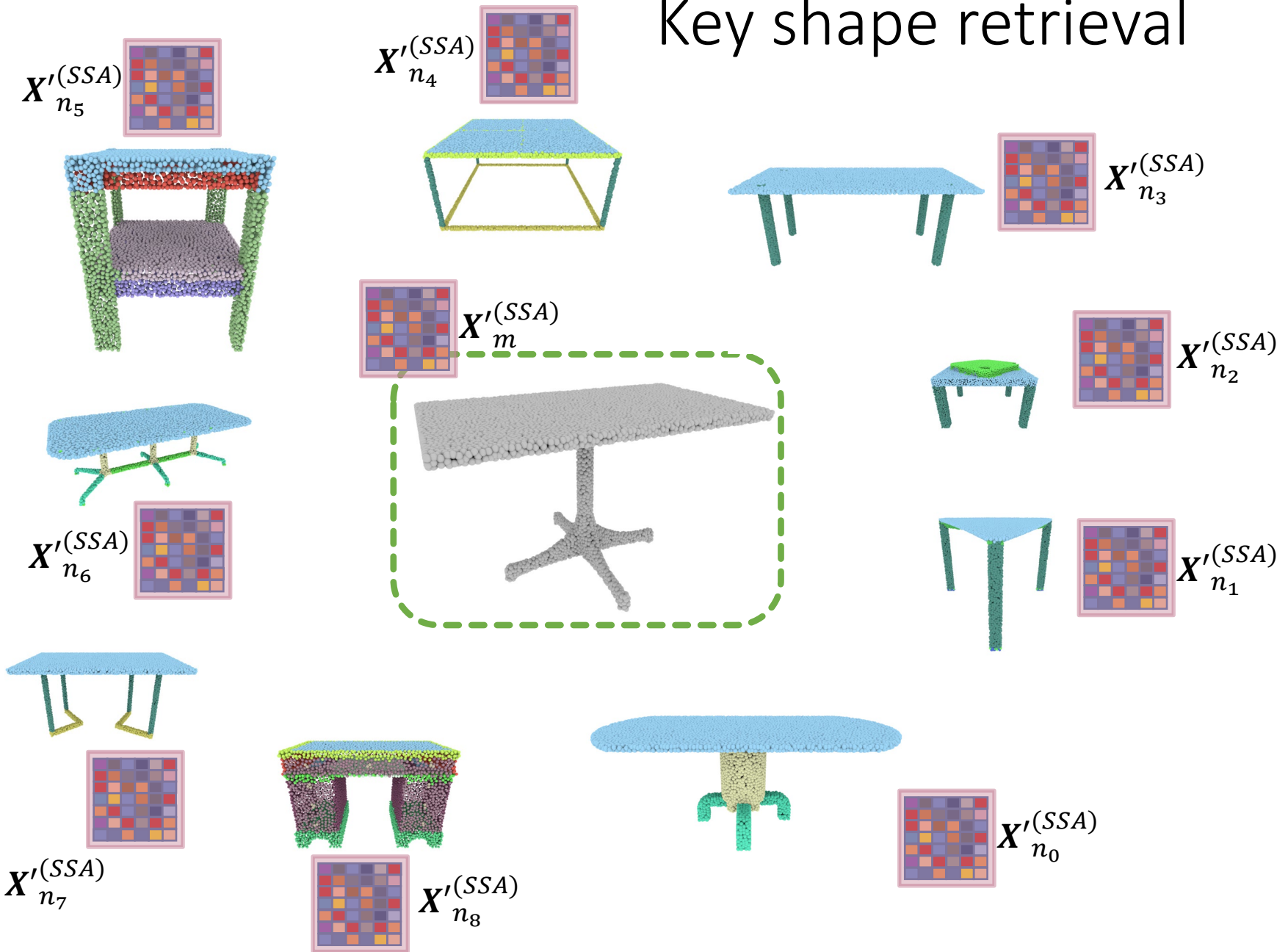
Key shape retrieval



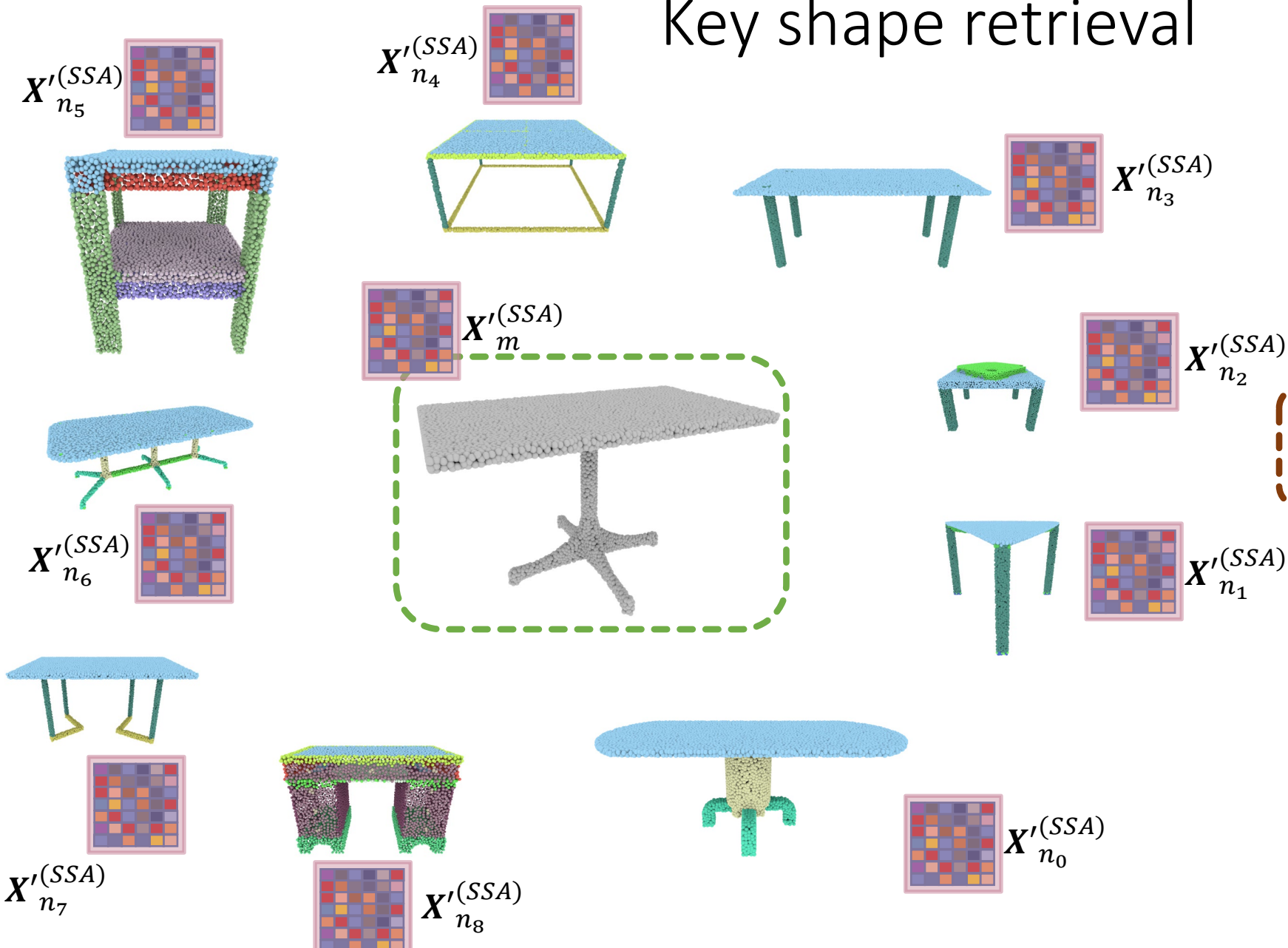
Key shape retrieval



Key shape retrieval



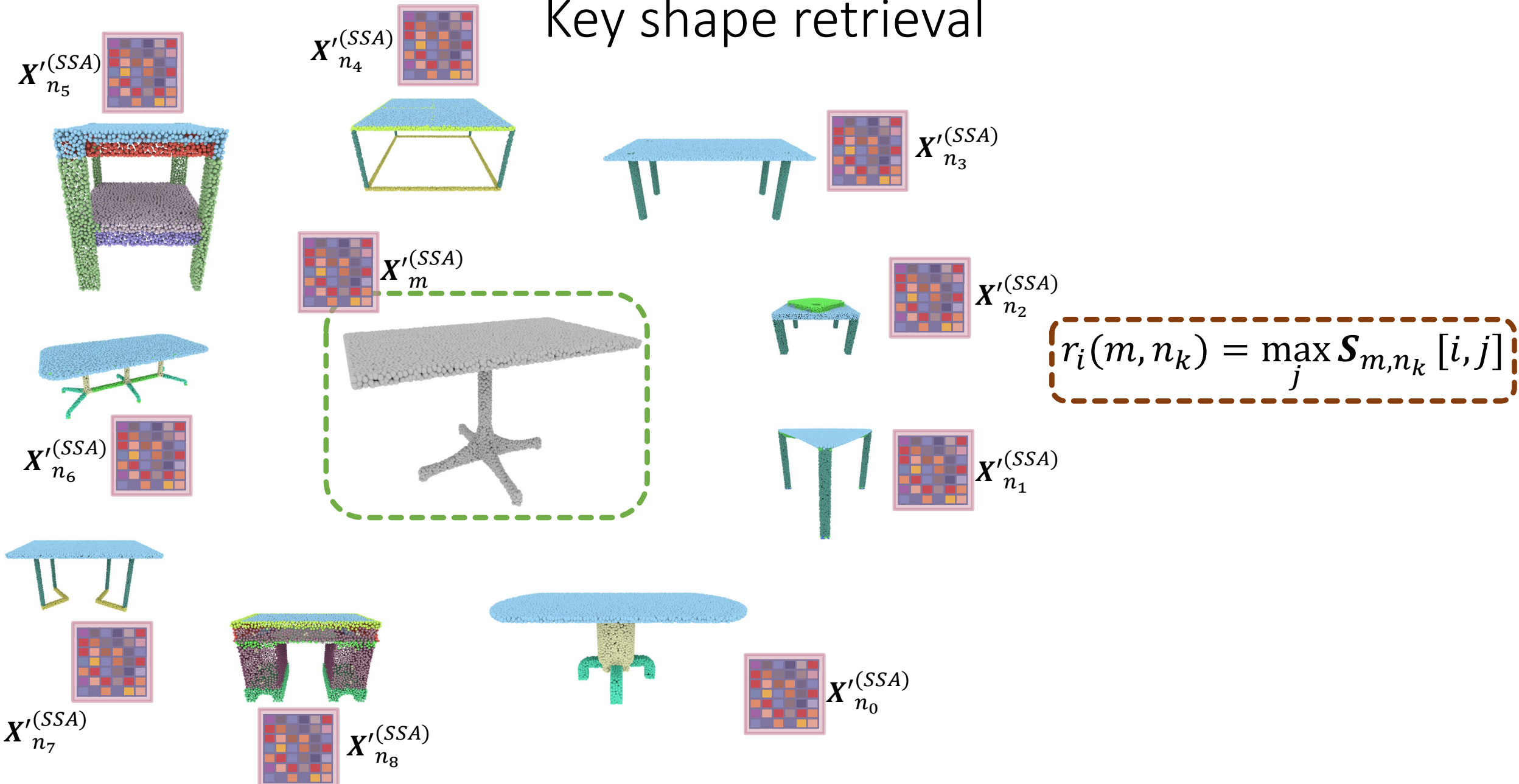
Key shape retrieval



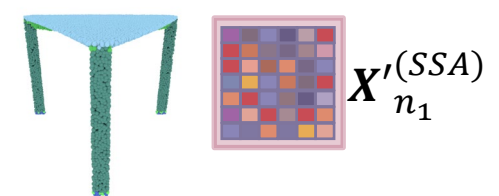
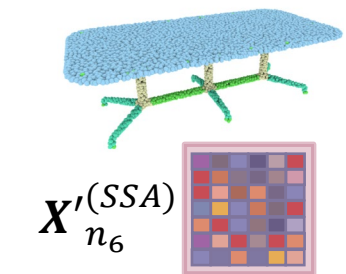
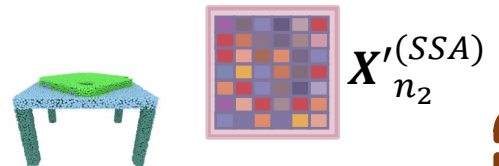
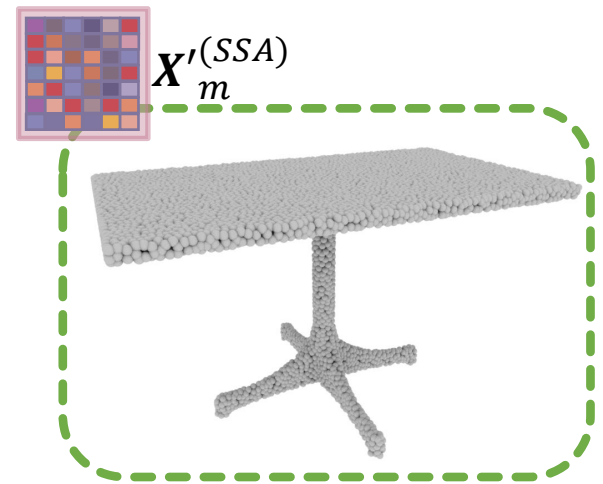
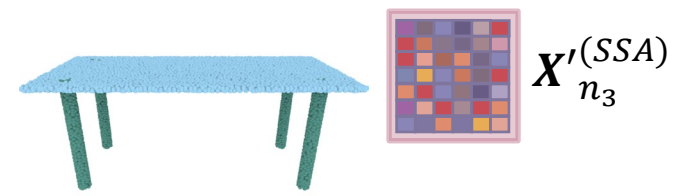
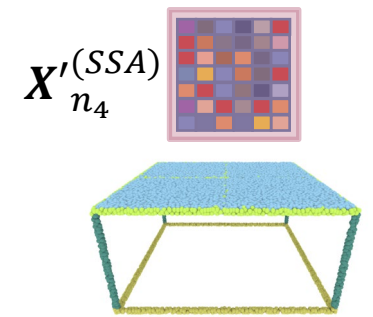
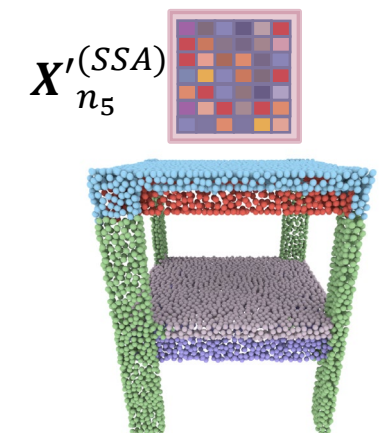
Cosine similarity

$$S_{m,n_k} = X'_m^{(SSA)} \cdot \left(X'_{n_k}^{(SSA)} \right)^T$$

Key shape retrieval

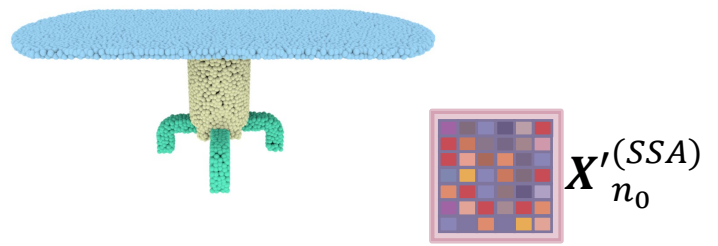
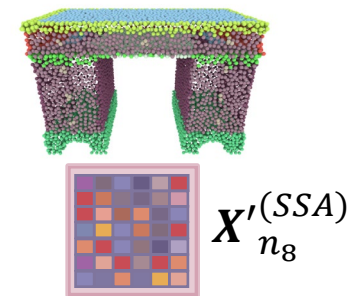
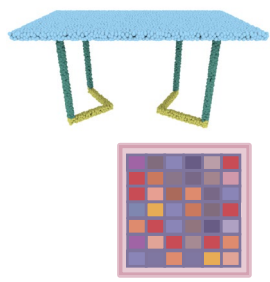


Key shape retrieval

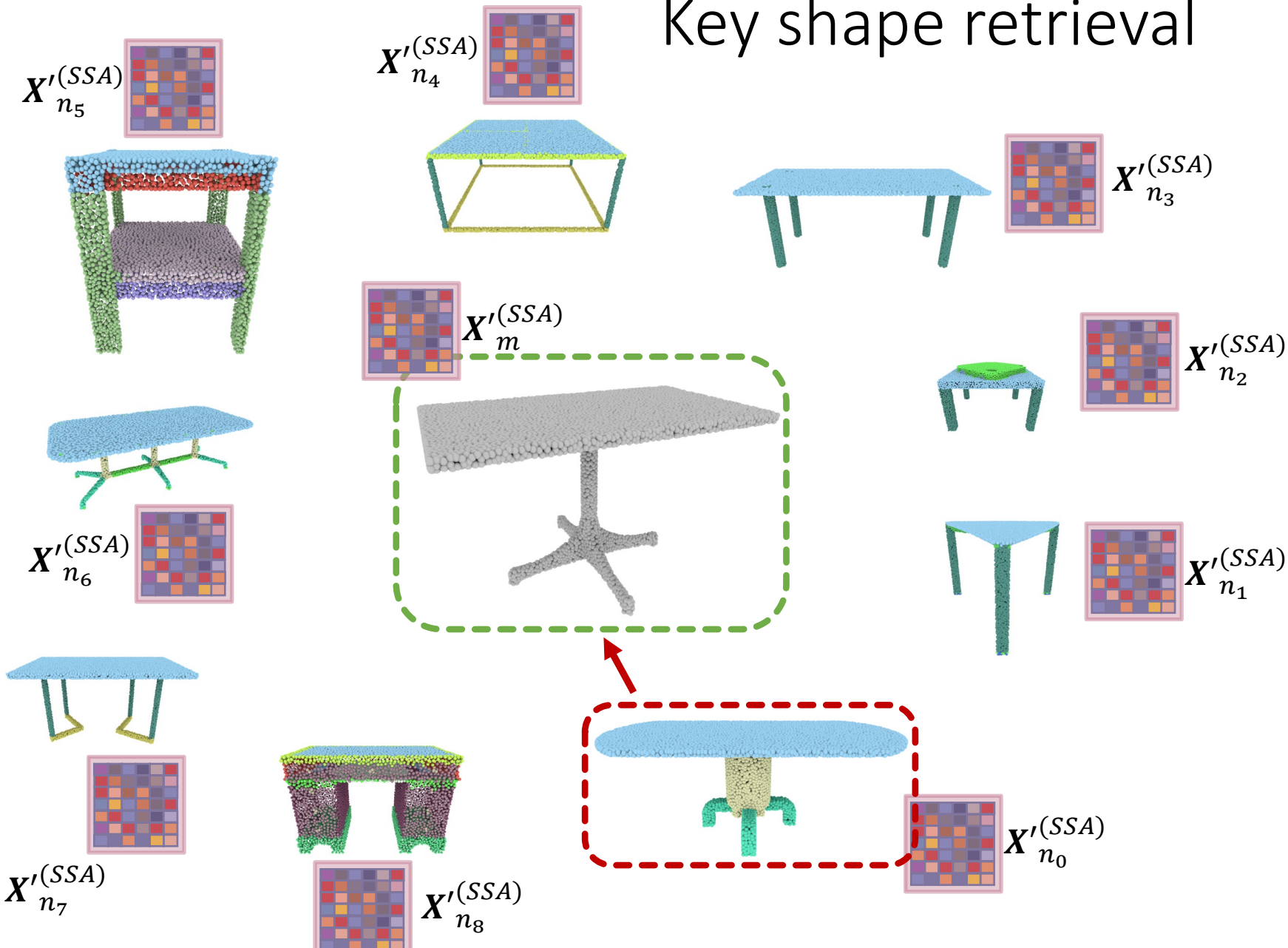


retrieval measure

$$r(m, n_k) = \text{avg}_i r_i(m, n_k)$$



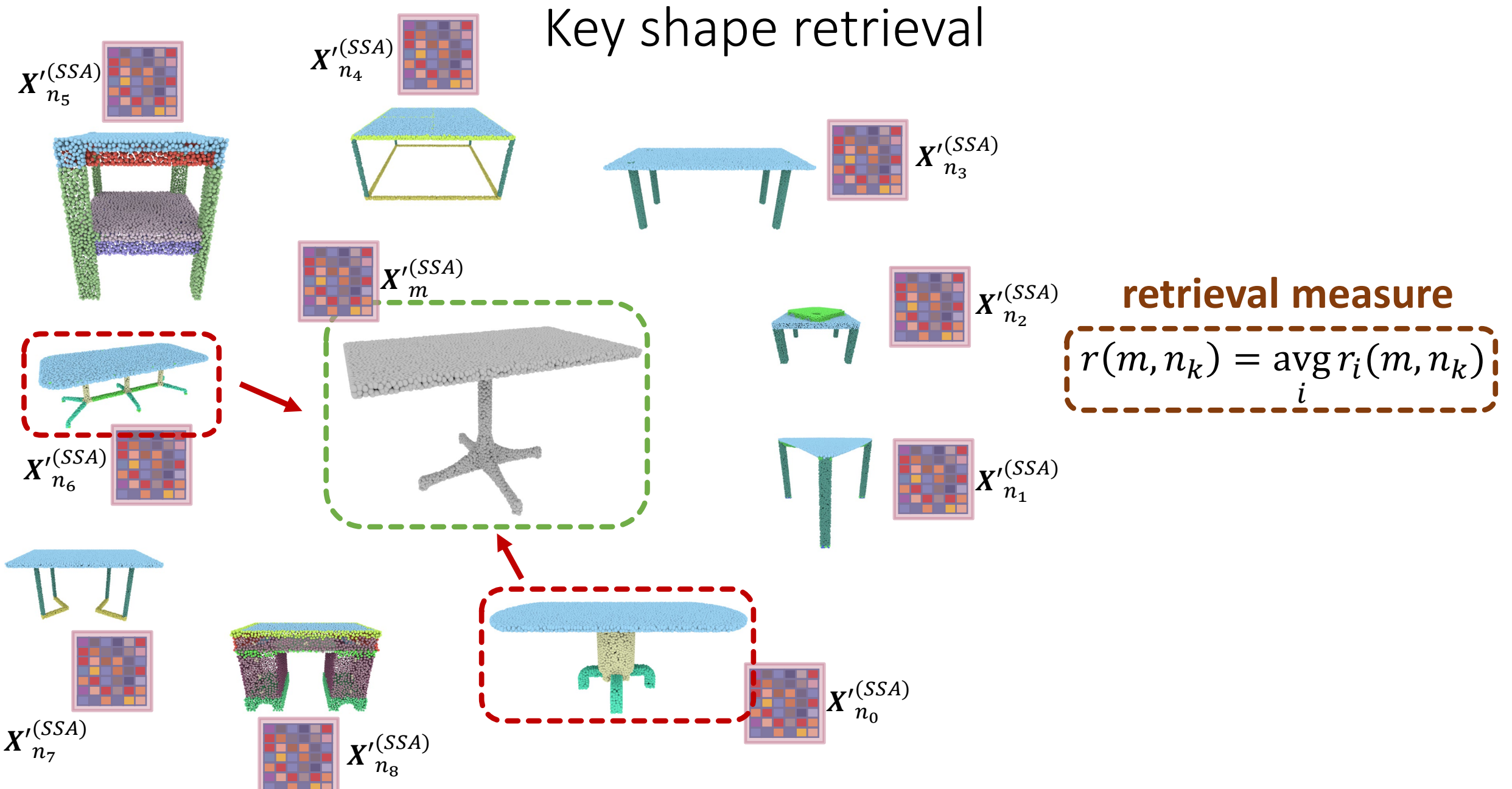
Key shape retrieval



retrieval measure

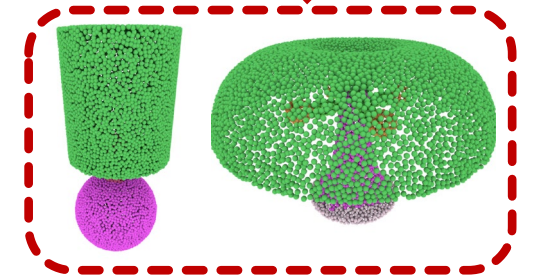
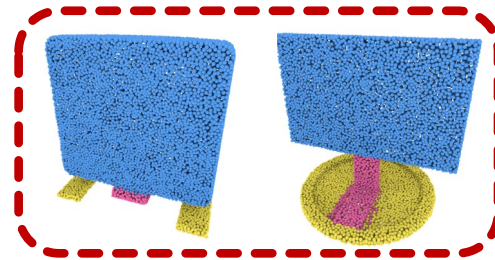
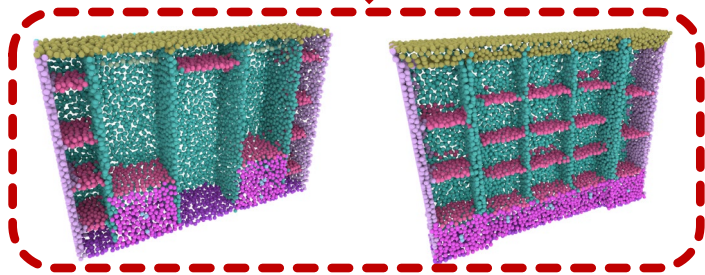
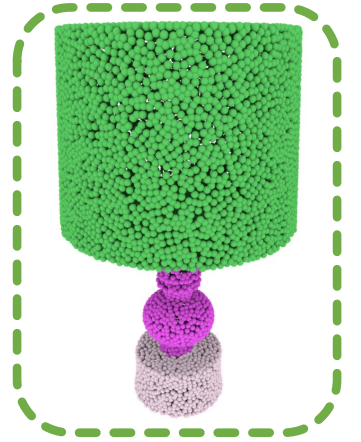
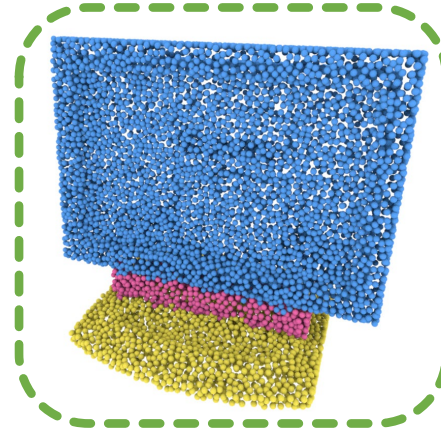
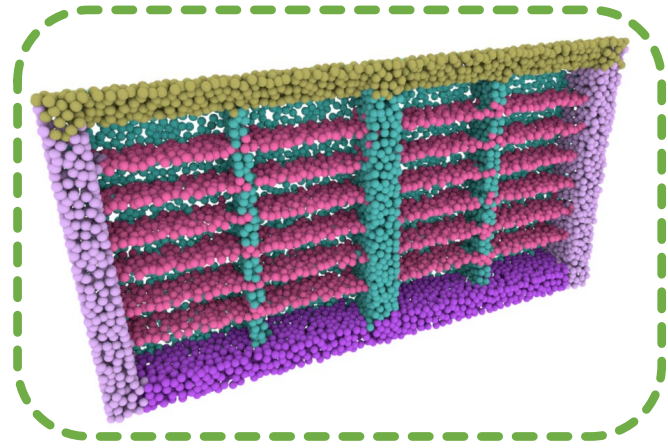
$$r(m, n_k) = \text{avg}_i r_i(m, n_k)$$

Key shape retrieval



Key shape retrieval: Examples

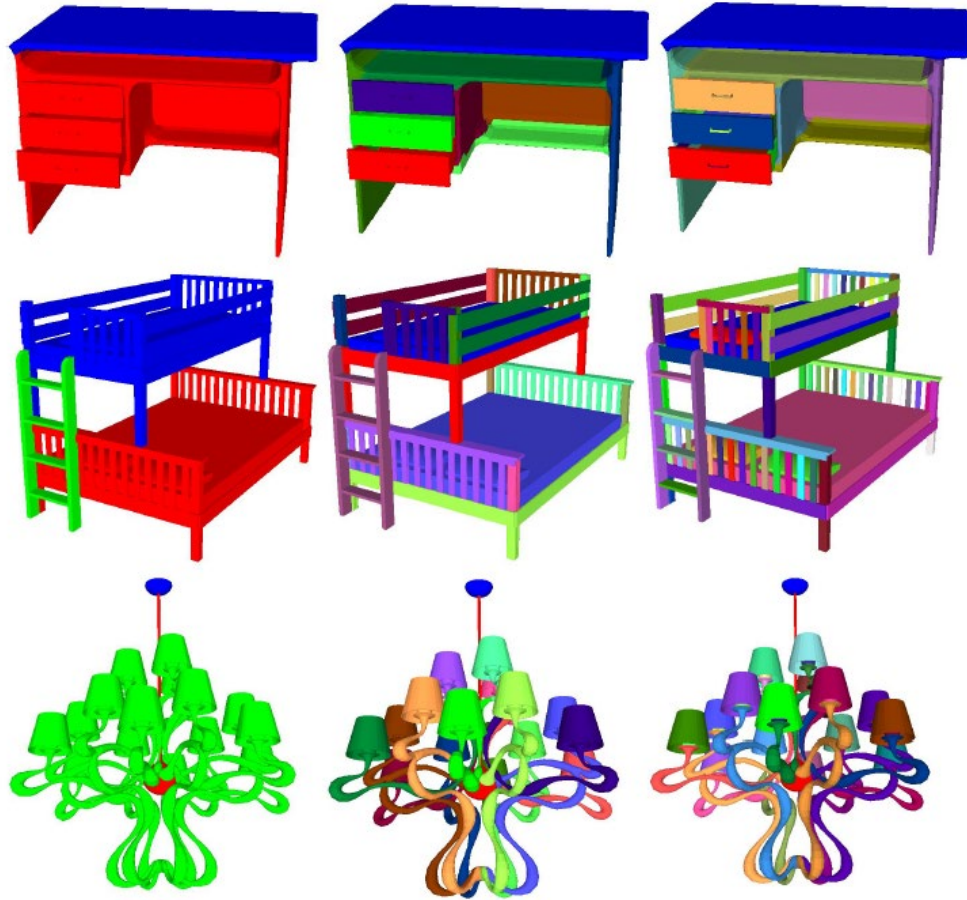
query shapes



key shapes

PartNet dataset

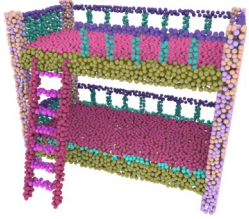
Coarse \longrightarrow Fine-grained



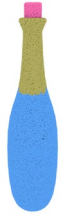
[Mo et al. 2019]

PartNet dataset

Bed



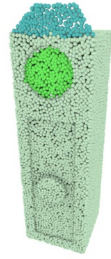
Bottle



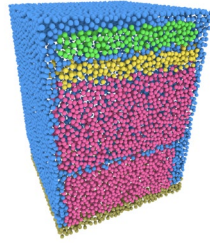
Chair



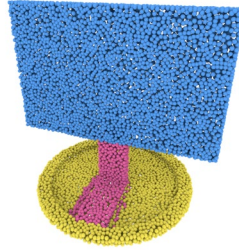
Clock



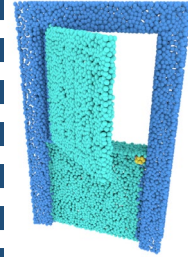
Dishwasher



Display



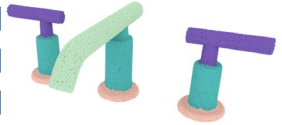
Door



Earphone



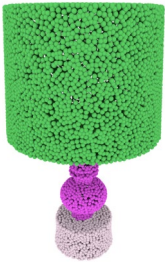
Faucet



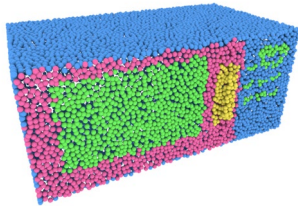
Knife



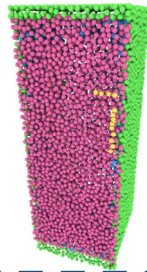
Lamp



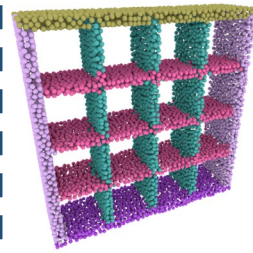
Microwave



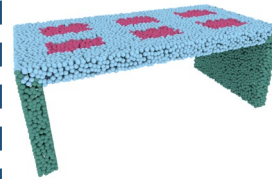
Refrigerator



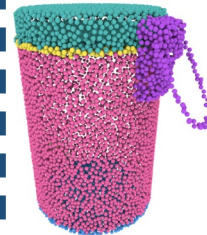
Storage Furn.



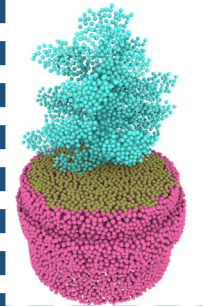
Table



Trashcan



Vase



Examples of shape collections

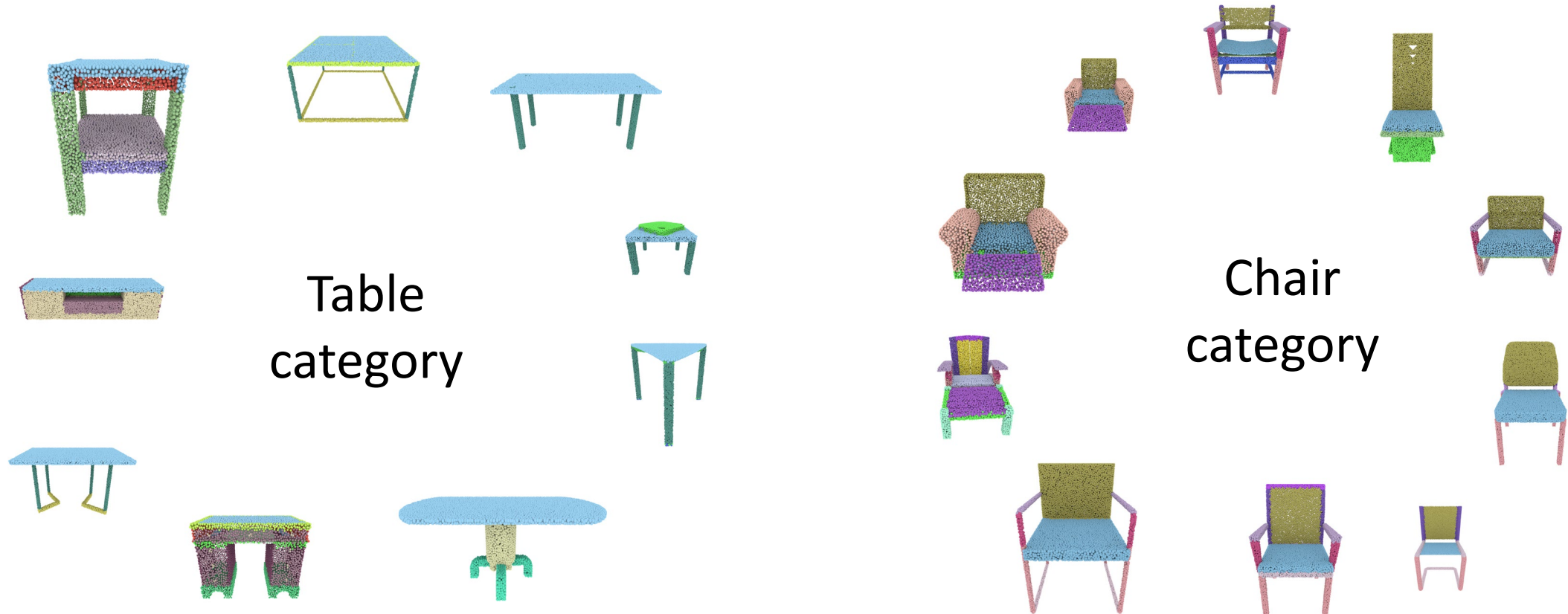


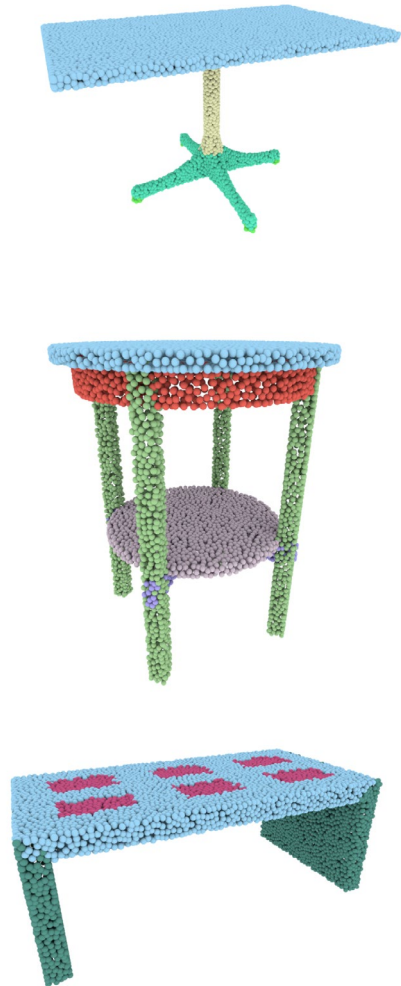
Table
category

Chair
category

5,707 training shapes

4,489 training shapes

Training details: Loss



training
data

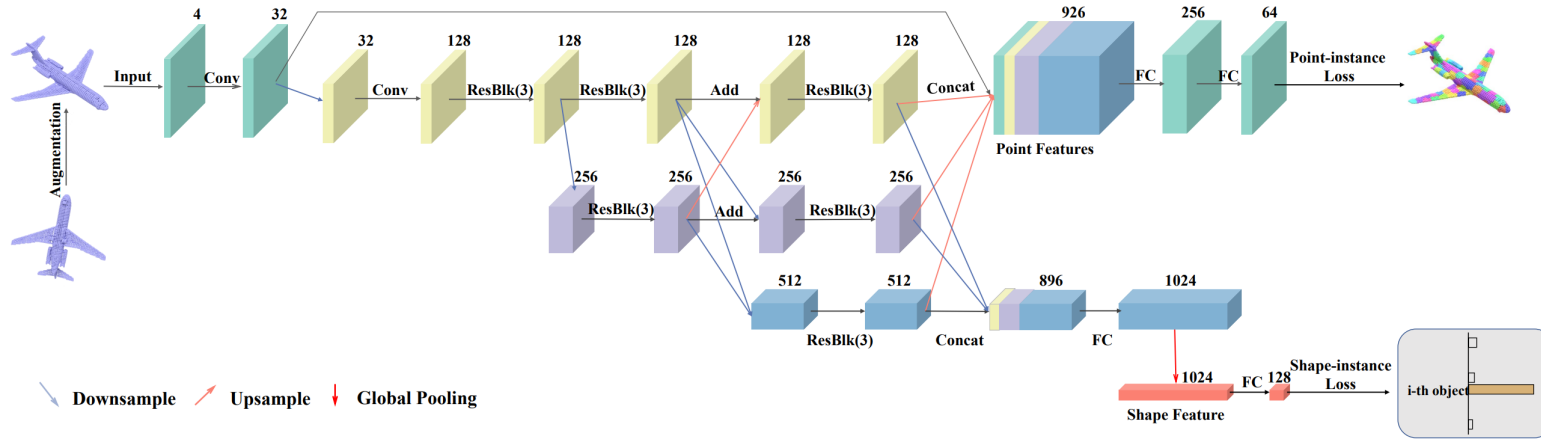
$$L_{CE} = - \sum_{\mathbf{p}_i \in \mathcal{S}_k} \hat{\mathbf{q}}_i \log \mathbf{q}_i$$

\mathcal{S}_k : shape $k = \{\mathbf{p}_i\}_{i=1}^{P_k}$

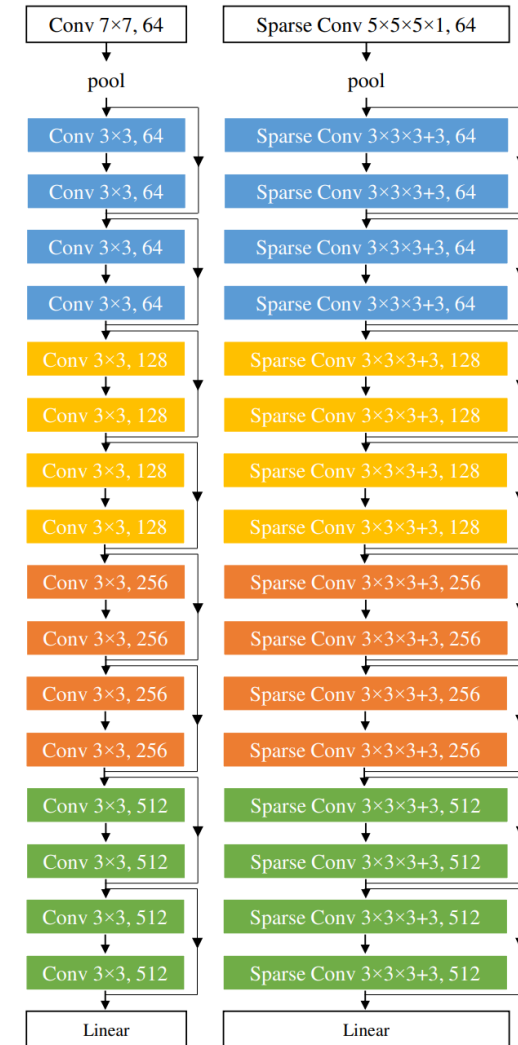
$\hat{\mathbf{q}}_i$: ground-truth one-hot label vector for point \mathbf{p}_i

\mathbf{q}_i : predicted label probabilities for point \mathbf{p}_i

Training details: Backbones

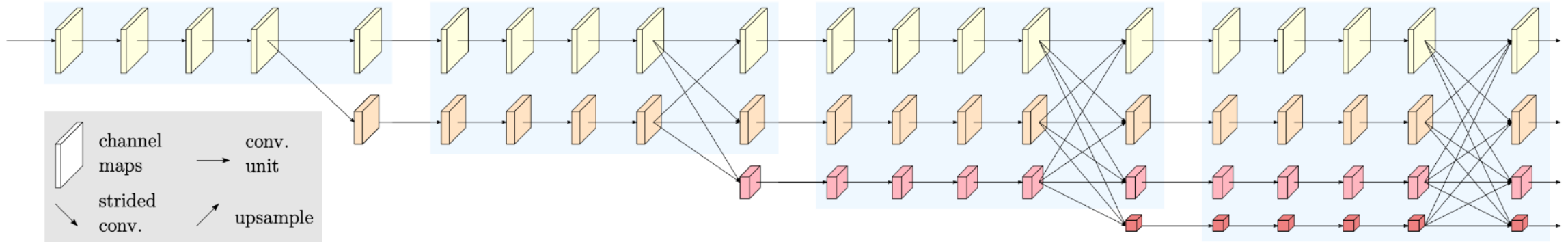


MID-FC [Wang et al. 2021]



MinkowskiNet [Choy et al. 2019]

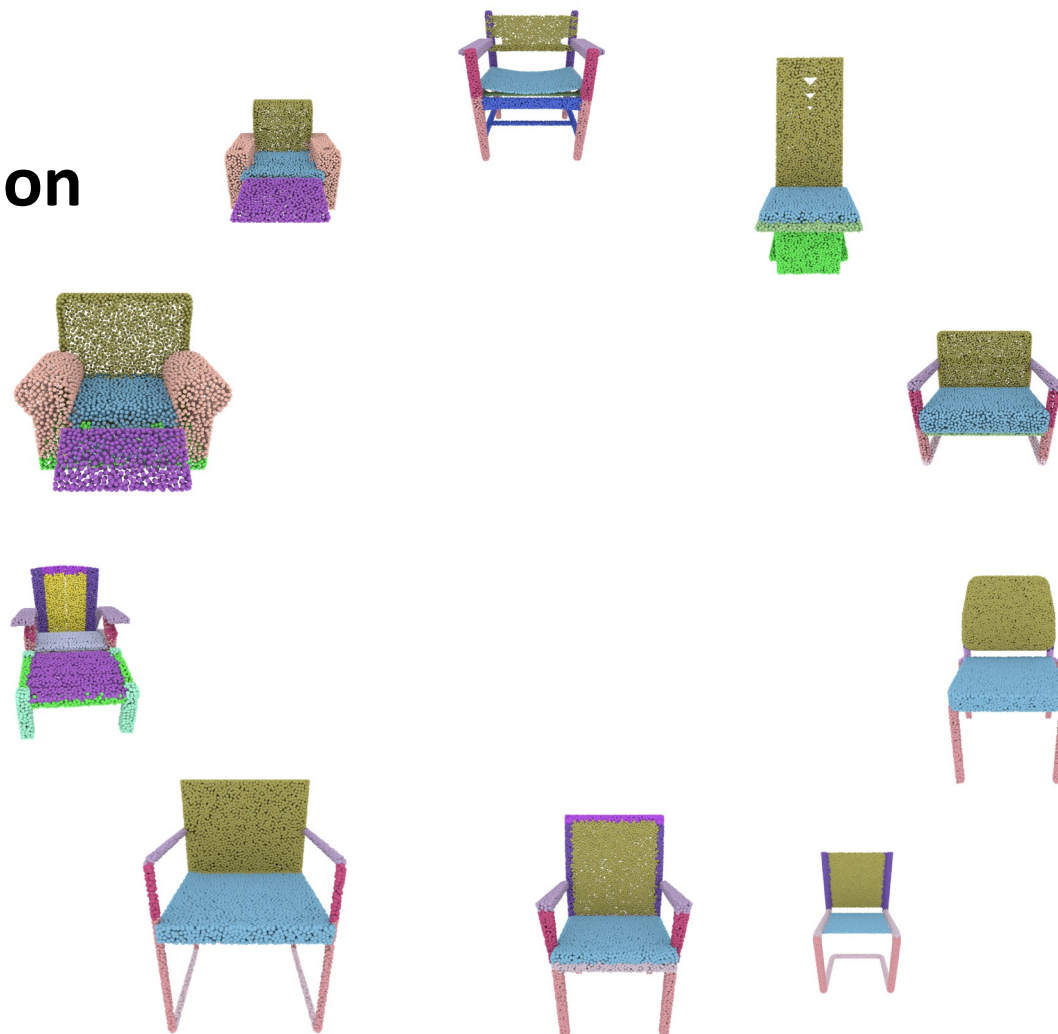
Training details: Backbones



HRNet [Wang et al. 2021]

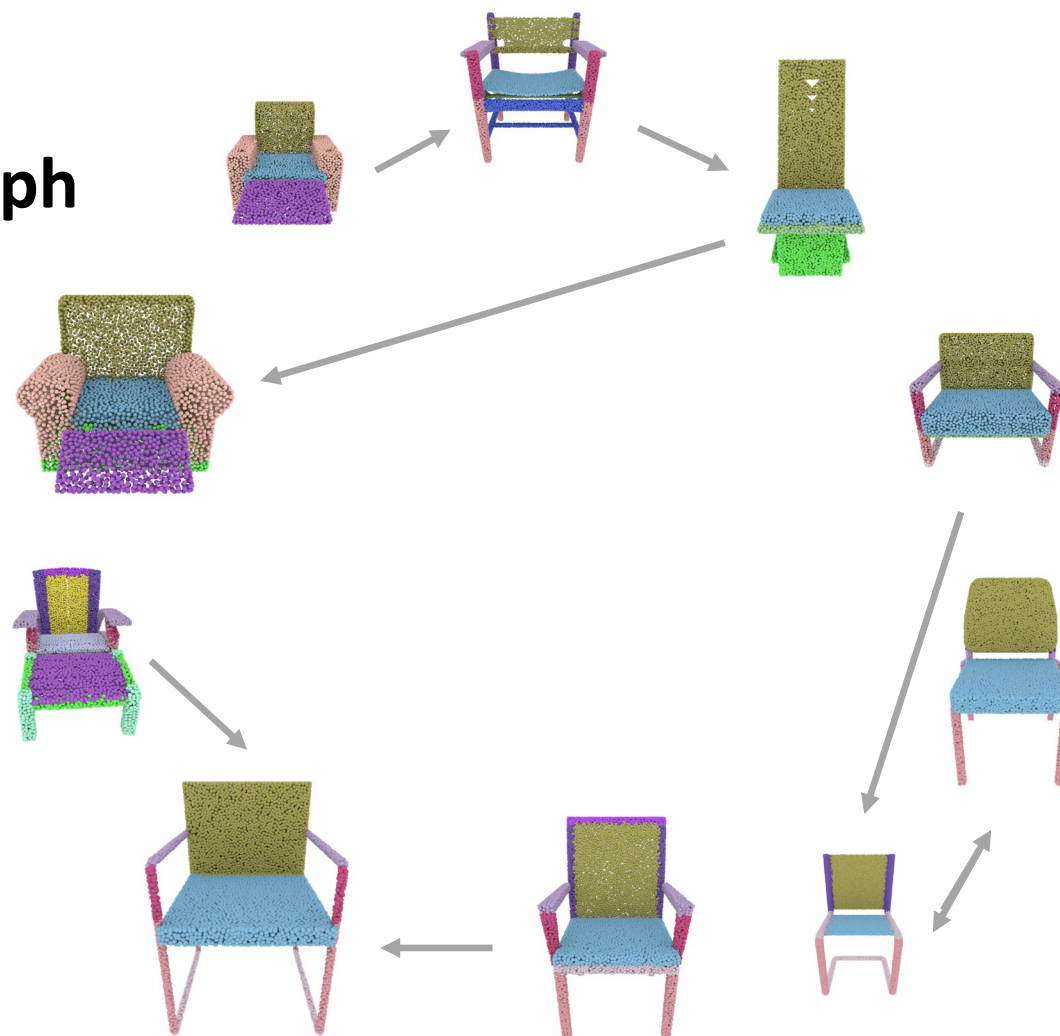
Training details: Collection graph

Shape Collection



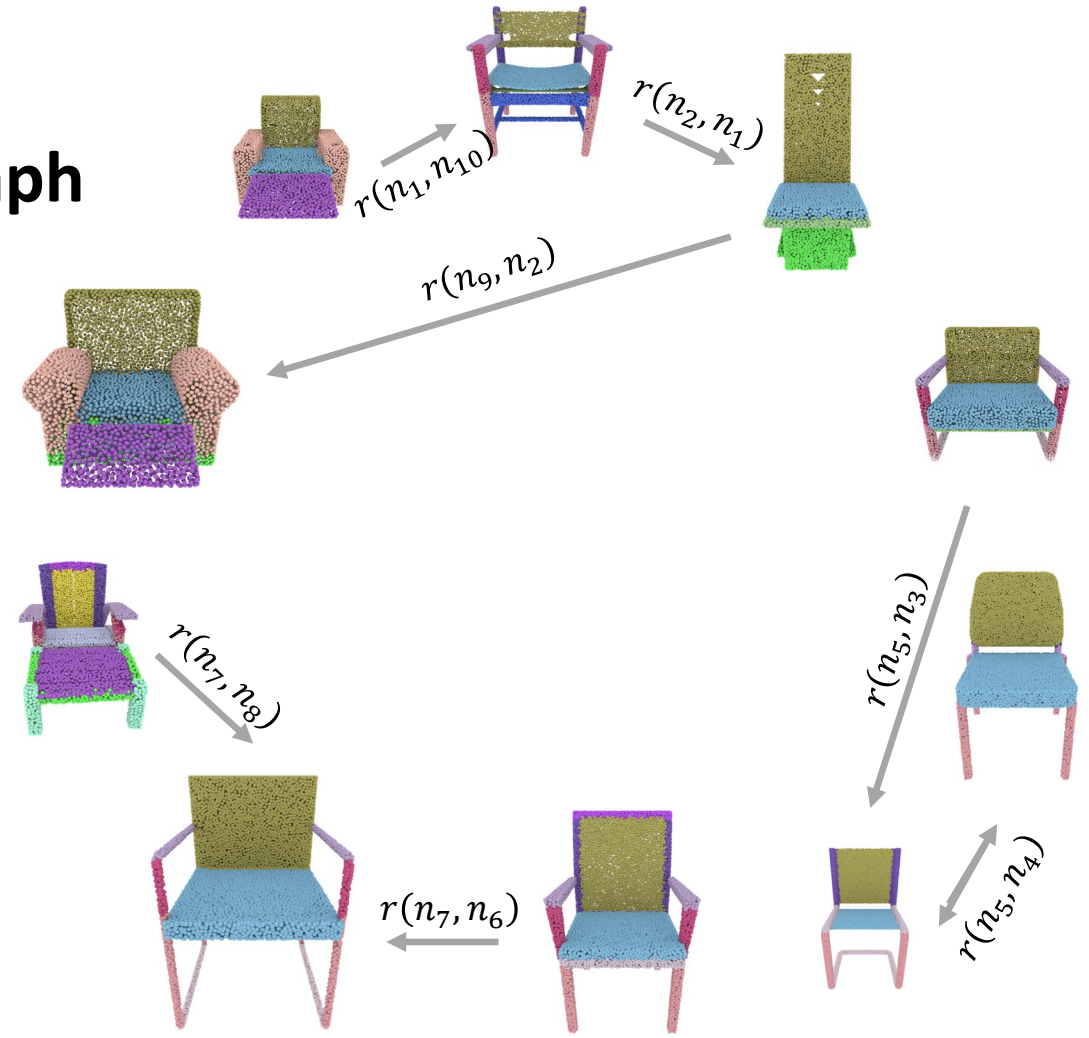
Training details: Collection graph

Collection graph



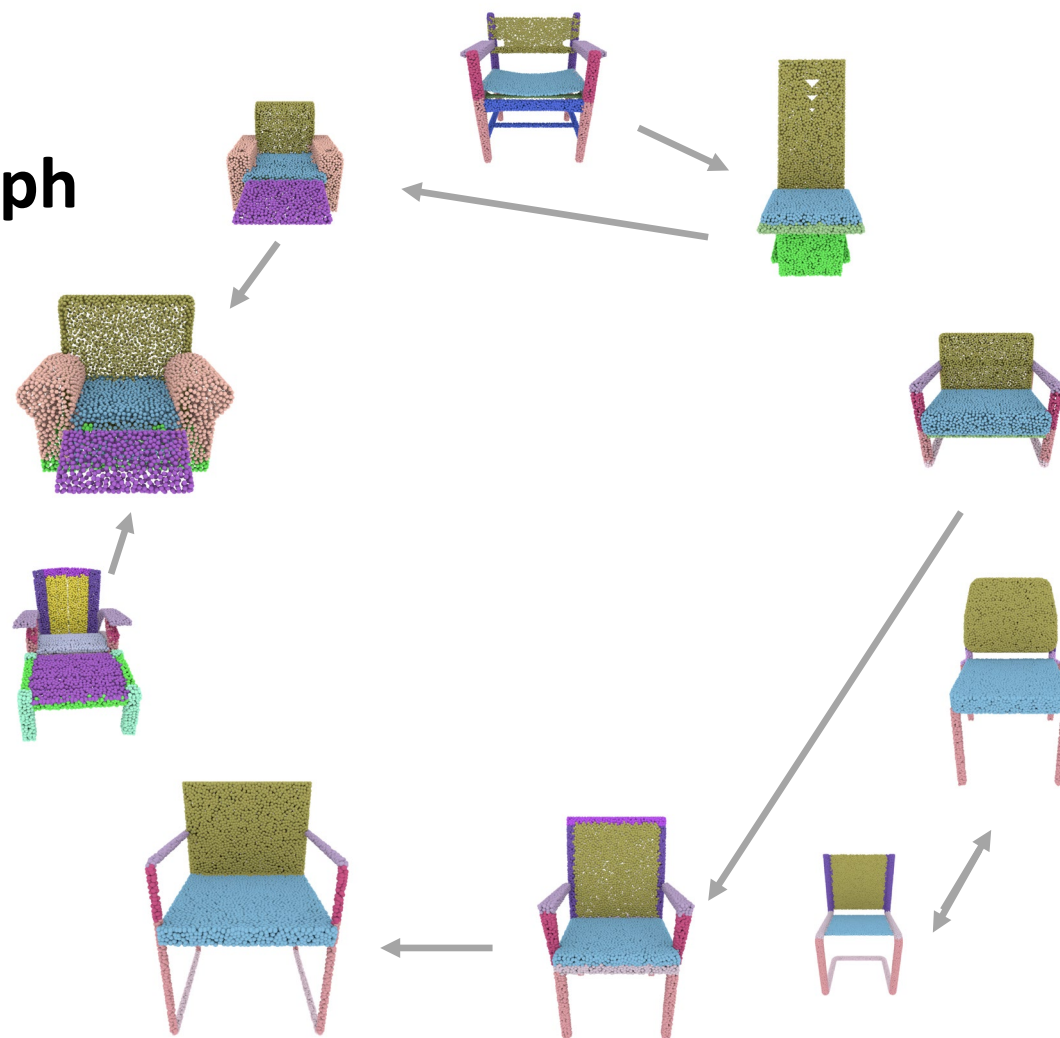
Training details: Collection graph

Collection graph



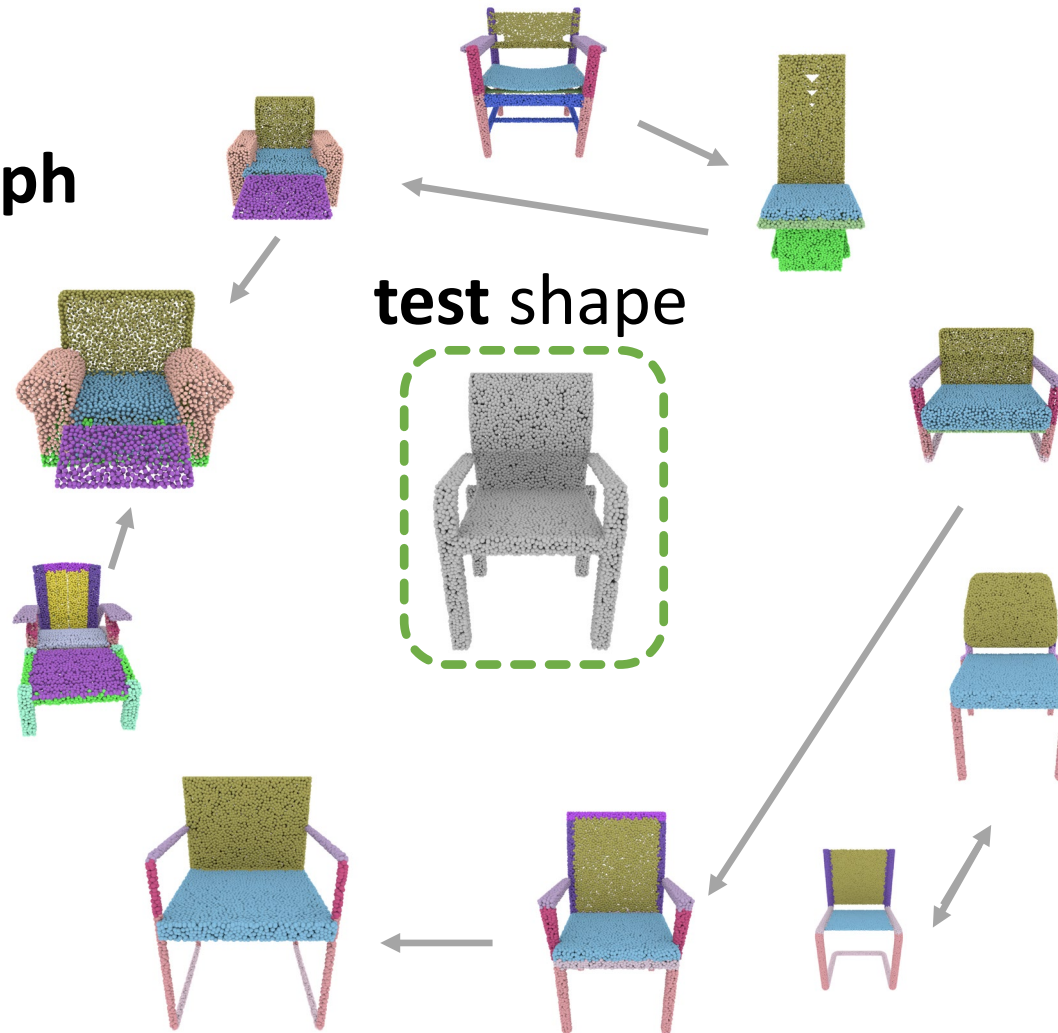
Training details: Collection graph

Collection graph



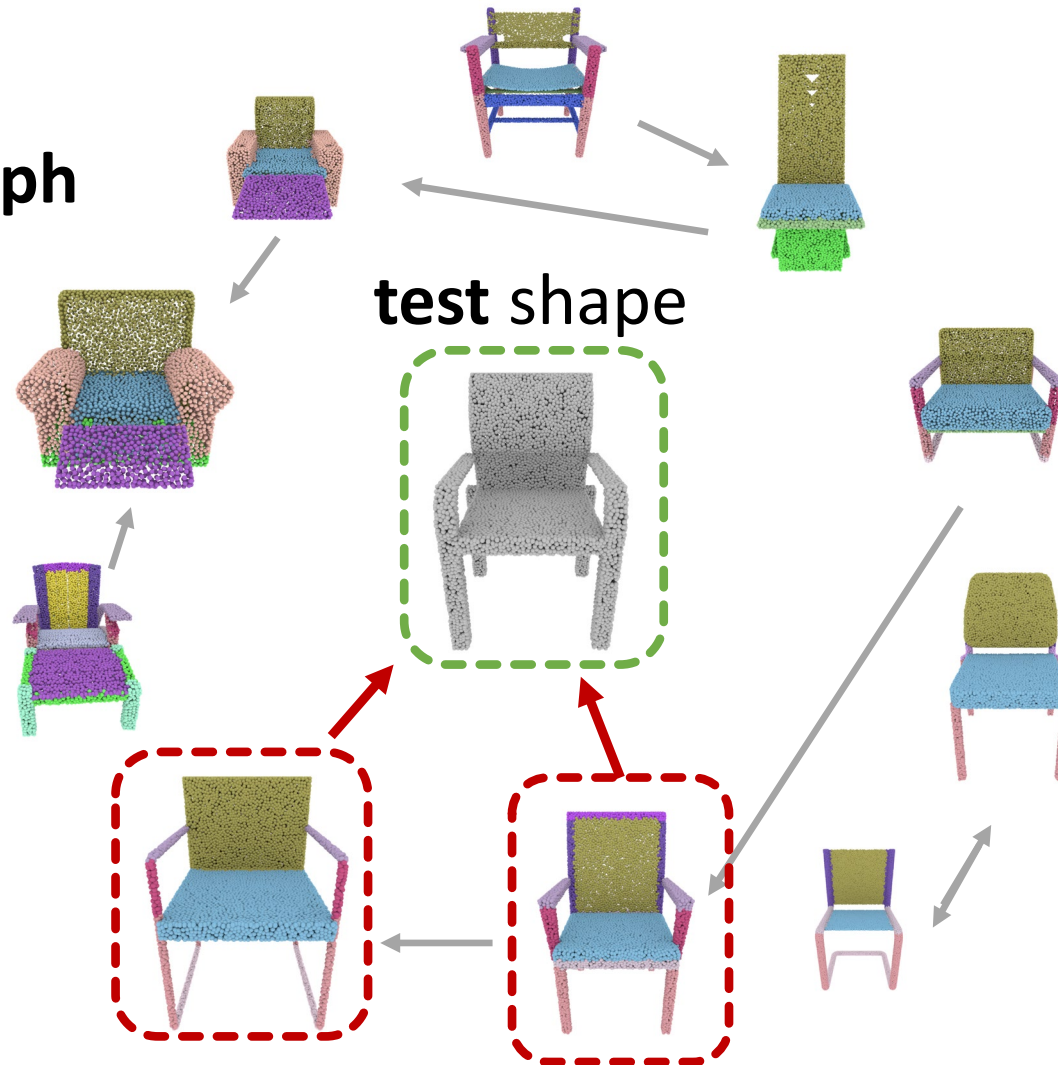
Inference: Collection graph

Collection graph



Inference: Collection graph

Collection graph



Results


Method	Part IoU
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Results: MinkowskiNet variants

Method	Part IoU
MinkHRNet	48.0

Results: MinkowskiNet variants

Method	Part IoU
MinkHRNet	48.0
MinkHRNetCSN-SSA	48.7



+0.7%

Results: MinkowskiNet variants

Method	Part IoU
MinkHRNet	48.0
MinkHRNetCSN-SSA	48.7
MinkHRNetCSN-K1	49.9
MinkHRNetCSN-K2	49.7

Results: MinkowskiNet variants

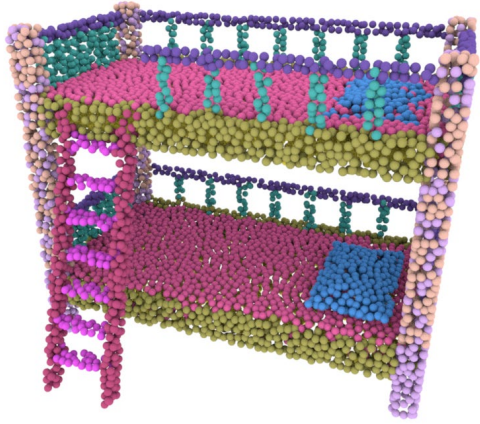
Method	Part IoU
MinkHRNet	48.0
MinkHRNetCSN-SSA	48.7
MinkHRNetCSN-K1	49.9
MinkHRNetCSN-K2	49.7

+1.2%



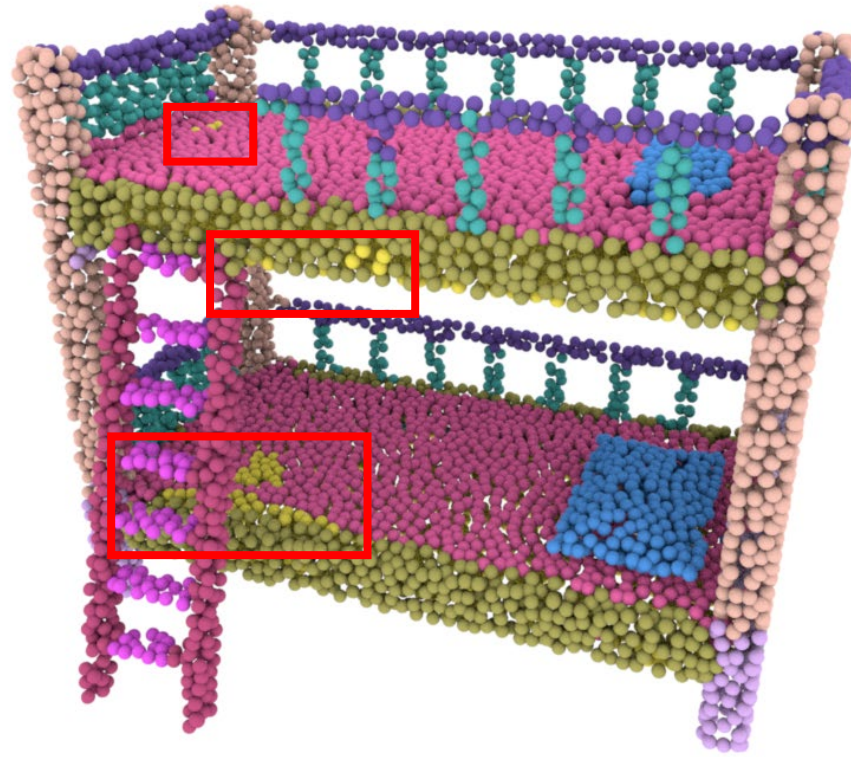
Results: MinkowskiNet variants

Ground truth



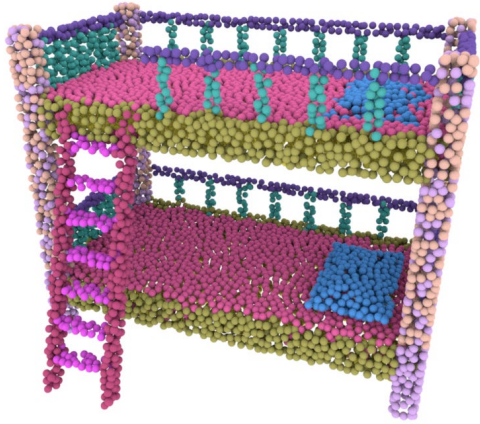
- Pillow
- Mattress
- Stretcher
- Leg
- Horizontal bar
- Vertical bar
- Bed post
- Ladder vertical bar
- Rung

MinkHRNet



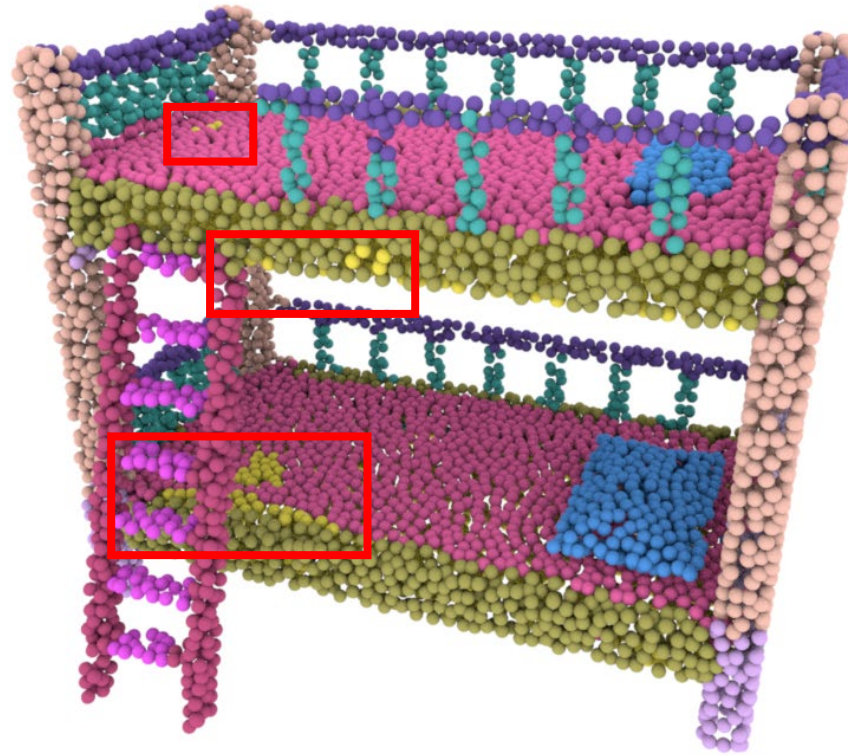
Results: MinkowskiNet variants

Ground truth

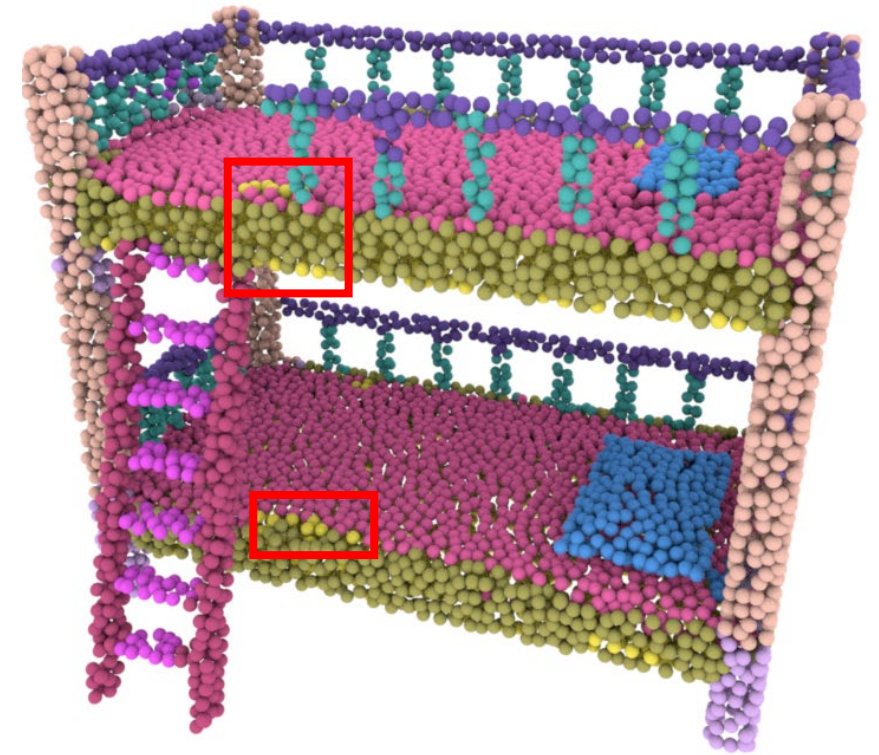


- Blue: Pillow
- Pink: Mattress
- Green: Stretcher
- Purple: Leg
- Dark Purple: Horizontal bar
- Teal: Vertical bar
- Tan: Bed post
- Maroon: Ladder vertical bar
- Magenta: Rung

MinkHRNet

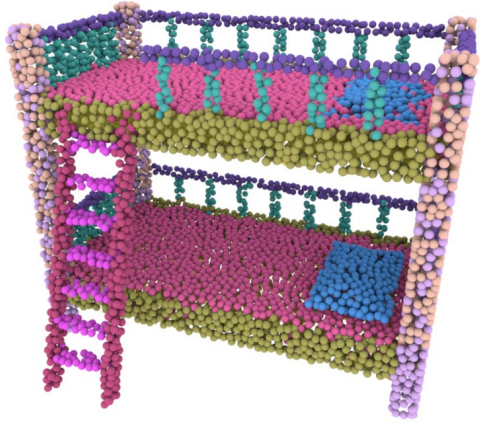


MinkHRNetCSN-SSA



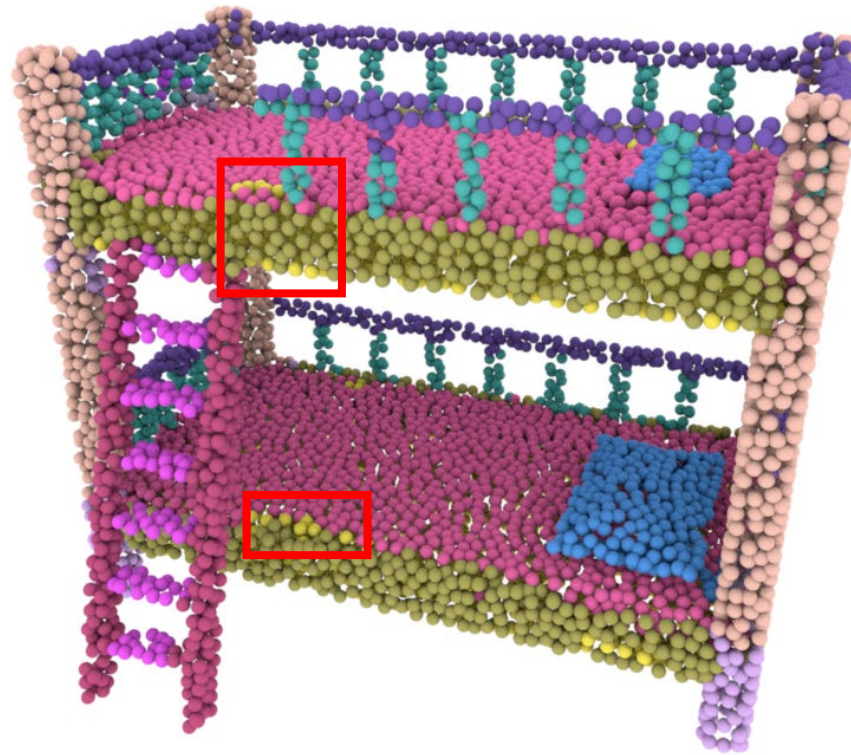
Results: MinkowskiNet variants

Ground truth

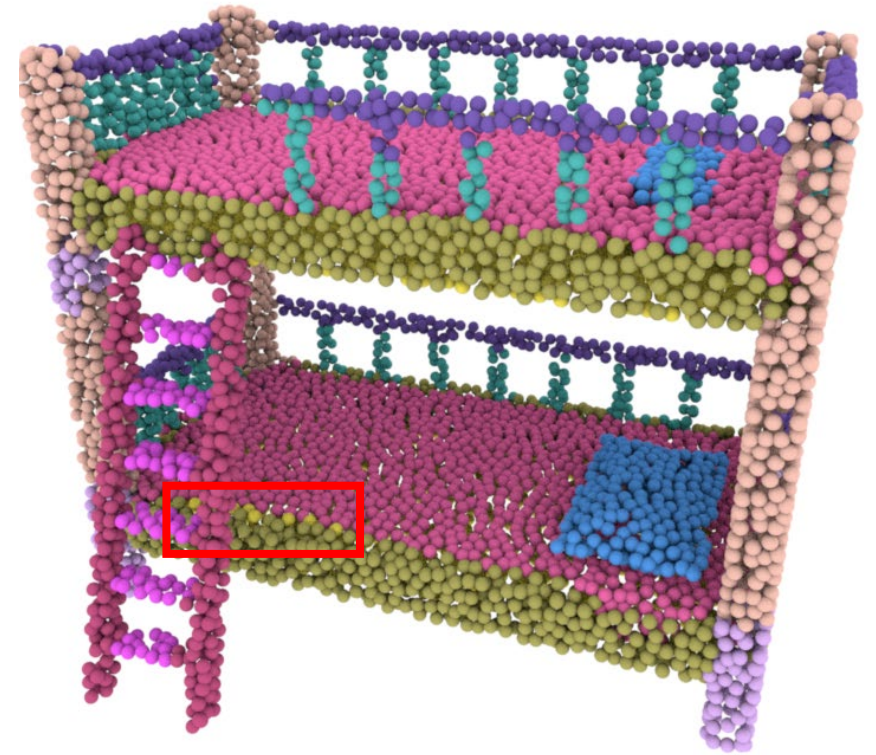


- Pillow
- Mattress
- Stretcher
- Leg
- Horizontal bar
- Vertical bar
- Bed post
- Ladder vertical bar
- Rung

MinkHRNetCSN-SSA



MinkHRNetCSN-K1




Results: MID-FC variants

Method	Part IoU
MID-FC	60.8

Results: MID-FC variants

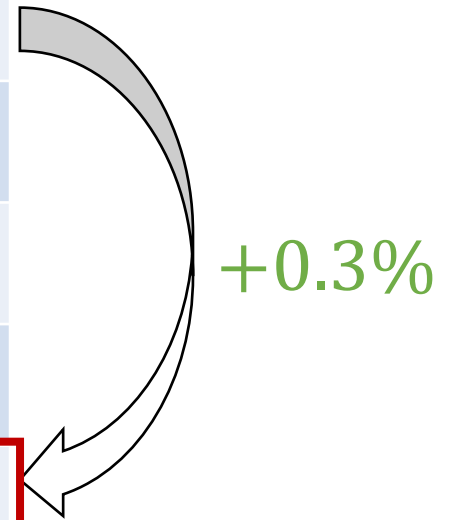
Method	Part IoU
MID-FC	60.8
MID-FC-CSN-SSA	61.8



+1.0%

Results: MID-FC variants

Method	Part IoU
MID-FC	60.8
MID-FC-CSN-SSA	61.8
MID-FC-CSN-K1	61.9
MID-FC-CSN-K2	61.9
MID-FC-CSN-K3	62.0
MID-FC-CSN-K4	62.1
MID-FC-CSN-K5	62.0

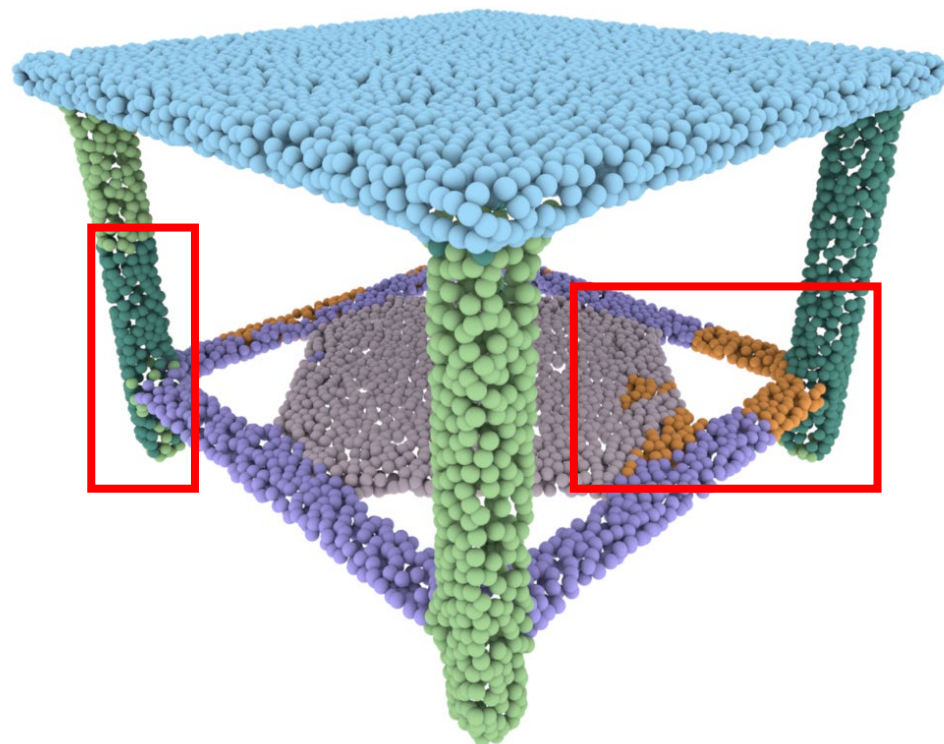
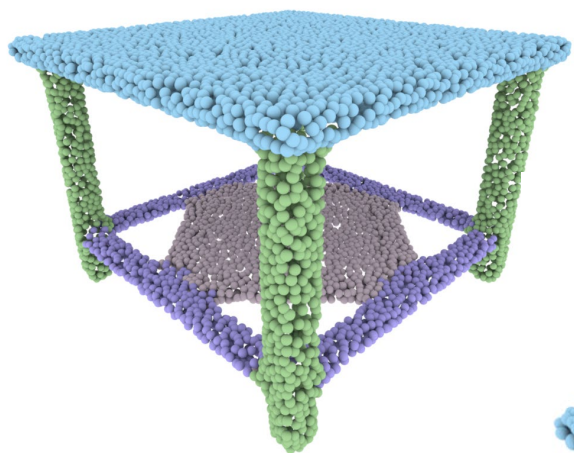


Ground truth

Results: MID-FC variants

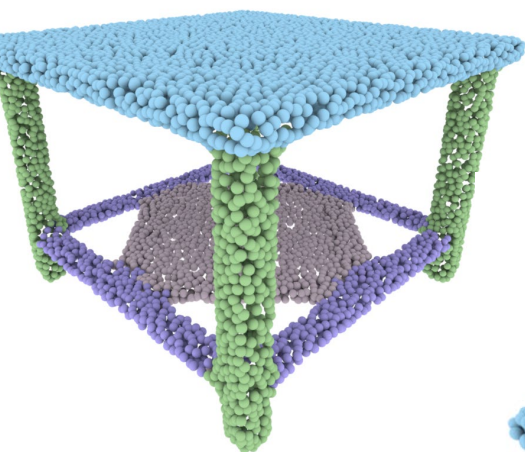
MID-FC

- Bar
- Leg
- Board
- Shelf



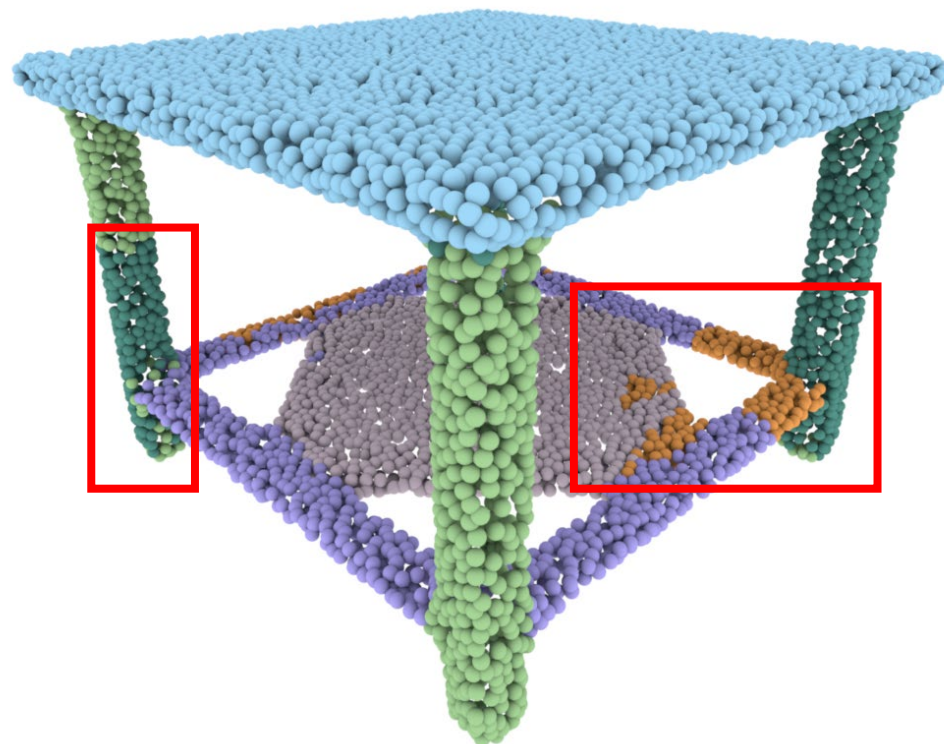
Ground truth

Results: MID-FC variants

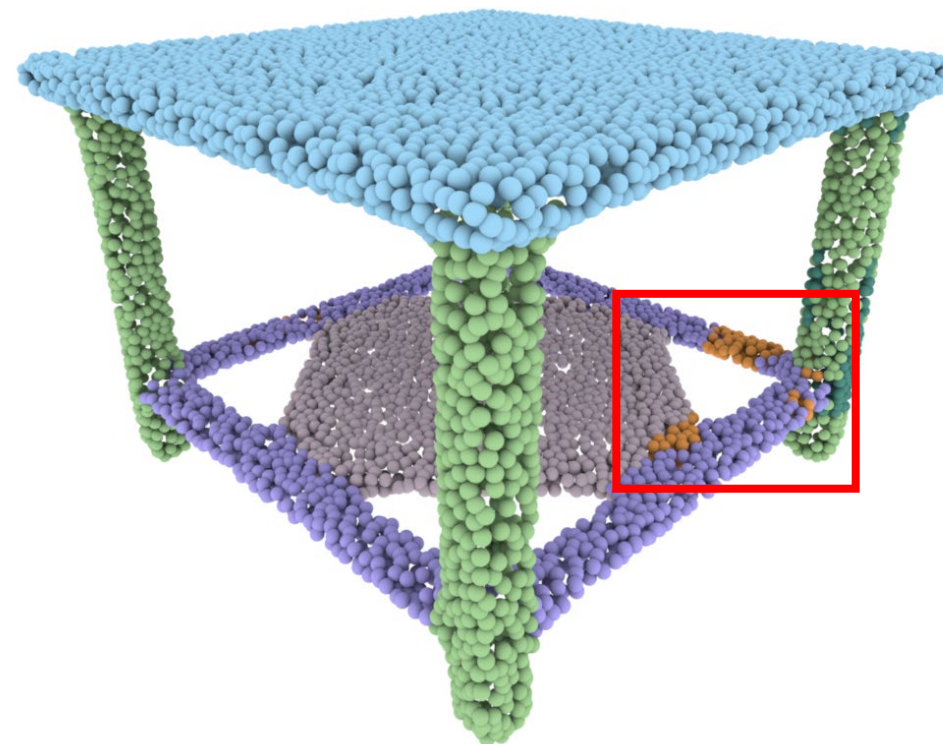


- Bar
- Leg
- Board
- Shelf

MID-FC

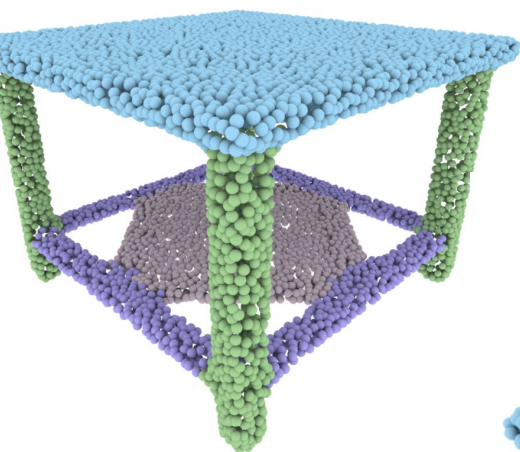


MID-FC-CSN-SSA



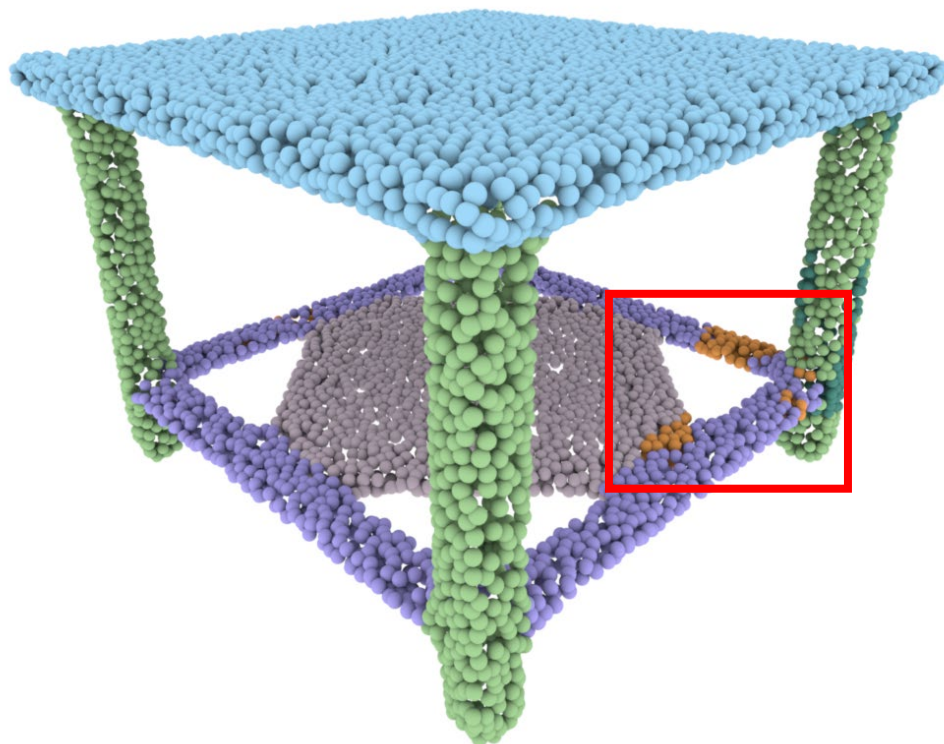
Ground truth

Results: MID-FC variants

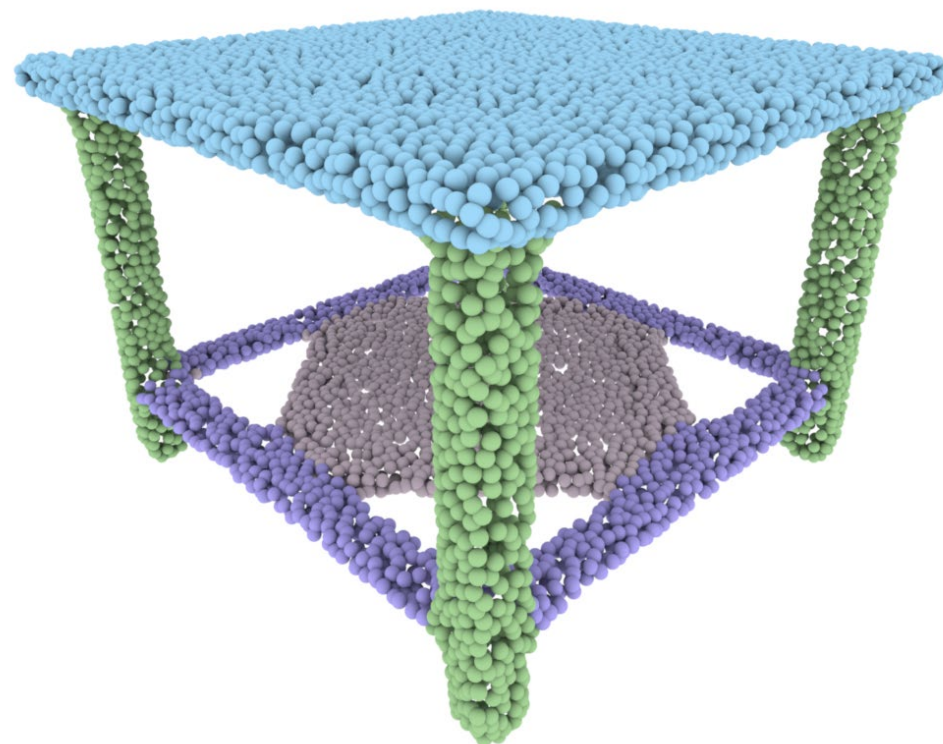


- Bar
- Leg
- Board
- Shelf

MID-FC-CSN-SSA



MID-FC-CSN-K4



Results: Comparison with other methods

Method	Part IoU
ResGCN-28 (Li et al. 2023)	45.1
CloserLook3D (Liu et al. 2020)	53.8
MinkResUNet (Choy et al. 2019)	46.8
MinkHRNetCSN-K1 (ours)	49.9
MID-FC (Wang et al. 2021)	60.8
MID-FC-CSN-K4 (ours)	62.1

Results: Comparison with other methods

Method	Part IoU
ResGCN-28 (Li et al. 2023)	45.1
CloserLook3D (Liu et al. 2020)	53.8
MinkResUNet (Choy et al. 2019)	46.8
MinkHRNetCSN-K1 (ours)	49.9
MID-FC (Wang et al. 2021)	60.8
MID-FC-CSN-K4 (ours)	62.1

+3.1%



Results: Comparison with other methods

Method	Part IoU
ResGCN-28 (Li et al. 2023)	45.1
CloserLook3D (Liu et al. 2020)	53.8
MinkResUNet (Choy et al. 2019)	46.8
MinkHRNetCSN-K1 (ours)	49.9
MID-FC (Wang et al. 2021)	60.8
MID-FC-CSN-K4 (ours)	62.1

+1.3%



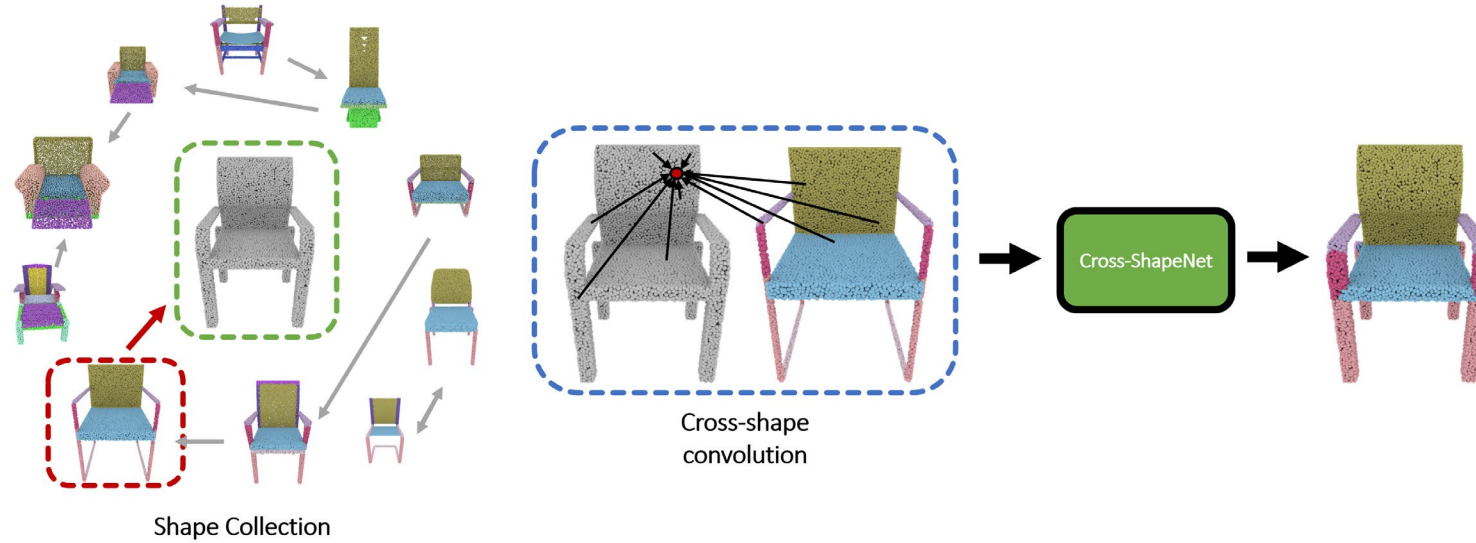
Results: Comparison with other methods

Method	Part IoU
ResGCN-28 (Li et al. 2023)	45.1
CloserLook3D (Liu et al. 2020)	53.8
MinkResUNet (Choy et al. 2019)	46.8
MinkHRNetCSN-K1 (ours)	49.9
MID-FC (Wang et al. 2021)	60.8
MID-FC-CSN-K4 (ours)	62.1

+1.3%

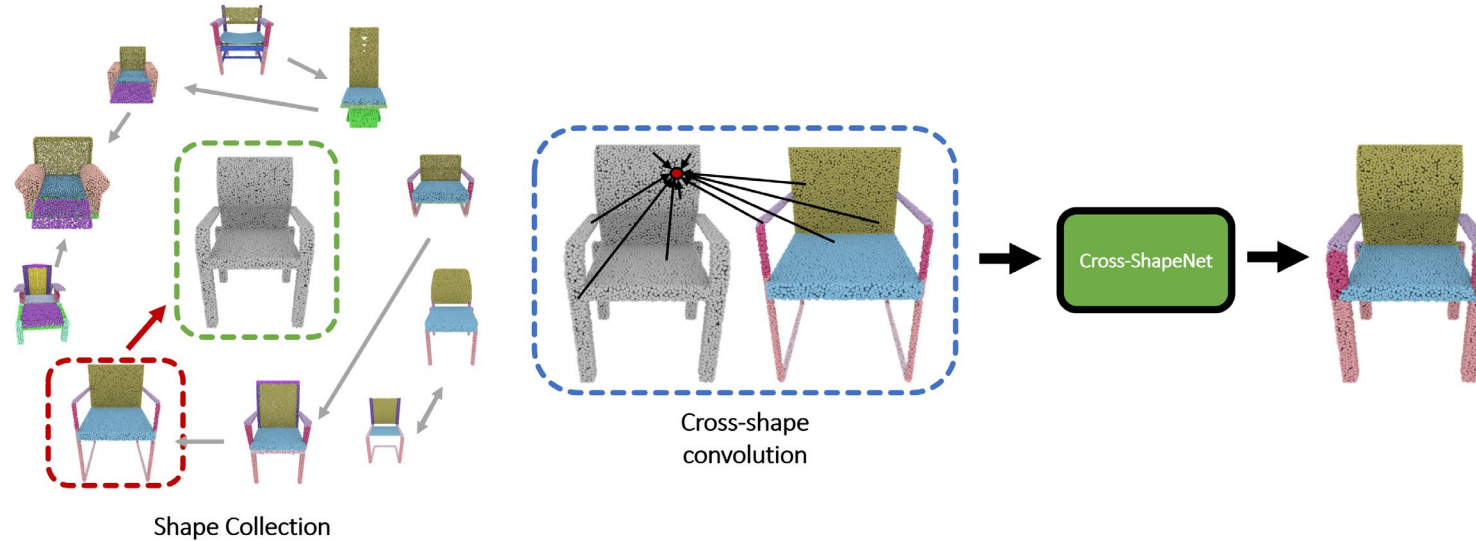
SOTA performance on the PartNet dataset

Summary



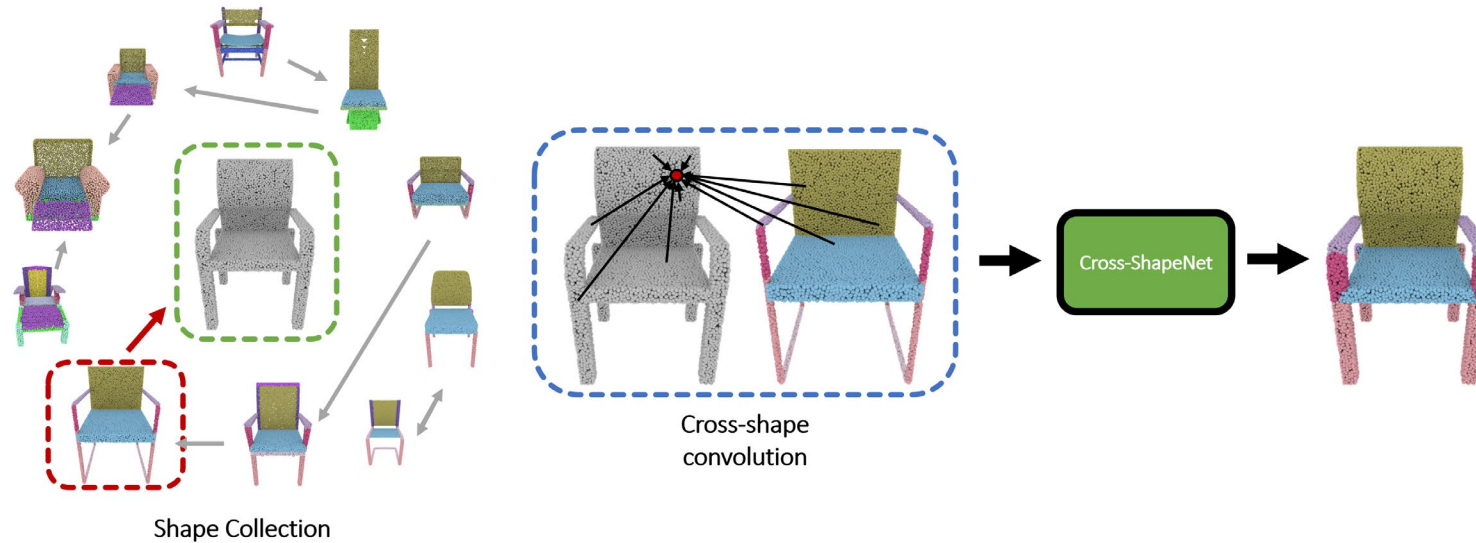
- Enable long range point feature interactions **across shapes**

Summary



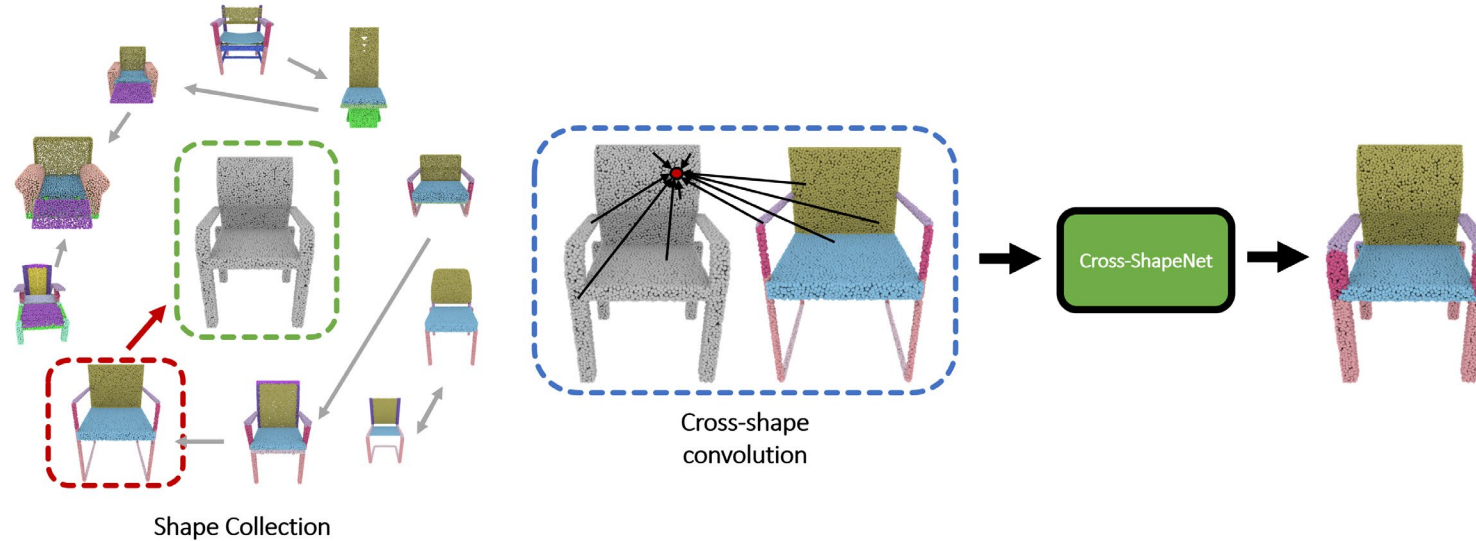
- Enable long range point feature interactions **across shapes**
- Introduce a **novel cross-shape attention** mechanism

Summary



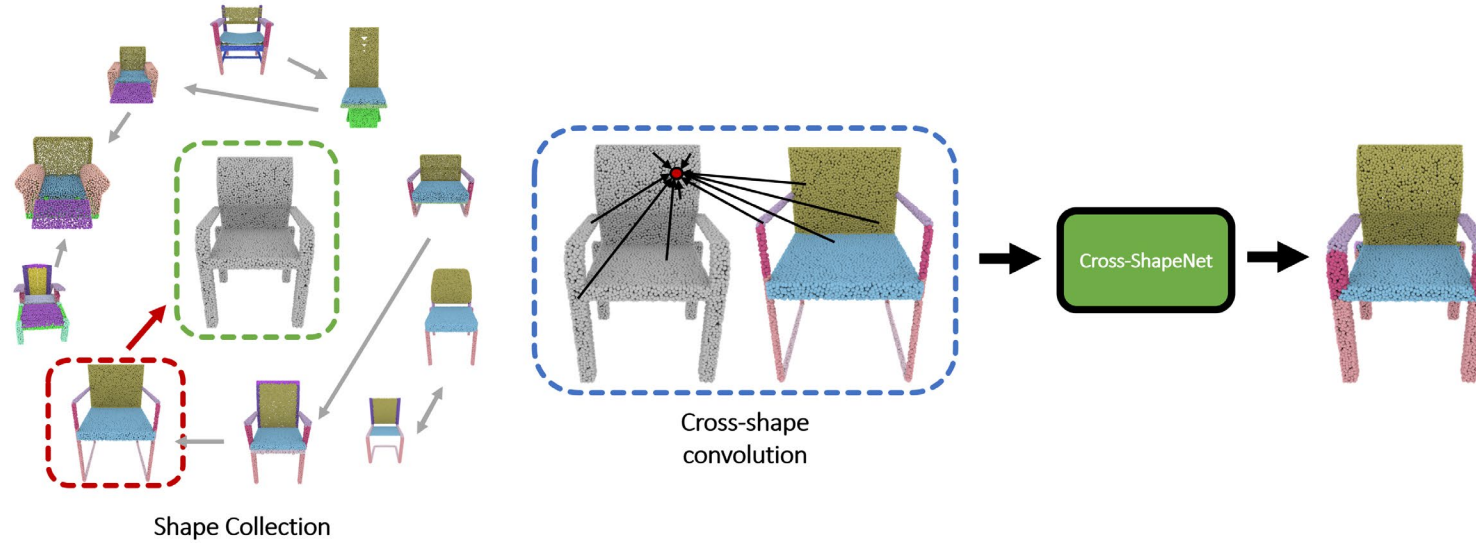
- Enable long range point feature interactions **across shapes**
- Introduce a **novel cross-shape attention** mechanism
- Retrieve **compatible shapes** for cross-shape attention

Summary



- Enable long range point feature interactions **across shapes**
- Introduce a **novel cross-shape attention** mechanism
- Retrieve **compatible shapes** for cross-shape attention
- **SOTA performance** on PartNet

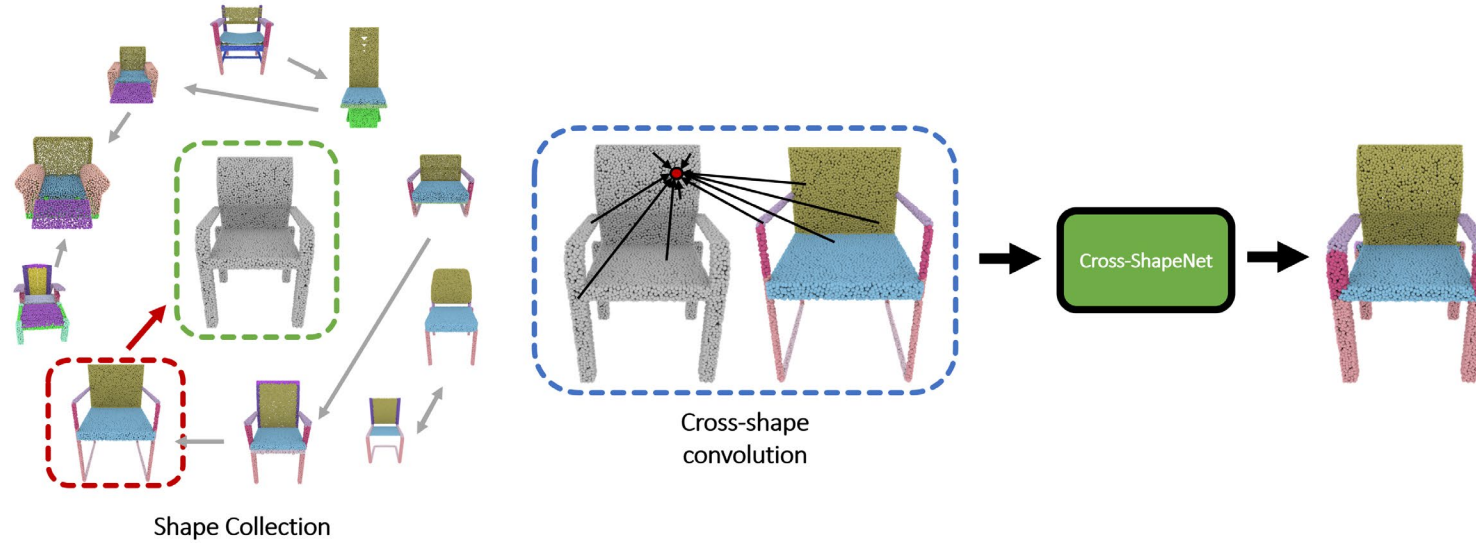
Summary



Limitations:

- **Increased computational cost due to shape retrieval**

Summary



Limitations:

- **Increased computational cost** due to shape retrieval
- Currently no support for **multi-object scenes**

Thank you!

Acknowledgements:



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DEPUTY MINISTRY OF
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AND DIGITAL POLICY
REPUBLIC OF CYPRUS



Our project web page:
<https://marios2019.github.io/CSN/>

